

# Абсолютные однооборотные энкодеры стандартные Sendix

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# Absolute encoders – singleturn

**Standard  
optical**

**Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)**

**PROFIsafe**



The optical absolute Sendix S58 PROFIsafe encoders are based on the new Kübler Industrial Ethernet encoder platform and are therefore already designed today for future Industry 4.0 concepts.

One example of this is the integrated web server: Features or adjustments can be implemented quickly and easily at any time.

As certified SIL3 / PLe encoders with redundant design and PROFINET interface, they support the PROFIsafe profile and are predestined for safety applications.



Safety-Lock™



High rotational speed



Temperature range  
-40°C...+80°C



High protection level  
IP67



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Reverse polarity protection



Optical sensor

## Reliable and safe

- **Robust**  
Sturdy bearing construction in Safety-Lock™ Design for resistance against vibration and installation errors.
- **High resolution**  
- Singleturn 15 bit (safe) or 24 bit (non safe).
- **Safe**  
- SIL 3, performance level PLe, safety category Cat. 3.  
- Transmission via safety telegrams 36/37, according to BP and XP.
- **100 % future-proof**  
- Implement features and adaptations quickly and easily.  
- Cyber Security update in preparation / High system availability, protection against misuse (acc. IEC 62443).

## Latest PROFINET functionality

- PROFINET IO, RT, IRT allows integration in applications with different performance requirements.
- Supports the Isochronous Mode, can thus be implemented in networks for hard real-time requirements with clock cycles up to 500 µs.
- PROFINET v2.4.1, encoder profile V 4.2, PROFIsafe profile v2.6.1, PROFIdrive profile v4.2
- Ideal for highly synchronous applications, such as e. g. axis synchronization.
- Interoperability between many different control and drive manufacturers thanks to the PROFIdrive profile.
- Integrated web server for firmware update.

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Standard optical	Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)	PROFIsafe
<b>Order code</b> <b>Shaft version</b>	<div> <div>8.S5858FS3</div> <div>Type</div> <div>.</div> <div>X</div> <div>X</div> <div>C</div> <div>N</div> <div>.</div> <div>C1</div> <div>1</div> <div>1</div> </div> <div> <div>a</div> <div>b</div> <div>c</div> <div>d</div> <div>e</div> </div>	
<p><b>a</b> Flange</p> <p>1 = clamping flange, IP65 ø 58 mm [2.28"]</p> <p>3 = clamping flange, IP67 ø 58 mm [2.28"]</p> <p>2 = synchro flange, IP65 ø 58 mm [2.28"]</p> <p>4 = synchro flange, IP67 ø 58 mm [2.28"]</p> <p>5 = square flange, IP65 □ 63.5 mm [2.5"]</p> <p>7 = square flange, IP67 □ 63.5 mm [2.5"]</p> <p><b>b</b> Shaft (ø x L), with flat</p> <p>2 = 10 x 20 mm [0.39 x 0.79"]</p> <p>5 = 12 x 20 mm [0.47 x 0.79"]</p> <p>4 = 3/8" x 7/8"</p> <p>Shaft (ø x L), with feather key DIN 6885 A-3x3x10</p> <p>A = 10 x 20 mm [0.39 x 0.79"]</p> <p>B = 12 x 20 mm [0.47 x 0.79"]</p> <p>C = 3/8" x 7/8"</p>	<p><b>c</b> Interface / Supply voltage</p> <p>C = PROFINET IO / 10 ... 30 V DC</p> <p><b>d</b> Type of connection</p> <p>N = 3 x axial M12 connector, 4-pin</p> <p><b>e</b> Fieldbus profile</p> <p>C1 = PROFINET IO</p> <p><i>Optional on request</i></p> <ul style="list-style-type: none"> <li>- Ex 2/22 (only for variants with IP67)</li> <li>- surface protection salt spray tested</li> </ul>	
<b>Order code</b> <b>Hollow shaft</b>	<div> <div>8.S5878FS3</div> <div>Type</div> <div>.</div> <div>X</div> <div>X</div> <div>C</div> <div>N</div> <div>.</div> <div>C1</div> <div>1</div> <div>1</div> </div> <div> <div>a</div> <div>b</div> <div>c</div> <div>d</div> <div>e</div> </div>	
<p><b>a</b> Flange</p> <p>1 = with torque stop FS, flexible, IP65</p> <p>2 = with torque stop FS, flexible, IP67</p> <p>5 = with stator coupling FS, ø 63 mm [2.48"], IP65</p> <p>6 = with stator coupling FS, ø 63 mm [2.48"], IP67</p> <p>7 = with torque stop FS, rigid, IP65 (incl. torque pin FS)</p> <p>8 = with torque stop FS, rigid, IP67 (incl. torque pin FS)</p> <p><b>b</b> Blind hollow shaft</p> <p>(insertion depth max. 30 mm [1.18"])</p> <p>A = ø 10 mm [0.39"]</p> <p>B = ø 12 mm [0.47"]</p> <p>C = ø 14 mm [0.55"]</p> <p>D = ø 15 mm [0.59"]</p> <p>E = ø 3/8"</p> <p>F = ø 1/2"</p>	<p><b>c</b> Interface / Supply voltage</p> <p>C = PROFINET IO / 10 ... 30 V DC</p> <p><b>d</b> Type of connection</p> <p>N = 3 x axial M12 connector, 4-pin</p> <p><b>e</b> Fieldbus profile</p> <p>C1 = PROFINET IO</p> <p><i>Optional on request</i></p> <ul style="list-style-type: none"> <li>- Ex 2/22 (only for variants with IP67)</li> <li>- surface protection salt spray tested</li> </ul>	

## Absolute encoders – singleturn

Standard optical		Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)	PROFIsafe
Mounting accessory for shaft encoders			Order no.
Bellows coupling FS	bellows coupling FS ø 25 mm [0.98"] for shaft 10 mm [0.39"]		8.0000.15FS.1010
	bellows coupling FS ø 25 mm [0.98"] for shaft 12 mm [0.47"]		8.0000.15FS.1212
Accessories			Order no.
Screw retention	Loctite 243, 5 ml		8.0000.4G05.0000
Cables and connectors			Order no.
Preassembled cables	M12 male connector with external thread, 4-pin, D coded, straight single-ended 2 m [6.56'] PUR cable	port 1 + port 2	05.00.6031.4411.002M
	M12 male connector with external thread, 4-pin, D coded, right-angle single-ended 2 m [6.56'] PUR cable	port 1 + port 2	05.00.6031.4511.002M
	M12 female connector with coupling nut, 4-pin, A coded, straight single-ended 2 m [6.56'] PUR cable	power supply	05.00.6061.6211.002M
	M12 female connector with coupling nut, 4-pin, A coded, right-angle single-ended 2 m [6.56'] PUR cable	power supply	05.00.6061.6311.002M
Connectors	M12 male connector with external thread, 4-pin, D coded, straight (metal)	port 1 + port 2	05.WASCSY4S
	M12 male connector with external thread, 4-pin, D coded, right-angle (metal)	port 1 + port 2	8.0000.5128.0000
	M12 female connector with coupling nut, 4-pin, A coded, straight (plastic)	power supply	05.B8141-0
	M12 female connector with coupling nut, 4-pin, A coded, right-angle (plastic)	power supply	05.B8241-0

Further Kübler accessories can be found at: [/accessories](#)

Further Kübler cables and connectors can be found at: [/connection-technology](#)

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<b>Standard optical</b>	<b>Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)</b>	<b>PROFIsafe</b>
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## Technical data

Notes regarding “Functional Safety”
These encoders are suitable for use in safety-related systems up to SIL3 acc. to EN 61800-5-2 and PLe to EN ISO 13849-1 in conjunction with controllers or evaluation units, which possess the necessary functionality. Additional functions can be found in the operating manual.

Safety characteristics	
Classification	PLe / SIL3
System structure	2 channel (Kat. 3)
PFH <sub>d</sub> value <sup>1)</sup>	9,54 x 10 <sup>-10</sup> h <sup>-1</sup>
Mission time / Proof test interval	20 years
Relevant standards	EN ISO 13849-1:2015; EN ISO 13849-2:2012; EN 61800-5-2:2007

Mechanical characteristics		
Max. speed		9000 min <sup>-1</sup> (short-term – 10 min) 6000 min <sup>-1</sup> (continuous)
Starting torque at 20 °C [68 °F]		< 0.01 Nm
Moment of inertia		
	shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
	blind hollow shaft version	4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
Load capacity of shaft		
	radial	80 N
	axial	40 N
Weight		approx. 0.45 kg [15.87 oz]
Protection acc. to EN 60529		IP65, IP67
Ambient temperature		-40 °C ... +80 °C [-40 °F ... +176 °F]
Material		
	shaft/hollow shaft	stainless steel
	flange	aluminum
	housing	aluminum
Shock resistance acc. EN 60068-2-27		1000 m/s <sup>2</sup> , 6 ms
Vibration resistance acc. EN 60068-2-6		100 m/s <sup>2</sup> , 55 ... 2000 Hz

Electrical characteristics	
Supply voltage	10 ... 30 V DC
Power consumption (no load)	max. 250 mA
Reverse polarity protection of the supply voltage (+V)	yes
Smallest safe measuring step	158,4 arcsec (0,044° / 4 increments)
Lowest safe speed	4 rpm ( $\sigma_v < 0,5 \%$ )

Approvals		
UL compliant in accordance with		File no. E224618
CE compliant in accordance with		
EMC Directive	2014/30/EU	
RoHS Directive	2011/65/EU	
ATEX Directive	2014/34/EU (for Ex 2/22 variants)	
Machinery Directive	2006/42/EG	

1) The specified value is based on a diagnostic coverage of 99 %, that must be achieved with an encoder evaluation unit.  
The encoder evaluation unit must meet at least the requirements for SIL3.




# Absolute encoders – singleturn

<b>Standard optical</b>	<b>Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)</b>	<b>PROFIsafe</b>
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## Interface characteristics PROFIsafe

General information		Adjustable parameters	
<b>Protocol</b>	PROFINET IO / PROFIsafe	<ul style="list-style-type: none"> <li>• Preset</li> <li>• Counting direction</li> <li>• Resolution per revolution - MUR</li> <li>• Unit speed</li> <li>• IP address</li> <li>• Total resolution - TMR</li> <li>• Position format</li> <li>• Speed reference value</li> </ul>	<ul style="list-style-type: none"> <li>• Scaling</li> <li>• Device name</li> <li>• F-Destination Address</li> <li>• I&amp;M 0...3 Parameter</li> <li>• Alarm behavior</li> <li>• Parameter write protection</li> <li>• Parameter initialization</li> </ul>
<b>Classifications</b>	RT Class 3 (IRT) Conformance Class C Application Class 6 Encoder Class 4 / S2 Netload Class III		
Resolution		PROFIsafe characteristics	
<b>Resolution Singleturn (MUR)</b>	scalable safe 1 ... 32 768 (15 bit) scalable non-safe 1 ... 16 777 216 (24 bit) default 8 192 (13 bit)	<ul style="list-style-type: none"> <li>• I&amp;M 0 ... 4</li> <li>• standard telegrams (81, 82, 83, 84, 86, 88)</li> <li>• standard safety telegrams (36, 37) BP and XP</li> <li>• IRT up to 500 µs</li> <li>• RT Safe up to 4 ms</li> </ul>	<ul style="list-style-type: none"> <li>• Isochronous Mode</li> <li>• MRP</li> <li>• LLDP</li> <li>• PDEV</li> <li>• SNMP</li> <li>• FSU</li> </ul>
		Process data	
		<ul style="list-style-type: none"> <li>• Position (Safe / Non-Safe)</li> <li>• Speed (Safe / Non-Safe)</li> </ul>	<ul style="list-style-type: none"> <li>• Failure</li> <li>• Warnings</li> </ul>

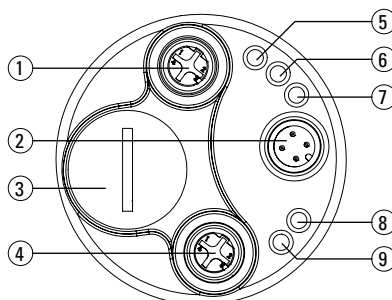
## Terminal assignment bus

Interface	Type of connection	Function	M12 connector, 4-pin						
C	N (3 x M12 connector)	Bus Port 1	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -		D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-		
			Pin:	1	2	3	4		
		Power supply	Signal:	Voltage +	—	Voltage —	—		
			Abbreviation:	+ V	—	0 V	—		
			Pin:	1	2	3	4		
		Bus Port 2	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -		D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-		
			Pin:	1	2	3	4		

## Rear side connections and display elements

①	Ethernet Port – Link 2	
②	Supply voltage	
③	Cover screw	
④	Ethernet Port – Link 1	
⑤	Link 2	flashes yellow when connected
⑥	BF – Bus Failure	displays network errors *)
⑦	SF – System Failure	displays system errors *)
⑧	ENC	shows status of encoder *)
⑨	Link 1	flashes yellow when connected

\*) see manual



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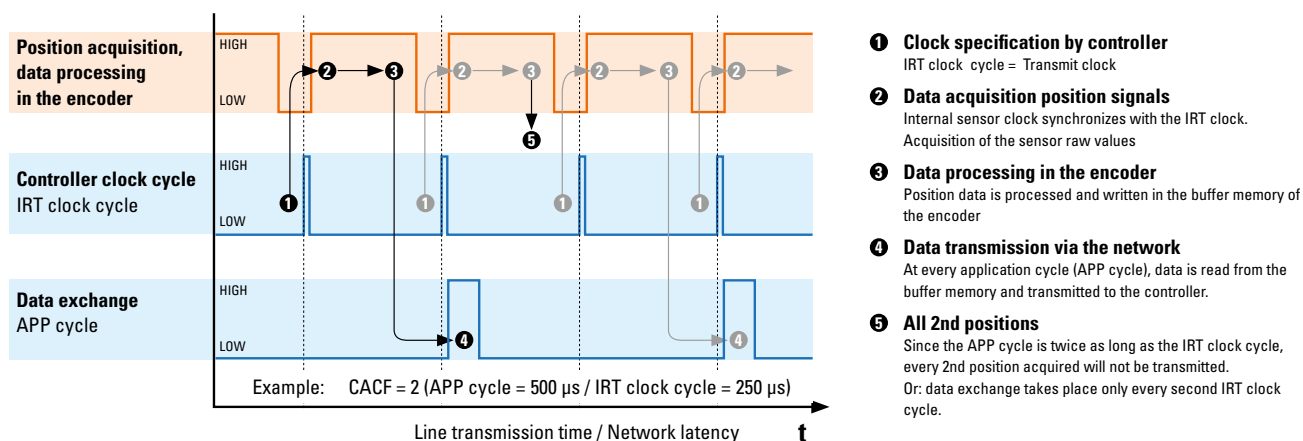
**PROFIsafe**

## Technology in detail

### Clock synchronicity – Isochronous Real Time (IRT) in position sensor technology

In general, for time-critical applications, focus is set on very short sensor cycle times. However, in order to achieve high control performance, simply accelerating data acquisition and processing by shortest cycle times is not sufficient. All sensors and actuators are to operate according to the same clock.

This is achieved thanks to a clock used for the whole network, defined by the controller. This transmit clock cycle (IRT clock) is however not necessarily the clock cycle used for process data exchange. Another cycle (application cycle) is used for this purpose, which can also be defined by the customer controller. The illustration below represents the connection between the different clock cycles.



When receiving the IRT clock signal, the sensor starts reading its current measured point. This raw value is processed internally (e.g. scaling, speed calculation, etc.) and stored in a buffer memory.

The buffer memory is read at every application cycle. If it contains a value, this value is transmitted to the controller via the network.

If the application cycle is a multiple of the IRT clock cycle, it may happen that the buffered process data is not sent directly, but is overwritten, because, even though this data is acquired with every IRT clock cycle, it is sent only with every application cycle.

The ratio between application cycle and IRT clock cycle represents the CACF (Controller Application Cycle Factor).

In this example, the CACF = 2. This indicates that only every 2nd acquired position will be transmitted to the controller.

The described methodology guarantees a determinism: since the controller defines a clock cycle for the whole network, this allows ensuring that all measured values transmitted by the sensors to the controller are never older than the selected IRT cycle! Therefore, all downstream actuators can always be regulated on the basis of the latest available measured values.

### PROFIsafe encoders – Data flow of safe and non-safe position values

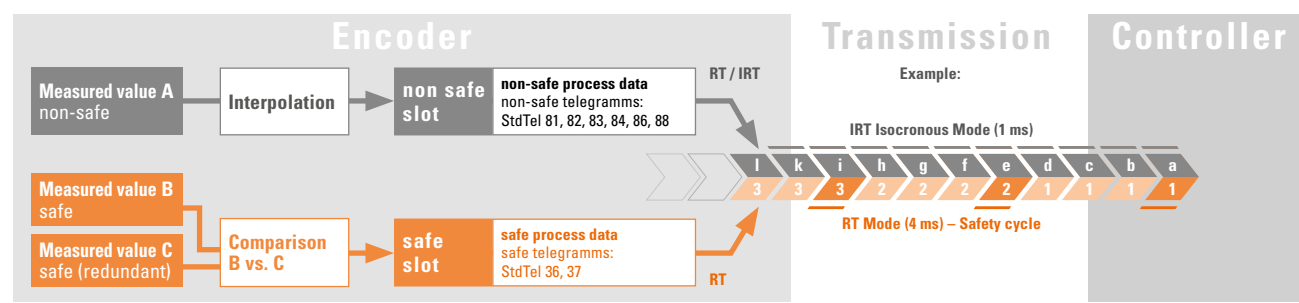
In safety-related applications, safe process data is required for sequence control, which must be detected at least redundantly and provided reliably.

With high performance controllers, it is possible to compare the two measured values against each other and thus generate safe process data. This data can be directly evaluated, calculated or scaled in the sensor before it is transferred.

Since there are restrictions on the resolution and transmission speed for safe process data due to the comparison of the redundant measured values, it can happen that non-safe process data is also required in addition to the safe data, for example to transmit a high-resolution position to the following periphery.

The safe process data is then sent via the same infrastructure as the non-safe process data according to the so-called „black channel“ principle. From the point of view of the protocol used, this takes place in a separate area (safe slot) that is distinct from the non-safe area (non-safe slot). Both transmissions can run parallel to each other.

Unlike with safe data, the non-safe process data can also be sent at a specified clock cycle of the controller (isochronous mode).



# Absolute encoders – singleturn

## Standard optical

Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)

PROFIsafe

### Dimensions shaft version

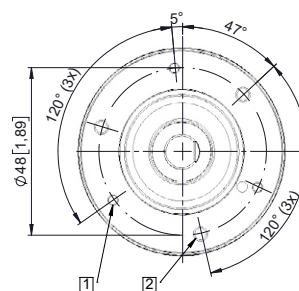
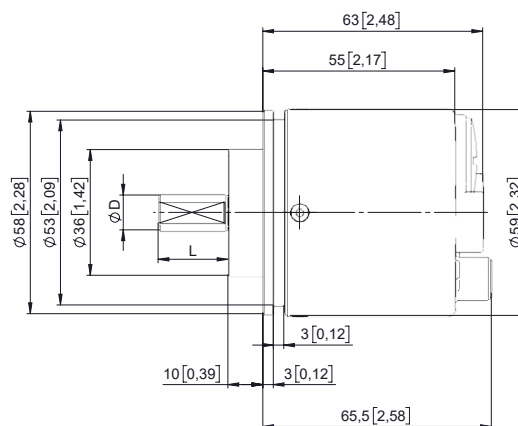
Dimensions in mm [inch]

#### Clamping flange, $\varnothing$ 58 [2.28]

Flange type 1 + 3

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.31] deep

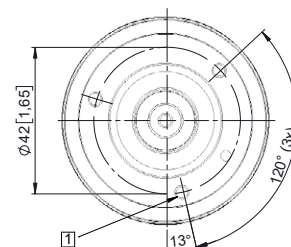
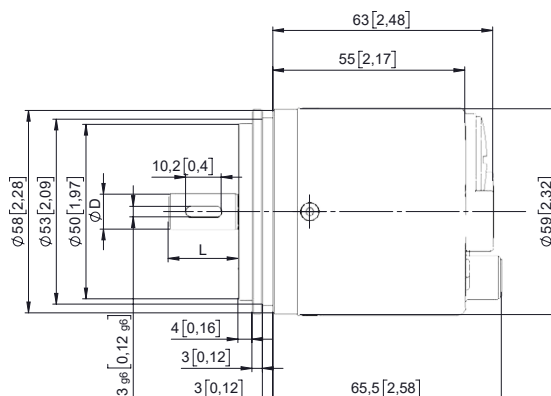


D	Fit	L
10 [0.39]	h7	20 [0.79]
12 [0.47]	h7	20 [0.79]
3/8"	h7	7/8"

#### Synchro flange, $\varnothing$ 58 [2.28]

Flange type 2 + 4

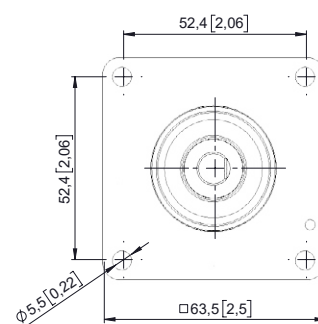
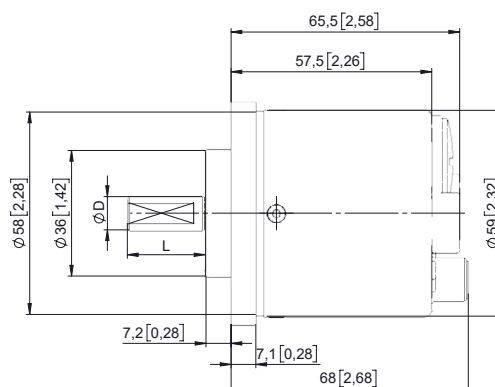
1 3 x M4, 8 [0.31] deep



D	Fit	L
10 [0.39]	h7	20 [0.79]
12 [0.47]	h7	20 [0.79]
3/8"	h7	7/8"

#### Square flange, $\square$ 63.5 [2.5]

Flange type 5 + 7



D	Fit	L
10 [0.39]	h7	20 [0.79]
12 [0.47]	h7	20 [0.79]
3/8"	h7	7/8"



# Absolute encoders – singleturn

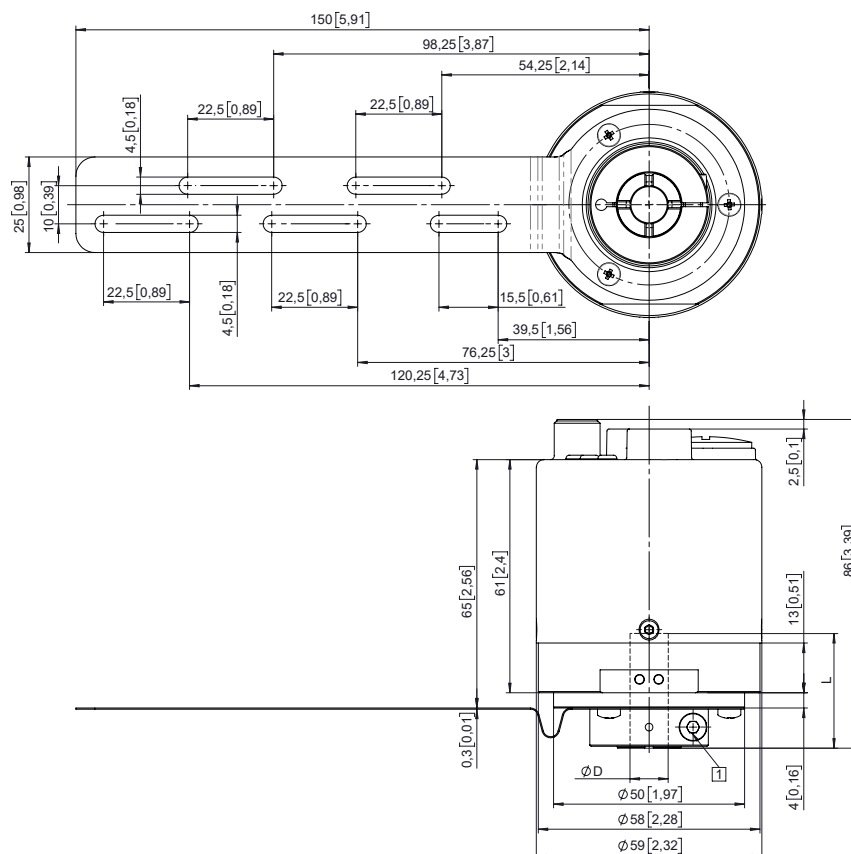
Standard optical	Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)	PROIfsafe
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## Dimensions hollow shaft version

Dimensions in mm [inch]

### Flange with torque stop FS, flexible Flange type 1 + 2

- 1 Recommended torque for the clamping ring 2.5 Nm

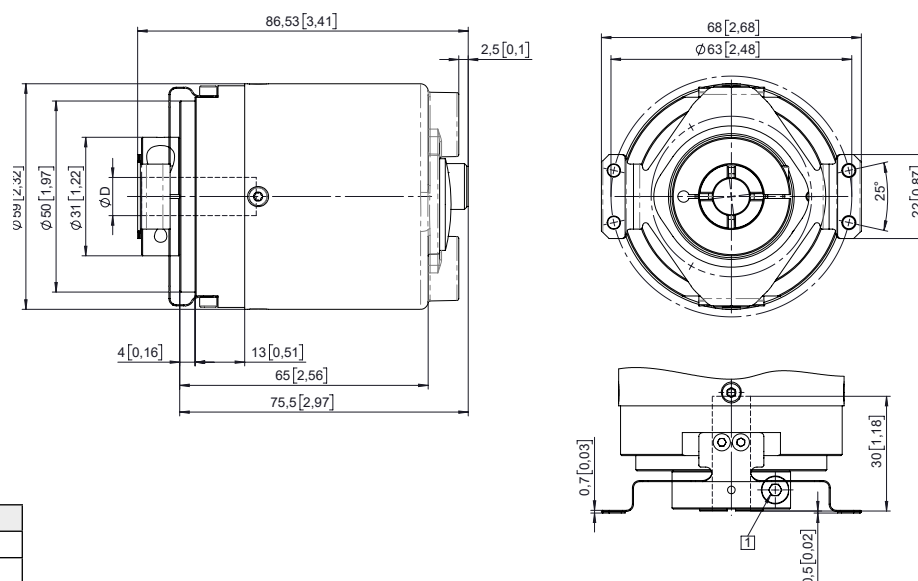


D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

### Flange with stator coupling FS, ø 63 [2.48] Flange type 5 + 6

- 1 Recommended torque for the clamping ring 2.5 Nm



D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

## Absolute encoders – singleturn

## Standard optical

### Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)

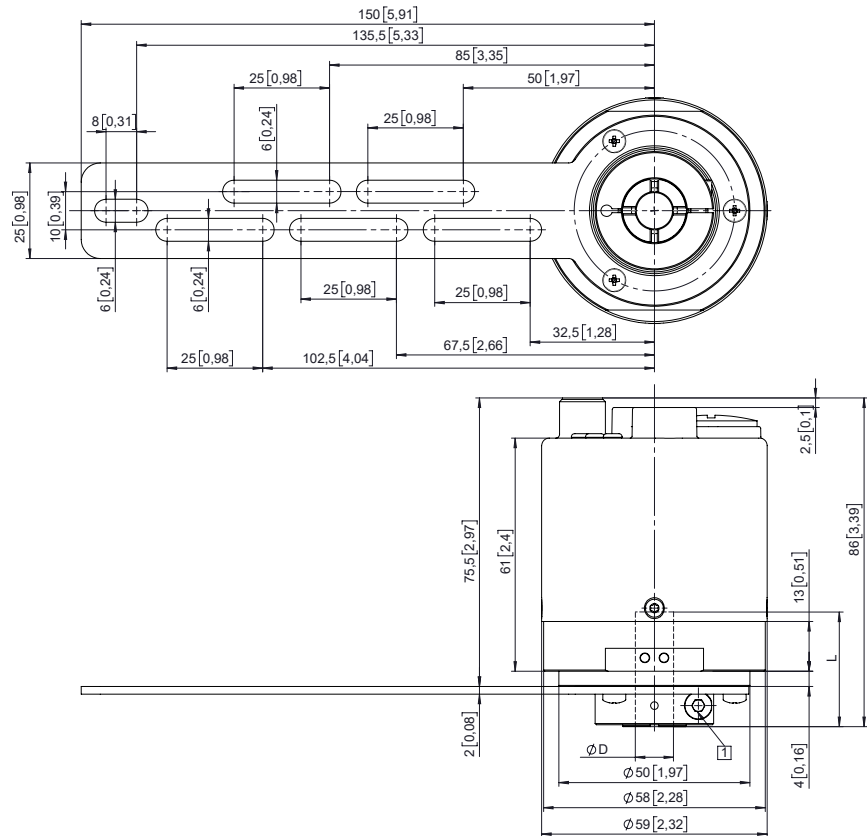
**PROFlsafe**

### Dimensions hollow shaft version

Dimensions in mm [inch]

**Flange with torque stop FS, rigid**  
**Flange type 7 + 8**

- 1** Recommended torque for the clamping ring 2.5 Nm

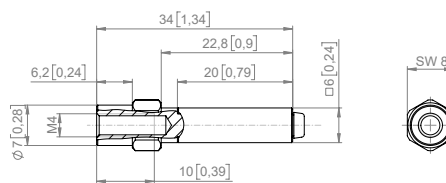


D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

L = insertion depth max. blind hollow shaft

Torque pin with rectangular sleeve with  
M4 thread  
(included in scope of delivery)



# Absolute encoders – singleturn

**Standard  
optical**

**Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)**

**PROFIsafe**



The optical absolute Sendix S58 PROFIsafe encoders are based on the new Kübler Industrial Ethernet encoder platform and are therefore already designed today for future Industry 4.0 concepts.

One example of this is the integrated web server: Features or adjustments can be implemented quickly and easily at any time.

As certified SIL3 / PLe encoders with redundant design and PROFINET interface, they support the PROFIsafe profile and are predestined for safety applications.



Safety-Lock™



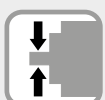
High rotational speed



Temperature range  
-40°C...+80°C



High protection level  
IP67



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Reverse polarity protection



Optical sensor

## Reliable and safe

- **Robust**  
Sturdy bearing construction in Safety-Lock™ Design for resistance against vibration and installation errors.
- **High resolution**  
- Singleturn 15 bit (safe) or 24 bit (non safe).
- **Safe**  
- SIL 3, performance level PLe, safety category Cat. 3.  
- Transmission via safety telegrams 36/37, according to BP and XP.
- **100 % future-proof**  
- Implement features and adaptations quickly and easily.  
- Cyber Security update in preparation / High system availability, protection against misuse (acc. IEC 62443).

## Latest PROFINET functionality

- PROFINET IO, RT, IRT allows integration in applications with different performance requirements.
- Supports the Isochronous Mode, can thus be implemented in networks for hard real-time requirements with clock cycles up to 500 µs.
- PROFINET v2.4.1, encoder profile V 4.2, PROFIsafe profile v2.6.1, PROFIdrive profile v4.2
- Ideal for highly synchronous applications, such as e. g. axis synchronization.
- Interoperability between many different control and drive manufacturers thanks to the PROFIdrive profile.
- Integrated web server for firmware update.

# Absolute encoders – singleturn

Standard optical	Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)	PROFIsafe
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Order code	8.S5858FS3	.XXCN.C111	
Shaft version	Type	a b c d e	
<b>a</b> Flange	1 = clamping flange, IP65 ø 58 mm [2.28"] 3 = clamping flange, IP67 ø 58 mm [2.28"] 2 = synchro flange, IP65 ø 58 mm [2.28"] 4 = synchro flange, IP67 ø 58 mm [2.28"] 5 = square flange, IP65 □ 63.5 mm [2.5"] 7 = square flange, IP67 □ 63.5 mm [2.5"]	<b>c</b> Interface / Supply voltage C = PROFINET IO / 10 ... 30 V DC	
<b>b</b> Shaft (ø x L), with flat	2 = 10 x 20 mm [0.39 x 0.79"] 5 = 12 x 20 mm [0.47 x 0.79"] 4 = 3/8" x 7/8" Shaft (ø x L), with feather key DIN 6885 A-3x3x10 A = 10 x 20 mm [0.39 x 0.79"] B = 12 x 20 mm [0.47 x 0.79"] C = 3/8" x 7/8"	<b>d</b> Type of connection N = 3 x axial M12 connector, 4-pin  <b>e</b> Fieldbus profile C1 = PROFINET IO  Optional on request - Ex 2/22 (only for variants with IP67) - surface protection salt spray tested	

Order code	8.S5878FS3	.XXCN.C111	
Hollow shaft	Type	a b c d e	
<b>a</b> Flange	1 = with torque stop FS, flexible, IP65 2 = with torque stop FS, flexible, IP67 5 = with stator coupling FS, ø 63 mm [2.48"], IP65 6 = with stator coupling FS, ø 63 mm [2.48"], IP67 7 = with torque stop FS, rigid, IP65 (incl. torque pin FS) 8 = with torque stop FS, rigid, IP67 (incl. torque pin FS)	<b>c</b> Interface / Supply voltage C = PROFINET IO / 10 ... 30 V DC	
<b>b</b> Blind hollow shaft (insertion depth max. 30 mm [1.18"])	A = ø 10 mm [0.39"] B = ø 12 mm [0.47"] C = ø 14 mm [0.55"] D = ø 15 mm [0.59"] E = ø 3/8" F = ø 1/2"	<b>d</b> Type of connection N = 3 x axial M12 connector, 4-pin  <b>e</b> Fieldbus profile C1 = PROFINET IO  Optional on request - Ex 2/22 (only for variants with IP67) - surface protection salt spray tested	

## Absolute encoders – singleturn

Standard optical		Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)	PROFIsafe
Mounting accessory for shaft encoders			Order no.
Bellows coupling FS	bellows coupling FS ø 25 mm [0.98"] for shaft 10 mm [0.39"]		8.0000.15FS.1010
	bellows coupling FS ø 25 mm [0.98"] for shaft 12 mm [0.47"]		8.0000.15FS.1212
Accessories			Order no.
Screw retention	Loctite 243, 5 ml		8.0000.4G05.0000
Cables and connectors			Order no.
Preassembled cables	M12 male connector with external thread, 4-pin, D coded, straight single-ended 2 m [6.56'] PUR cable	port 1 + port 2	05.00.6031.4411.002M
	M12 male connector with external thread, 4-pin, D coded, right-angle single-ended 2 m [6.56'] PUR cable	port 1 + port 2	05.00.6031.4511.002M
	M12 female connector with coupling nut, 4-pin, A coded, straight single-ended 2 m [6.56'] PUR cable	power supply	05.00.6061.6211.002M
	M12 female connector with coupling nut, 4-pin, A coded, right-angle single-ended 2 m [6.56'] PUR cable	power supply	05.00.6061.6311.002M
Connectors	M12 male connector with external thread, 4-pin, D coded, straight (metal)	port 1 + port 2	05.WASCSY4S
	M12 male connector with external thread, 4-pin, D coded, right-angle (metal)	port 1 + port 2	8.0000.5128.0000
	M12 female connector with coupling nut, 4-pin, A coded, straight (plastic)	power supply	05.B8141-0
	M12 female connector with coupling nut, 4-pin, A coded, right-angle (plastic)	power supply	05.B8241-0

Further Kübler accessories can be found at: [/accessories](#)

Further Kübler cables and connectors can be found at: [/connection-technology](#)

# Absolute encoders – singleturn

<b>Standard optical</b>	<b>Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)</b>	<b>PROFIsafe</b>
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## Technical data

Notes regarding “Functional Safety”
These encoders are suitable for use in safety-related systems up to SIL3 acc. to EN 61800-5-2 and PLe to EN ISO 13849-1 in conjunction with controllers or evaluation units, which possess the necessary functionality. Additional functions can be found in the operating manual.

Safety characteristics	
Classification	PLe / SIL3
System structure	2 channel (Kat. 3)
PFH <sub>d</sub> value <sup>1)</sup>	9,54 x 10 <sup>-10</sup> h <sup>-1</sup>
Mission time / Proof test interval	20 years
Relevant standards	EN ISO 13849-1:2015; EN ISO 13849-2:2012; EN 61800-5-2:2007

Mechanical characteristics		
Max. speed		9000 min <sup>-1</sup> (short-term – 10 min) 6000 min <sup>-1</sup> (continuous)
Starting torque at 20 °C [68 °F]		< 0.01 Nm
Moment of inertia		
	shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
	blind hollow shaft version	4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
Load capacity of shaft	radial	80 N
	axial	40 N
Weight		approx. 0.45 kg [15.87 oz]
Protection acc. to EN 60529		IP65, IP67
Ambient temperature		-40 °C ... +80 °C [-40 °F ... +176 °F]
Material	shaft/hollow shaft flange housing	stainless steel aluminum aluminum
Shock resistance acc. EN 60068-2-27		1000 m/s <sup>2</sup> , 6 ms
Vibration resistance acc. EN 60068-2-6		100 m/s <sup>2</sup> , 55 ... 2000 Hz

Electrical characteristics	
Supply voltage	10 ... 30 V DC
Power consumption (no load)	max. 250 mA
Reverse polarity protection of the supply voltage (+V)	yes
Smallest safe measuring step	158,4 arcsec (0,044° / 4 increments)
Lowest safe speed	4 rpm ( $\sigma_v < 0,5 \%$ )

Approvals		
UL compliant in accordance with		File no. E224618
CE compliant in accordance with		
EMC Directive	2014/30/EU	
RoHS Directive	2011/65/EU	
ATEX Directive	2014/34/EU (for Ex 2/22 variants)	
Machinery Directive	2006/42/EG	

1) The specified value is based on a diagnostic coverage of 99 %, that must be achieved with an encoder evaluation unit.  
The encoder evaluation unit must meet at least the requirements for SIL3.




# Absolute encoders – singleturn

<b>Standard optical</b>	<b>Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)</b>	<b>PROFIsafe</b>
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## Interface characteristics PROFIsafe

General information		Adjustable parameters	
<b>Protocol</b>	PROFINET IO / PROFIsafe	<ul style="list-style-type: none"> <li>• Preset</li> <li>• Counting direction</li> <li>• Resolution per revolution - MUR</li> <li>• Unit speed</li> <li>• IP address</li> <li>• Total resolution - TMR</li> <li>• Position format</li> <li>• Speed reference value</li> </ul>	<ul style="list-style-type: none"> <li>• Scaling</li> <li>• Device name</li> <li>• F-Destination Address</li> <li>• I&amp;M 0...3 Parameter</li> <li>• Alarm behavior</li> <li>• Parameter write protection</li> <li>• Parameter initialization</li> </ul>
<b>Classifications</b>	RT Class 3 (IRT) Conformance Class C Application Class 6 Encoder Class 4 / S2 Netload Class III		
Resolution		PROFIsafe characteristics	
<b>Resolution Singleturn (MUR)</b>	scalable safe 1 ... 32 768 (15 bit) scalable non-safe 1 ... 16 777 216 (24 bit) default 8 192 (13 bit)	<ul style="list-style-type: none"> <li>• I&amp;M 0 ... 4</li> <li>• standard telegrams (81, 82, 83, 84, 86, 88)</li> <li>• standard safety telegrams (36, 37) BP and XP</li> <li>• IRT up to 500 µs</li> <li>• RT Safe up to 4 ms</li> </ul>	<ul style="list-style-type: none"> <li>• Isochronous Mode</li> <li>• MRP</li> <li>• LLDP</li> <li>• PDEV</li> <li>• SNMP</li> <li>• FSU</li> </ul>
		Process data	
		<ul style="list-style-type: none"> <li>• Position (Safe / Non-Safe)</li> <li>• Speed (Safe / Non-Safe)</li> </ul>	<ul style="list-style-type: none"> <li>• Failure</li> <li>• Warnings</li> </ul>

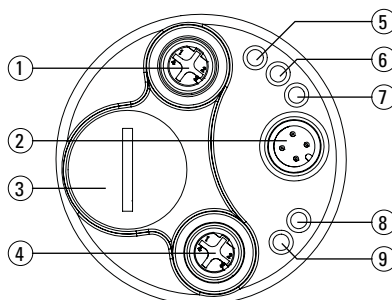
## Terminal assignment bus

Interface	Type of connection	Function	M12 connector, 4-pin						
C	N (3 x M12 connector)	Bus Port 1	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -		D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-		
			Pin:	1	2	3	4		
		Power supply	Signal:	Voltage +	—	Voltage —	—		
			Abbreviation:	+ V	—	0 V	—		
			Pin:	1	2	3	4		
		Bus Port 2	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -		D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-		
			Pin:	1	2	3	4		

## Rear side connections and display elements

①	Ethernet Port – Link 2	
②	Supply voltage	
③	Cover screw	
④	Ethernet Port – Link 1	
⑤	Link 2	flashes yellow when connected
⑥	BF – Bus Failure	displays network errors *)
⑦	SF – System Failure	displays system errors *)
⑧	ENC	shows status of encoder *)
⑨	Link 1	flashes yellow when connected

\*) see manual



# Absolute encoders – singleturn

**Standard  
optical**

**Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)**

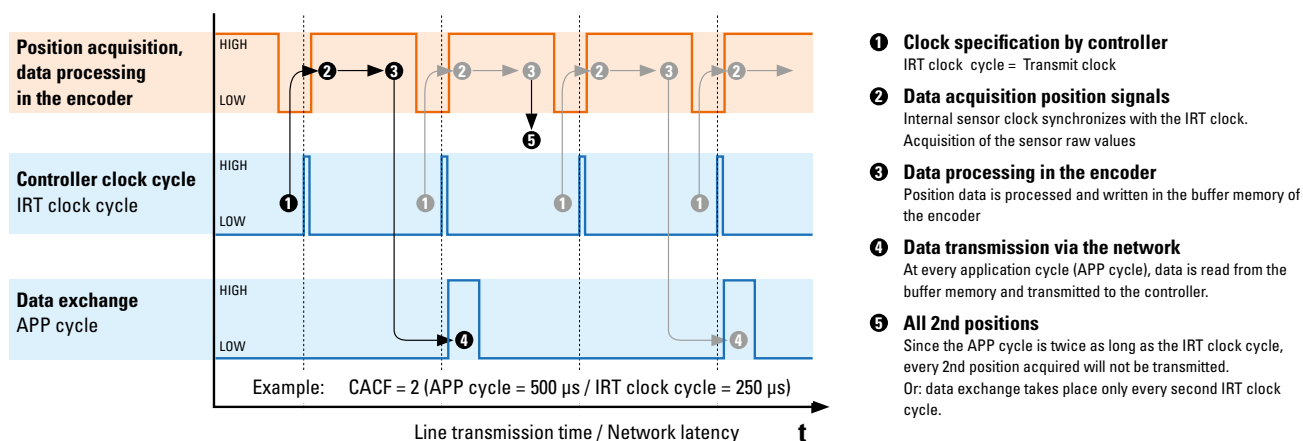
**PROFIsafe**

## Technology in detail

### Clock synchronicity – Isochronous Real Time (IRT) in position sensor technology

In general, for time-critical applications, focus is set on very short sensor cycle times. However, in order to achieve high control performance, simply accelerating data acquisition and processing by shortest cycle times is not sufficient. All sensors and actuators are to operate according to the same clock.

This is achieved thanks to a clock used for the whole network, defined by the controller. This transmit clock cycle (IRT clock) is however not necessarily the clock cycle used for process data exchange. Another cycle (application cycle) is used for this purpose, which can also be defined by the customer controller. The illustration below represents the connection between the different clock cycles.



When receiving the IRT clock signal, the sensor starts reading its current measured point. This raw value is processed internally (e.g. scaling, speed calculation, etc.) and stored in a buffer memory.

The buffer memory is read at every application cycle. If it contains a value, this value is transmitted to the controller via the network.

If the application cycle is a multiple of the IRT clock cycle, it may happen that the buffered process data is not sent directly, but is overwritten, because, even though this data is acquired with every IRT clock cycle, it is sent only with every application cycle.

The ratio between application cycle and IRT clock cycle represents the CACF (Controller Application Cycle Factor).

In this example, the CACF = 2. This indicates that only every 2nd acquired position will be transmitted to the controller.

The described methodology guarantees a determinism: since the controller defines a clock cycle for the whole network, this allows ensuring that all measured values transmitted by the sensors to the controller are never older than the selected IRT cycle! Therefore, all downstream actuators can always be regulated on the basis of the latest available measured values.

### PROFIsafe encoders – Data flow of safe and non-safe position values

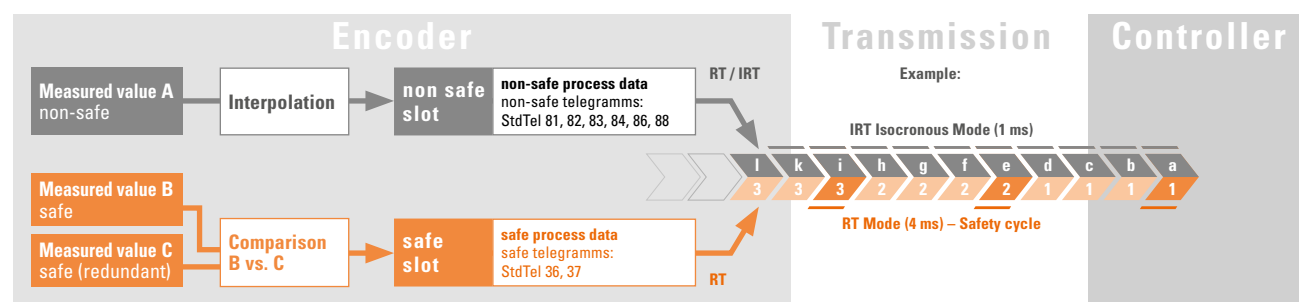
In safety-related applications, safe process data is required for sequence control, which must be detected at least redundantly and provided reliably.

With high performance controllers, it is possible to compare the two measured values against each other and thus generate safe process data. This data can be directly evaluated, calculated or scaled in the sensor before it is transferred.

Since there are restrictions on the resolution and transmission speed for safe process data due to the comparison of the redundant measured values, it can happen that non-safe process data is also required in addition to the safe data, for example to transmit a high-resolution position to the following periphery.

The safe process data is then sent via the same infrastructure as the non-safe process data according to the so-called „black channel“ principle. From the point of view of the protocol used, this takes place in a separate area (safe slot) that is distinct from the non-safe area (non-safe slot). Both transmissions can run parallel to each other.

Unlike with safe data, the non-safe process data can also be sent at a specified clock cycle of the controller (isochronous mode).





# Absolute encoders – singleturn

## Standard optical

Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)

PROFlsafe

### Dimensions shaft version

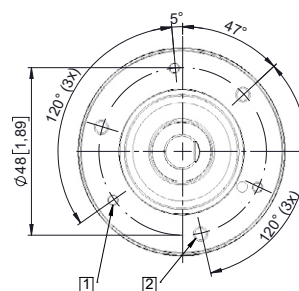
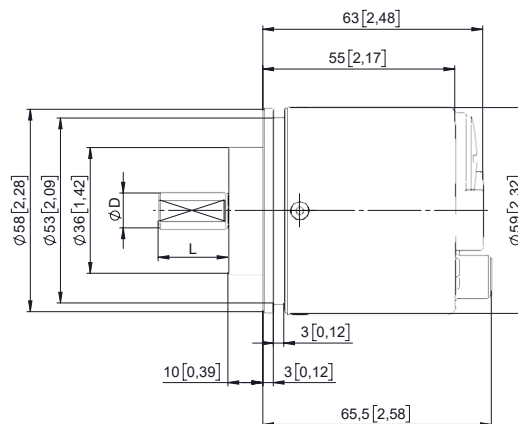
Dimensions in mm [inch]

#### Clamping flange, $\varnothing$ 58 [2.28]

##### Flange type 1 + 3

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.31] deep

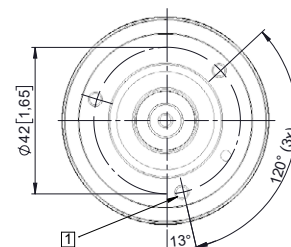
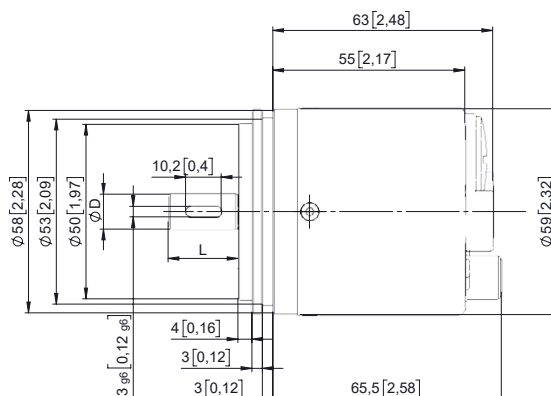


D	Fit	L
10 [0.39]	h7	20 [0.79]
12 [0.47]	h7	20 [0.79]
3/8"	h7	7/8"

#### Synchro flange, $\varnothing$ 58 [2.28]

##### Flange type 2 + 4

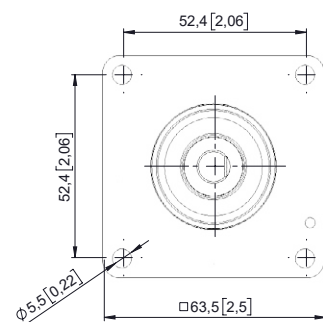
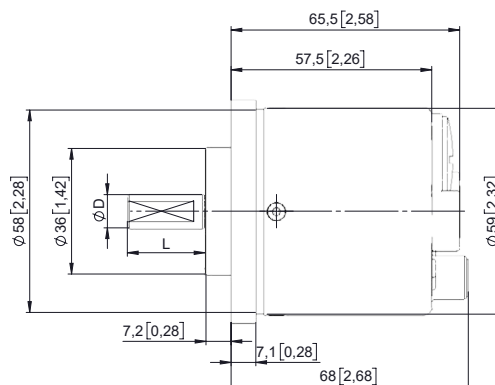
1 3 x M4, 8 [0.31] deep



D	Fit	L
10 [0.39]	h7	20 [0.79]
12 [0.47]	h7	20 [0.79]
3/8"	h7	7/8"

#### Square flange, $\square$ 63.5 [2.5]

##### Flange type 5 + 7



D	Fit	L
10 [0.39]	h7	20 [0.79]
12 [0.47]	h7	20 [0.79]
3/8"	h7	7/8"

# Absolute encoders – singleturn

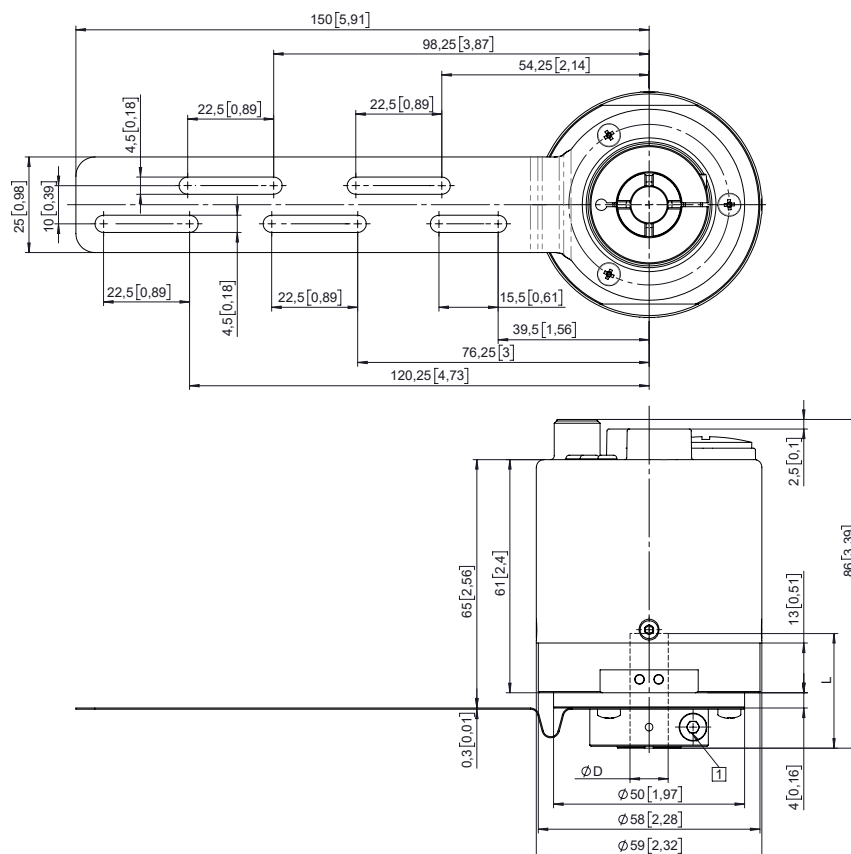
Standard optical	Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)	PROFlsafe
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## Dimensions hollow shaft version

Dimensions in mm [inch]

### Flange with torque stop FS, flexible Flange type 1 + 2

- 1 Recommended torque for the clamping ring 2.5 Nm

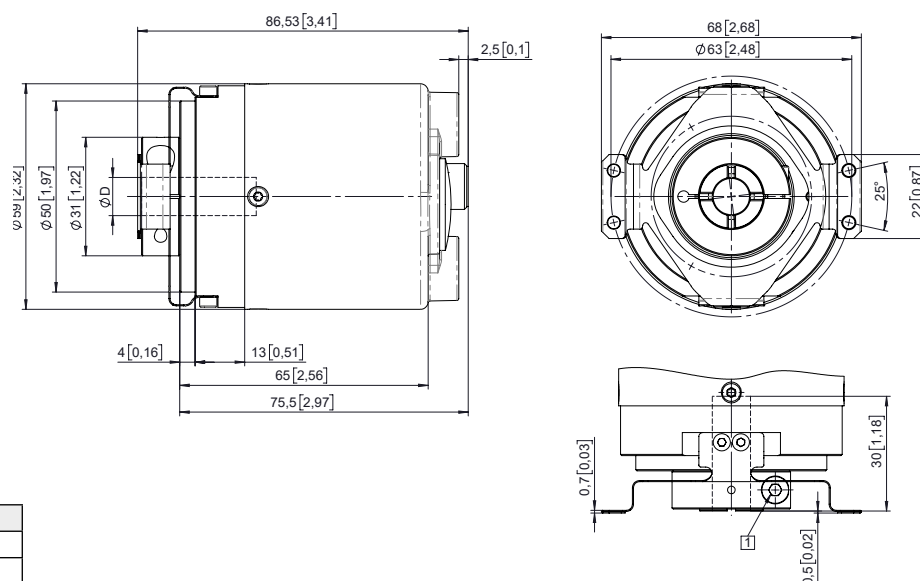


D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

### Flange with stator coupling FS, ø 63 [2.48] Flange type 5 + 6

- 1 Recommended torque for the clamping ring 2.5 Nm



D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

# Absolute encoders – singleturn

**Standard  
optical**

**Sendix S5858FS3 / S5878FS3 (shaft / hollow shaft)**

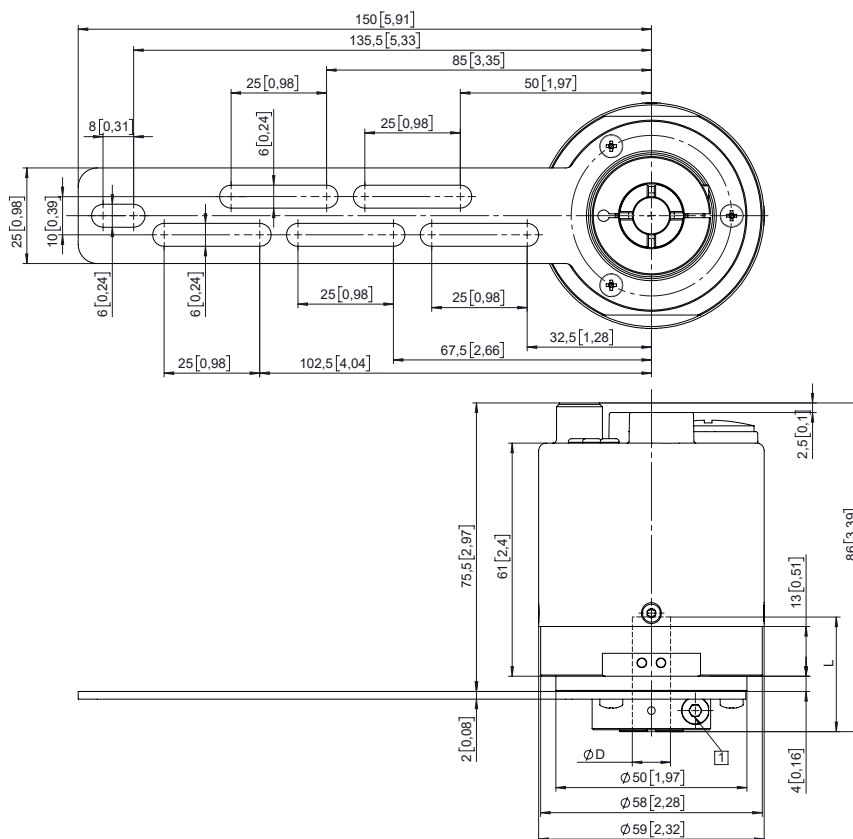
**PROFIsafe**

## Dimensions hollow shaft version

Dimensions in mm [inch]

**Flange with torque stop FS, rigid  
Flange type 7 + 8**

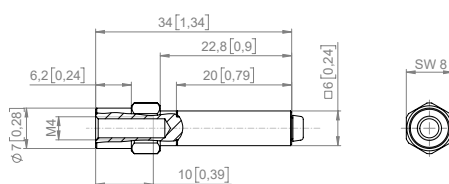
1 Recommended torque for the  
clamping ring 2.5 Nm



D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

**Torque pin with rectangular sleeve with  
M4 thread  
(included in scope of delivery)**



# Absolute encoders – singleturn

**Standard  
optical**

**Sendix F5858 / F5878 (shaft / hollow shaft)**

**EtherNet/IP**



## New generation - ready for the future.

The optical absolute singleturn and multiturn Sendix F58 EtherNet/IP encoders are based on the latest CIP version v3.32 and EtherNet/IP version v1.30.

Key features are neighborhood detection, gear factor, the calculation of acceleration and simultaneous connection to up to 5 controllers. Thanks to the new framework, the functionality can be extended at any time via the integrated web server by update.



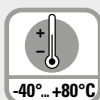
**EtherNet/IP™**



Safety-Lock™



High rotational  
speed



Temperature  
range  
-40°C...+80°C



High protection  
level  
IP67



High shaft load  
capacity



Shock / vibration  
resistant



Magnetic field  
proof



Reverse polarity  
protection



Optical sensor

## Features

- Scaling of the total resolution via the gear factor.
- High resolution: singleturn up to 19 bit.
- High-precision setting of velocity and acceleration values through filter and hysteresis.
- Device Level Ring (DLR) ring redundancy of the network with two network ports.
- Low RPI time of minimum 1 ms - this makes the encoder usable for time-critical applications up to 1000 Hz update frequency.

## Benefits


- Direct mapping of pitch ratios, e.g. for gear ratios or gear reductions.
- Precise position detection.
- Cost and time savings when setting up the control system.
- Communication is maintained when the ring structure is interrupted.

# Absolute encoders – singleturn


Standard optical	Sendix F5858 / F5878 (shaft / hollow shaft)	EtherNet/IP
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Order code	8.F5858 . XXAN . A3 2 2					
Shaft version	Type	a	b	c	d	e
<b>a</b> Flange	1 = clamping flange, IP65 ø 58 mm [2.28"] 3 = clamping flange, IP67 ø 58 mm [2.28"] 2 = synchro flange, IP65 ø 58 mm [2.28"] 4 = synchro flange, IP67 ø 58 mm [2.28"] 5 = square flange, IP65 □ 63.5 mm [2.5"] 7 = square flange, IP67 □ 63.5 mm [2.5"]					
<b>b</b> Shaft (ø x L), with flat	1 = 6 x 10 mm [0.24 x 0.39"] 2 = 10 x 20 mm [0.39 x 0.79"] 3 = 1/4" x 7/8" 4 = 3/8" x 7/8"					
<b>c</b> Interface / Supply voltage	A = EtherNet/IP / 10 ... 30 V DC					
<b>d</b> Type of connection	N = 3 x axial M12 connector, 4-pin					
<b>e</b> Fieldbus profile	A3 = EtherNet/IP					


*Options – Standard types (available from 1 piece)*



Surface protection salt spray tested with clamping flange IP67 and shaft ø 10 mm:  
8.F5858.32AN.A322-**C**



Stainless steel V2A <sup>1)</sup>  
Order expansion:  
8.F5858.XXAN.A322-**V2A**



Stainless steel V4A <sup>1)</sup>  
Order expansion:  
8.F5858.XXAN.A322-**V4A**

*Options – on request (for other flange/shaft combinations)*

- Surface protection salt spray tested
- Stainless steel V2A
- Stainless steel V4A

Order code	8.F5878	.	X	X	A	N	.	A3	2	2
Hollow shaft	Type		a	b	c	d		e		

**a** Flange

1 = with spring element long, IP65  
2 = with spring element long, IP67  
3 = with stator coupling, IP65 ø 65 mm [2.56"]  
4 = with stator coupling, IP67 ø 65 mm [2.56"]  
5 = with stator coupling, IP65 ø 63 mm [2.48"]  
6 = with stator coupling, IP67 ø 63 mm [2.48"]  
9 = with torque stop, flexible, IP65  
J = with torque stop, flexible, IP67

**b** Blind hollow shaft (insertion depth max. 30 mm [1.18"])

A = ø 10 mm [0.39"]  
B = ø 12 mm [0.47"]  
C = ø 14 mm [0.55"]  
D = ø 15 mm [0.59"]  
E = ø 3/8"  
F = ø 1/2"

**c** Interface / Supply voltage

A = EtherNet/IP / 10 ... 30 V DC

**d** Type of connection

N = 3 x axial M12 connector, 4-pin

**e** Fieldbus profile

A3 = EtherNet/IP

Options – Standard types (available from 1 piece)

**V2A**  
DIN 1.4305  
AISI 303

Stainless steel V2A <sup>2)</sup>  
Order expansion:  
8.F5878.2XAN.A322-**V2A**

**V4A**  
DIN 1.4404  
AISI 316L

Stainless steel V4A <sup>2)</sup>  
Order expansion:  
8.F5878.2XAN.A322-**V4A**

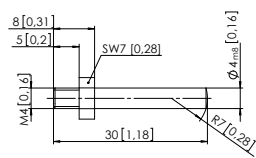
Options – on request (for other flange/hollow shaft combinations)

- Surface protection salt spray tested
- Stainless steel V2A
- Stainless steel V4A

1) Only in conjunction with flange **a** = 3 or 4 and shaft **b** = 1 or 2.

2) Only in conjunction with flange **a** = 2 and hollow shaft **b** = B or D.

# Absolute encoders – singleturn

Standard optical		Sendix F5858 / F5878 (shaft / hollow shaft)	EtherNet/IP
Mounting accessory for shaft encoders			Order no.
Coupling	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]		8.0000.1102.0606
	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]		8.0000.1102.1010
Mounting accessory for hollow shaft encoders Dimensions in mm [inch]			Order no.
Torque pin, ø 4 mm for flange with spring element (flange type 1)	with fixing thread		8.0010.4700.0000
			
Cables and connectors			Order no.
Preassembled cables	M12 male connector with external thread, 4-pin, D coded, straight single-ended 2 m [6.56'] PUR cable	port 1 + port 2	05.00.6031.4411.002M
	M12 male connector with external thread, 4-pin, D coded, right-angle single-ended 2 m [6.56'] PUR cable	port 1 + port 2	05.00.6031.4511.002M
	M12 female connector with coupling nut, 4-pin, A coded, straight single-ended 2 m [6.56'] PUR cable	power supply	05.00.6061.6211.002M
	M12 female connector with coupling nut, 4-pin, A coded, right-angle single-ended 2 m [6.56'] PUR cable	power supply	05.00.6061.6311.002M
Connectors	M12 male connector with external thread, 4-pin, D coded, straight (metal)	port 1 + port 2	05.WASCSY4S
	M12 male connector with external thread, 4-pin, D coded, right-angle (metal)	port 1 + port 2	8.0000.5128.0000
	M12 female connector with coupling nut, 4-pin, A coded, straight (plastic)	power supply	05.B8141-0
	M12 female connector with coupling nut, 4-pin, A coded, right-angle (plastic)	power supply	05.B8241-0

Further Kübler accessories can be found at: [/accessories](#)

Further Kübler cables and connectors can be found at: [/connection-technology](#)

# Absolute encoders – singleturn

Standard optical	Sendix F5858 / F5878 (shaft / hollow shaft)	EtherNet/IP
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## Technical data

Mechanical characteristics				
Max. speed		9000 min <sup>-1</sup> (short-term – 10 min)		
		6000 min <sup>-1</sup> (continuous)		
Starting torque at 20 °C [68 °F]		< 0.01 Nm		
Moment of inertia	shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup>		
	blind hollow shaft version	4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>		
Load capacity of shaft	radial	80 N		
	axial	40 N		
Weight		approx. 0.45 kg [15.87 oz]		
Protection acc. to EN 60529		IP65, IP67		
Working temperature range		-40 °C ... +80 °C [-40 °F ... +176 °F]		
Material	Standard	V2A	V4A	
		DIN 1.4305	DIN 1.4404	
		AISI 303	AISI 316L	
	shaft/hollow shaft	V2A	V2A	V4A
	flange	aluminum	V2A	V4A
	housing	aluminum	V2A	V4A
Shock resistance acc. EN 60068-2-27		2500 m/s <sup>2</sup> , 6 ms		
Vibration resistance acc. EN 60068-2-6		100 m/s <sup>2</sup> , 55 ... 2000 Hz		

Electrical characteristics	
Power supply	10 ... 30 V DC
Current consumption (at 24 V DC)	max. 45 mA
Power consumption	max. 1.5 W
Reverse polarity protection of the power supply (V+)	yes

Approvals	
UL compliant in accordance with	File no. E224618
CE compliant in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU

## Interface characteristics EtherNet/IP

General information		
EtherNet/IP conformance tested acc. to	version CT-12 of 11. Dez. 2014	
EtherNet/IP specification	Vol 2, Ed 1.17	
CIP specification	Vol 1, Ed 3.16	
Protocol		
	F58x8 Standards & Features	CIP Version v3.32
		Ethernet/IP Version v1.30
		LLDP
		BOOTP
		DHCP
	Device Profile	Encoder Device

Resolution		
Resolution singleturn (MUR)		
	scalable	1 ... 524 288 (19 bit)
	default	262 144 (18 bit)

Adjustable parameters	
<ul style="list-style-type: none"> <li>• Preset</li> <li>• Count direction</li> <li>• Resolution</li> <li>• Unity of speed</li> <li>• IP address</li> <li>• Number of revolutions</li> <li>• Position</li> <li>• Position format</li> <li>• Position limit</li> </ul>	<ul style="list-style-type: none"> <li>• Acceleration unit</li> <li>• Speed limit</li> <li>• Acceleration limit</li> <li>• Scaling</li> <li>• Gear factor</li> <li>• Filter for speed and acceleration</li> <li>• Hysteresis for speed and acceleration</li> </ul>

Objects (CIP Objects)	
<ul style="list-style-type: none"> <li>• Identity Object</li> <li>• Message Router</li> <li>• Assembly Object</li> <li>• Connection Manager</li> <li>• Position Sensor Object</li> </ul>	<ul style="list-style-type: none"> <li>• Qos Object</li> <li>• Port Object</li> <li>• TCP / IP Interface Object</li> <li>• EtherNet Link Object</li> </ul>

EtherNet/IP features	
<ul style="list-style-type: none"> <li>• DLR (Device Level Ring) possible</li> <li>• Qos (Quality of Service) possible</li> <li>• ACD (Address Conflict Detection)</li> </ul>	<ul style="list-style-type: none"> <li>• Multicast and unicast capability</li> <li>• Up to 5 PLC connections</li> </ul>

Process data	
<ul style="list-style-type: none"> <li>• Position</li> <li>• Speed data</li> <li>• Acceleration</li> <li>• Errors</li> <li>• Alarms</li> </ul>	<ul style="list-style-type: none"> <li>• Warnings</li> <li>• Offset (for preset)</li> <li>• Battery voltage</li> <li>• Operating voltage</li> <li>• Temperature</li> </ul>




# Absolute encoders – singleturn

**Standard  
optical**

**Sendix F5858 / F5878 (shaft / hollow shaft)**

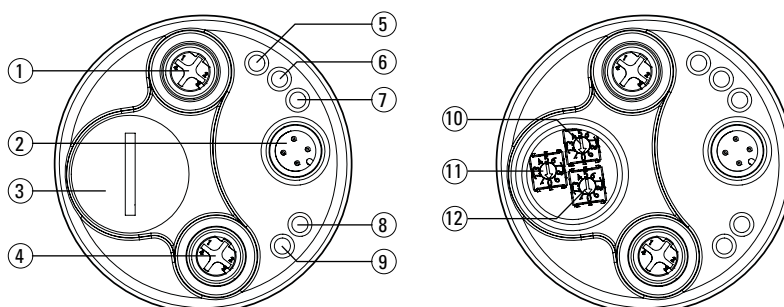
**EtherNet/IP**

## Terminal assignment bus

Interface	Type of connection	Function	M12 connector, 4-pin					
A	N (3 x M12 connector)	Bus Port 1	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	 D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	
		Power supply	Signal:	Voltage +	–	Voltage –	–	
			Abbreviation:	+ V	–	0 V	–	
			Pin:	1	2	3	4	
		Bus Port 2	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	 D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	

## Rear side connections and display elements

①	Ethernet Port – Link 2	
②	Supply voltage	
③	Cover screw	
④	Ethernet Port – Link 1	
⑤	Link 2	flashes yellow when connected
⑥	BF – Bus Failure	displays network errors *)
⑦	SF – System Failure	displays system errors *)
⑧	ENC	Shows status of encoder *)
⑨	Link 1	flashes yellow when connected
⑩	Switch: x 100	
⑪	Switch: x 10	
⑫	Switch: x 1	



\*) see manual

## Settings rotary switch

Switch position	Meaning
000	Address assignment via DHCP
1 ... 254	Use stored subnet (standard: 192.168.1.x, mask: 255.255.255.0) The last digit „x“ of the IP address is determined by the rotary switch.
300	Explicit Protection Mode OFF
555	Resetting the encoder to factory setting. To reset, this switch position must be set. If necessary, switch off the operating voltage and switch it on again within 10 seconds. After that, the encoder can be switched off and the switch setting desired during operation can be made. All parameters are now set to factory settings - both the encoder objects and the TCP/IP settings.
800	Explicit Protection Mode ON
Other positions	Reserved, do not use!



# Absolute encoders – singleturn

Standard optical	Sendix F5858 / F5878 (shaft / hollow shaft)	EtherNet/IP
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## Dimensions shaft version

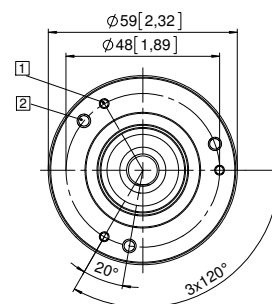
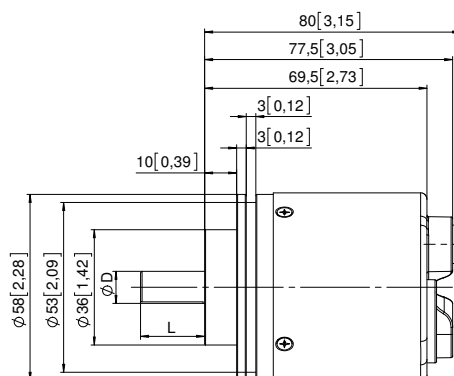
Dimensions in mm [inch]

### Clamping flange, ø 58 [2.28]

#### Flange type 1 + 3

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.31] deep

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

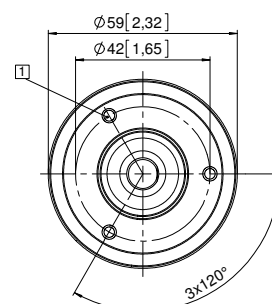
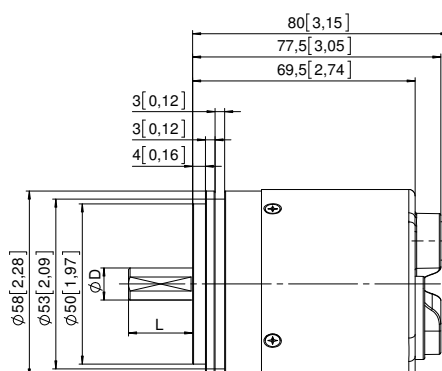


### Synchro flange, ø 58 [2.28]

#### Flange type 2 + 4

- 1 3 x M3, 6 [0.24] deep

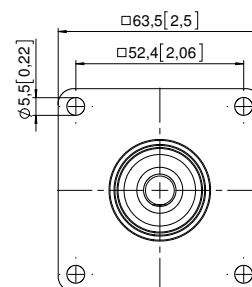
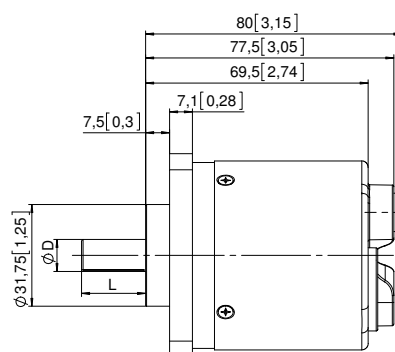
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"



### Square flange, □ 63.5 [2.5]

#### Flange type 5 + 7

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"



## Absolute encoders – singleturn

## Standard optical

## Sendix F5858 / F5878 (shaft / hollow shaft)

## EtherNet/IP

### Dimensions hollow shaft version

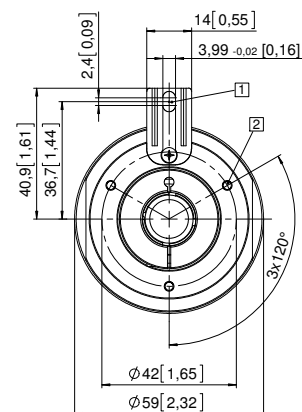
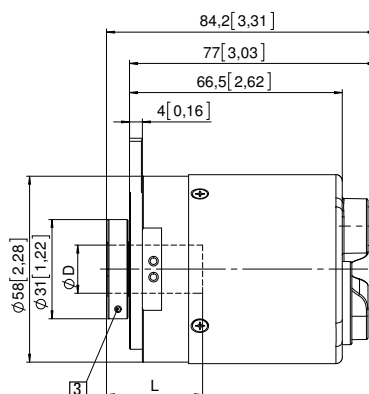
Dimensions in mm [inch]

### Flange with spring element, long Flange type 1 + 2

- 1 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing$  4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

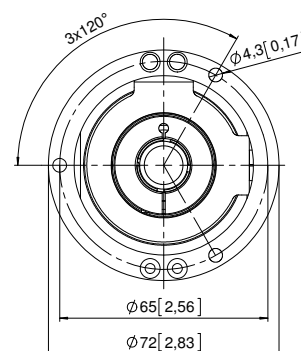
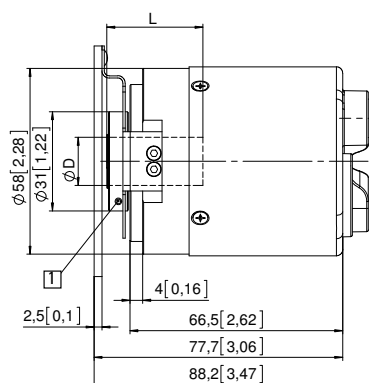


**Flange with stator coupling, ø 65 [2.56]**  
**Flange type 3 + 4**

- 1** Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

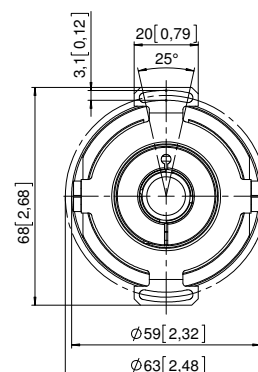
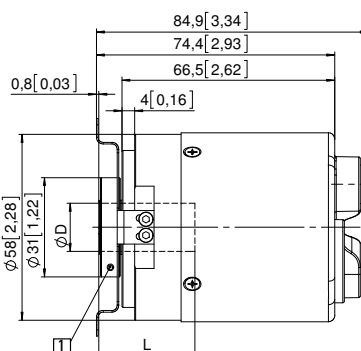


**Flange with stator coupling, ø 63 [2.48]**  
**Flange type 5 + 6**

- 1** Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



# Absolute encoders – singleturn

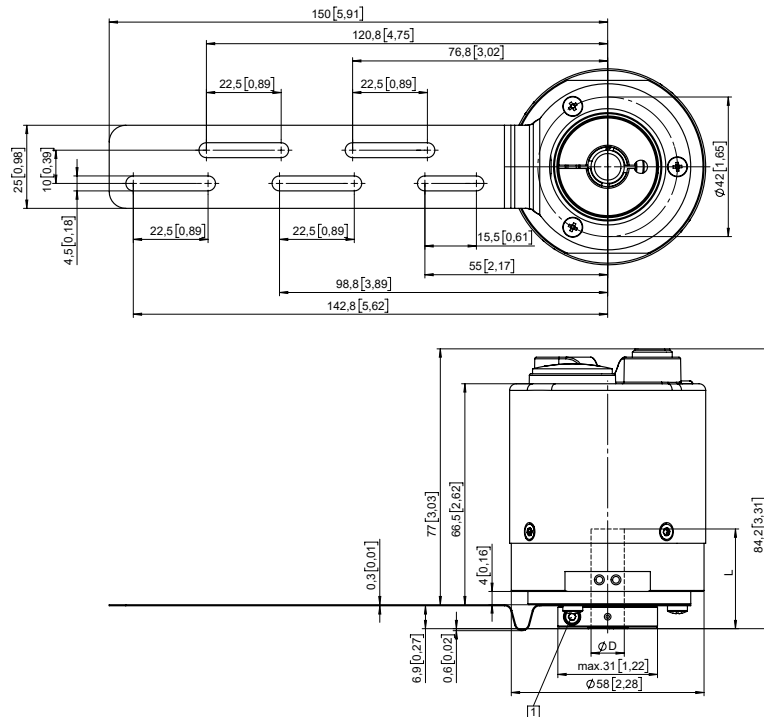
Standard optical	Sendix F5858 / F5878 (shaft / hollow shaft)	EtherNet/IP
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## Dimensions hollow shaft version

Dimensions in mm [inch]

Flange with torque stop, flexible  
Flange type 9 + J

- 1 Recommended torque for the clamping ring 0.6 Nm



D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

# Absolute encoders – singleturn

**Standard  
optical**

**Sendix F5858 / F5878 (shaft / hollow shaft)**

**PROFINET IO**



The Sendix F58 singleturn is a particularly high resolution optical encoder without gears and with 100 percent magnetic insensitivity. 19 bits total resolution, shaft up to 10 mm, blind hollow shaft up to 15 mm and certified PROFINET functionality. A minimum cycle time of 250 µs, the PROFIdrive application profile and a web server for FW updates are supported.



Safety-Lock™



High rotational speed



Temperature range  
-40°C ... +80°C



High protection level  
IP67



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Reverse polarity protection



Optical sensor

## Latest PROFINET functionality

- PROFINET IO, RT, IRT allows integration in applications with different performance requirements.
- Supports the Isochronous Mode, can thus be implemented in networks for hard real-time requirements with clock cycles up to 250 µs.
- Encoder profile V 4.2 with full support of various Profinet features.
- Ideal for highly synchronous applications, such as e. g. axis synchronization.
- Interoperability between many different control and drive manufacturers thanks to the PROFIdrive profile.

## Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ Design for resistance against vibration and installation errors.
- Wide temperature range, -40 °C ... +80 °C.

# Absolute encoders – singleturn

Standard optical	Sendix F5858 / F5878 (shaft / hollow shaft)	PROFINET IO
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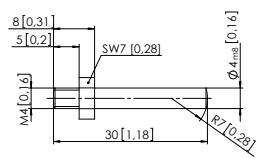
Order code	8.F5858	.XXCN.	C122
Shaft version	Type	a b c d	e
<b>a</b> Flange	1 = clamping flange, IP65 ø 58 mm [2.28"] 3 = clamping flange, IP67 ø 58 mm [2.28"] 2 = synchro flange, IP65 ø 58 mm [2.28"] 4 = synchro flange, IP67 ø 58 mm [2.28"] 5 = square flange, IP65 □ 63.5 mm [2.5"] 7 = square flange, IP67 □ 63.5 mm [2.5"]	<b>e</b> Fieldbus profile C1 = PROFINET IO	Options – Standard types (available from 1 piece) Surface protection salt spray tested with clamping flange IP67 and shaft ø 10 mm: 8.F5858.32CN.C122-C Stainless steel V2A <sup>1)</sup> Order expansion: 8.F5858.XXCN.C122-V2A Stainless steel V4A <sup>1)</sup> Order expansion: 8.F5858.XXCN.C122-V4A
<b>b</b> Shaft (ø x L), with flat	1 = 6 x 10 mm [0.24 x 0.39"] 2 = 10 x 20 mm [0.39 x 0.79"] 3 = 1/4" x 7/8" 4 = 3/8" x 7/8"	Options – on request (for other flange/shaft combinations) - Surface protection salt spray tested - Stainless steel V2A - Stainless steel V4A	
<b>c</b> Interface / Supply voltage	C = PROFINET IO / 10 ... 30 V DC		
<b>d</b> Type of connection	N = 3 x axial M12 connector, 4-pin		

Order code	8.F5878	.XXCN.	C122
Hollow shaft	Type	a b c d	e
<b>a</b> Flange	1 = with spring element long, IP65 2 = with spring element long, IP67 3 = with stator coupling, IP65 ø 65 mm [2.56"] 4 = with stator coupling, IP67 ø 65 mm [2.56"] 5 = with stator coupling, IP65 ø 63 mm [2.48"] 6 = with stator coupling, IP67 ø 63 mm [2.48"] 9 = with torque stop, flexible, IP65 J = with torque stop, flexible, IP67	<b>e</b> Fieldbus profile C1 = PROFINET IO	Options – Standard types (available from 1 piece) Stainless steel V2A <sup>2)</sup> Order expansion: 8.F5878.2XCN.C122-V2A Stainless steel V4A <sup>2)</sup> Order expansion: 8.F5878.2XCN.C122-V4A
<b>b</b> Blind hollow shaft (insertion depth max. 30 mm [1.18"])	A = ø 10 mm [0.39"] B = ø 12 mm [0.47"] C = ø 14 mm [0.55"] D = ø 15 mm [0.59"] E = ø 3/8" F = ø 1/2"	Options – on request (for other flange/hollow shaft combinations) - Surface protection salt spray tested - Stainless steel V2A - Stainless steel V4A	
<b>c</b> Interface / Supply voltage	C = PROFINET IO / 10 ... 30 V DC		
<b>d</b> Type of connection	N = 3 x axial M12 connector, 4-pin		

1) Only in conjunction with flange **a** = 3 or 4 and shaft **b** = 1 or 2.

2) Only in conjunction with flange **a** = 2 and hollow shaft **b** = B or D.

# Absolute encoders – singleturn

Standard optical		Sendix F5858 / F5878 (shaft / hollow shaft)	PROFINET IO
Mounting accessory for shaft encoders			Order no.
Coupling	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]		8.0000.1102.0606
	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]		8.0000.1102.1010
Mounting accessory for hollow shaft encoders Dimensions in mm [inch]			Order no.
Torque pin, ø 4 mm for flange with spring element (flange type 1)	with fixing thread		8.0010.4700.0000
			
Cables and connectors			Order no.
Preassembled cables	M12 male connector with external thread, 4-pin, D coded, straight single-ended 2 m [6.56'] PUR cable	port 1 + port 2	05.00.6031.4411.002M
	M12 male connector with external thread, 4-pin, D coded, right-angle single-ended 2 m [6.56'] PUR cable	port 1 + port 2	05.00.6031.4511.002M
	M12 female connector with coupling nut, 4-pin, A coded, straight single-ended 2 m [6.56'] PUR cable	power supply	05.00.6061.6211.002M
	M12 female connector with coupling nut, 4-pin, A coded, right-angle single-ended 2 m [6.56'] PUR cable	power supply	05.00.6061.6311.002M
Connectors	M12 male connector with external thread, 4-pin, D coded, straight (metal)	port 1 + port 2	05.WASCSY4S
	M12 male connector with external thread, 4-pin, D coded, right-angle (metal)	port 1 + port 2	8.0000.5128.0000
	M12 female connector with coupling nut, 4-pin, A coded, straight (plastic)	power supply	05.B8141-0
	M12 female connector with coupling nut, 4-pin, A coded, right-angle (plastic)	power supply	05.B8241-0

Further Kübler accessories can be found at: [/accessories](#)

Further Kübler cables and connectors can be found at: [/connection-technology](#)

# Absolute encoders – singleturn

Standard optical	Sendix F5858 / F5878 (shaft / hollow shaft)	PROFINET IO
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## Technical data

Mechanical characteristics				
Max. speed		9000 min <sup>-1</sup> (short-term – 10 min)		
		6000 min <sup>-1</sup> (continuous)		
Starting torque at 20 °C [68 °F]		< 0.01 Nm		
Moment of inertia	shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup>		
	blind hollow shaft version	4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>		
Load capacity of shaft	radial	80 N		
	axial	40 N		
Weight		approx. 0.45 kg [15.87 oz]		
Protection acc. to EN 60529		IP65, IP67		
Working temperature range		-40 °C ... +80 °C [-40 °F ... +176 °F]		
Material	Standard	V2A	V4A	
		DIN 1.4305	DIN 1.4404	
		AISI 303	AISI 316L	
	shaft/hollow shaft	V2A	V4A	
	flange	aluminum	V2A	V4A
	housing	aluminum	V2A	V4A
Shock resistance acc. EN 60068-2-27		2500 m/s <sup>2</sup> , 6 ms		
Vibration resistance acc. EN 60068-2-6		100 m/s <sup>2</sup> , 55 ... 2000 Hz		

Electrical characteristics	
Power supply	10 ... 30 V DC
Current consumption (at 24 V DC)	max. 45 mA
Power consumption	max. 1.5 W
Reverse polarity protection of the power supply (V+)	yes

Approvals		
UL compliant in accordance with	File no. E224618	
CE compliant in accordance with	EMC Directive	2014/30/EU
	RoHS Directive	2011/65/EU

## Interface characteristics PROFINET IO

General information	
Protocol	PROFINET IO
Classifications	RT Class 3 (IRT) Conformance Class C Application Class 6 Encoder Class 4 Netload Class III

Adjustable parameters	
<ul style="list-style-type: none"> <li>• Preset</li> <li>• Counting direction</li> <li>• Resolution per revolution - MUR</li> <li>• Unit speed</li> <li>• IP address</li> <li>• Total resolution - TMR</li> <li>• Position format</li> <li>• Speed reference value</li> </ul>	<ul style="list-style-type: none"> <li>• Scaling</li> <li>• Device name</li> <li>• F-Destination Address</li> <li>• I&amp;M 0...3 Parameter</li> <li>• Alarm behavior</li> <li>• Parameter write protection</li> <li>• Parameter initialization</li> </ul>

Resolution	
Resolution Singleturn (MUR)	
scalable	1 ... 524 288 (19 bit)
default	8 192 (13 bit)

PROFINET characteristics	
<ul style="list-style-type: none"> <li>• I&amp;M 0 ... 3</li> <li>• standard telegrams (81, 82, 83, 84, 86, 88)</li> <li>• IRT up to 250 µs</li> <li>• Isochronous Mode</li> </ul>	<ul style="list-style-type: none"> <li>• MRP</li> <li>• LLDP</li> <li>• PDEV</li> <li>• SNMP</li> <li>• FSU</li> </ul>

Process data	
<ul style="list-style-type: none"> <li>• Position</li> <li>• Speed</li> </ul>	<ul style="list-style-type: none"> <li>• Failure</li> <li>• Warnings</li> </ul>




## Absolute encoders – singleturn

**Standard  
optical**

**Sendix F5858 / F5878 (shaft / hollow shaft)**

**PROFINET IO**

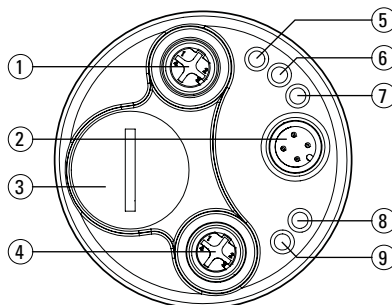
### Terminal assignment bus

Interface	Type of connection	Function	M12 connector, 4-pin					
C	N (3 x M12 connector)	Bus Port 1	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	 D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	
		Power supply	Signal:	Voltage +	–	Voltage –	–	
			Abbreviation:	+ V	–	0 V	–	
			Pin:	1	2	3	4	
		Bus Port 2	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	 D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	

### Rear side connections and display elements

①	Ethernet Port – Link 2	
②	Supply voltage	
③	Cover screw	
④	Ethernet Port – Link 1	
⑤	Link 2	flashes yellow when connected
⑥	BF – Bus Failure	displays network errors *)
⑦	SF – System Failure	displays system errors *)
⑧	ENC	shows status of encoder *)
⑨	Link 1	flashes yellow when connected

\*) see manual





# Absolute encoders – singleturn

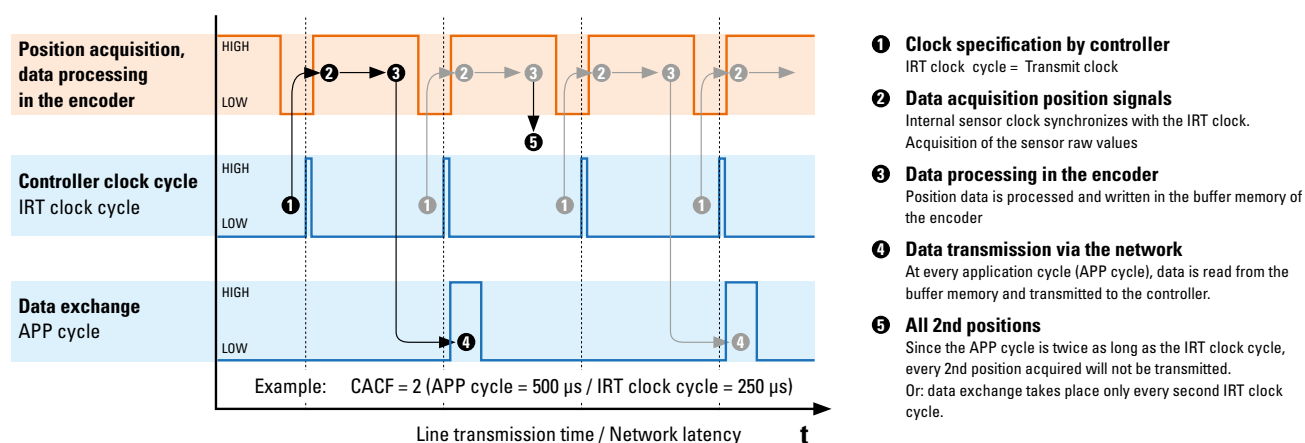
<b>Standard optical</b>	<b>Sendix F5858 / F5878 (shaft / hollow shaft)</b>	<b>PROFINET IO</b>
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## Technology in detail

### Clock synchronicity – Isochronous Real Time (IRT) in position sensor technology

In general, for time-critical applications, focus is set on very short sensor cycle times. However, in order to achieve high control performance, simply accelerating data acquisition and processing by shortest cycle times is not sufficient. All sensors and actuators are to operate according to the same clock.

This is achieved thanks to a clock used for the whole network, defined by the controller. This transmit clock cycle (IRT clock) is however not necessarily the clock cycle used for process data exchange. Another cycle (application cycle) is used for this purpose, which can also be defined by the customer controller. The illustration below represents the connection between the different clock cycles.



When receiving the IRT clock signal, the sensor starts reading its current measured point. This raw value is processed internally (e.g. scaling, speed calculation, etc.) and stored in a buffer memory.

The buffer memory is read at every application cycle. If it contains a value, this value is transmitted to the controller via the network.

If the application cycle is a multiple of the IRT clock cycle, it may happen that the buffered process data is not sent directly, but is overwritten, because, even though this data is acquired with every IRT clock cycle, it is sent only with every application cycle.

The ratio between application cycle and IRT clock cycle represents the CACF (Controller Application Cycle Factor).

In this example, the  $CACF = 2$ . This indicates that only every 2nd acquired position will be transmitted to the controller.

The described methodology guarantees a determinism: since the controller defines a clock cycle for the whole network, this allows ensuring that all measured values transmitted by the sensors to the controller are never older than the selected IRT cycle! Therefore, all downstream actuators can always be regulated on the basis of the latest available measured values.

# Absolute encoders – singleturn

## Standard optical

## Sendix F5858 / F5878 (shaft / hollow shaft)

## PROFINET IO

### Dimensions shaft version

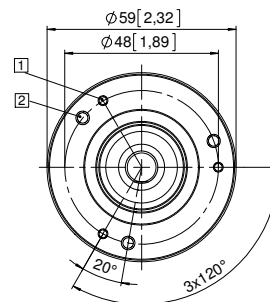
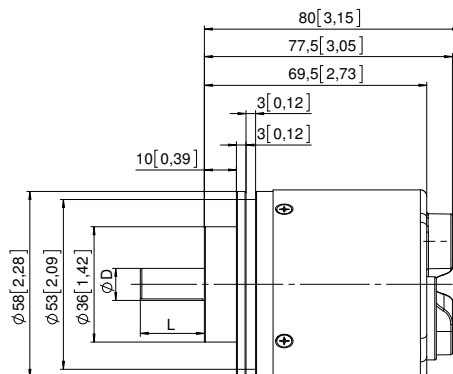
Dimensions in mm [inch]

#### Clamping flange, ø 58 [2.28]

##### Flange type 1 + 3

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.31] deep

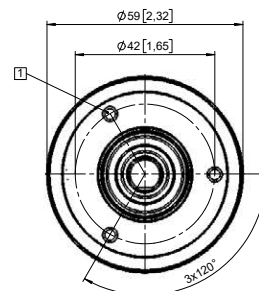
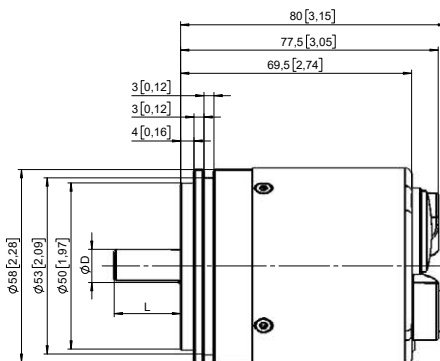


D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

#### Synchro flange, ø 58 [2.28]

##### Flange type 2 + 4

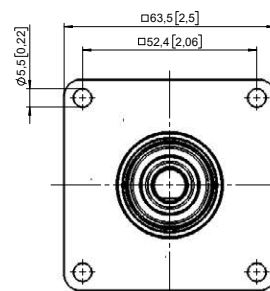
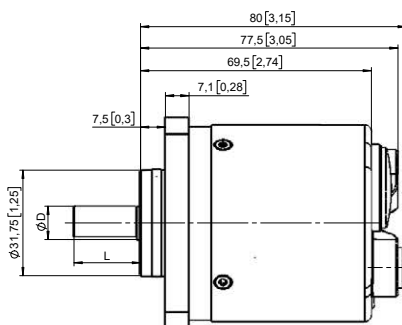
1 3 x M3, 6 [0.24] deep



D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

#### Square flange, □ 63.5 [2.5]

##### Flange type 5 + 7



D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

# Absolute encoders – singleturn

Standard optical	Sendix F5858 / F5878 (shaft / hollow shaft)	PROFINET IO
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## Dimensions hollow shaft version

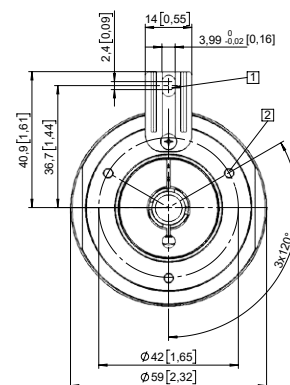
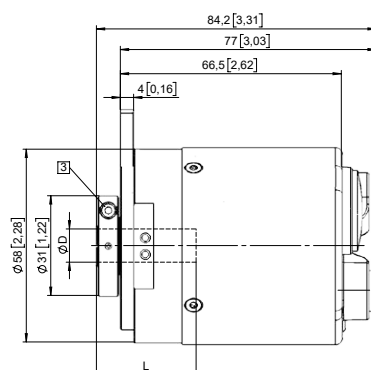
Dimensions in mm [inch]

### Flange with spring element, long Flange type 1 + 2

- 1 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing 4$  [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

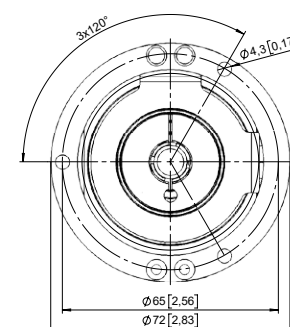
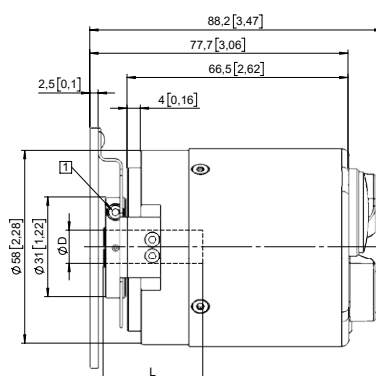


### Flange with stator coupling, $\varnothing 65$ [2.56] Flange type 3 + 4

- 1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

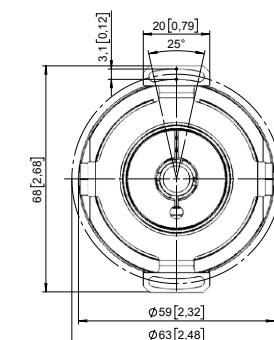
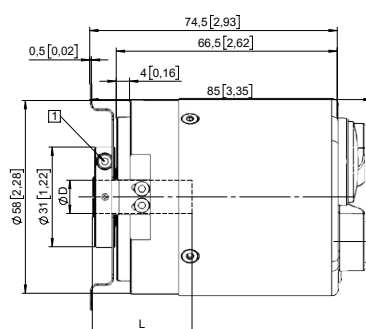


### Flange with stator coupling, $\varnothing 63$ [2.48] Flange type 5 + 6

- 1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

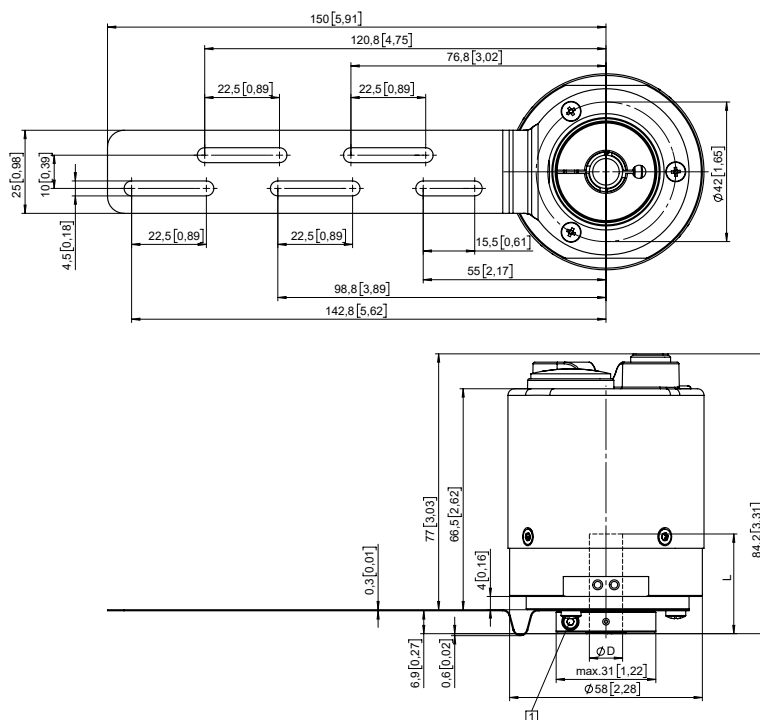
L = insertion depth max. blind hollow shaft



## PROFINET IO

Dimensions in mm [inch]

**1** Recommended torque for the clamping ring 0.6 Nm



D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

L = insertion depth max. blind hollow shaft

# Absolute encoders – singleturn

**Standard  
magnetic**

**Sendix M5851A (shaft)**

**Analog**



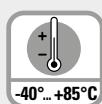
The Sendix M5851A is a magnetic singleturn encoder in compact design. High robustness and high resolution make this encoder the ideal device for use in demanding applications.



Safety-Lockplus™



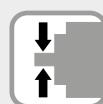
High rotational speed



Temperature range



High protection level



High shaft load capacity



Shock / vibration resistant



Reverse polarity protection

## Highest robustness

- Sturdy bearing construction in Safety-Lockplus™ design for particularly high resistance.
- Extra large bearings.
- Mechanically protected shaft seal.
- Wide temperature range -40 °C ... +85 °C.

## Application oriented

- Current output 4 ... 20 mA.
- Voltage output 0 ... 10 V or 0 ... 5 V.
- Different measuring ranges.
- SET input for easy start-up.

**Order code  
Shaft version**

**8.M5851A**  
Type

.XXXX.XXX2  
a b c d e f g

### a Version

- 3 = clamping flange, IP65, ø 58 mm [2.28"]
- 4 = synchro flange, IP65, ø 58 mm [2.28"]

### b Shaft (ø x L), with flat

- 1 = ø 6 x 12.5 mm [0.24 x 0.49"]
- 5 = ø 10 x 20 mm [0.39 x 0.79"]

### c Output circuit<sup>1)</sup>

- 3 = current output
- 4 = voltage output

### d Type of connection

- 2 = radial cable, 1 m [3.28'] PVC
- B = radial cable, special length PVC \*)
- 4 = radial M12 connector, 5-pin

Type of connection with changed terminal assignment  
(see page 5)

- D = radial M12 connector, 5-pin

\*) Available special lengths (connection types B):  
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']  
order code expansion .XXXX = length in dm  
ex.: 8.M5851A.313B.3112.0030 (for cable length 3 m)

### e Interface / resolution / supply voltage

- 3 = 4 ... 20 mA / 12 bit / 10 ... 30 V DC
- 4 = 0 ... 10 V / 12 bit / 15 ... 30 V DC
- 5 = 0 ... 5 V / 11 bit / 10 ... 30 V DC

### f Measuring range

- 1 = 1 x 360°
- 2 = 1 x 180°
- 3 = 1 x 90°
- 4 = 1 x 45°

### g Counting direction

- 1 = cw
- 2 = ccw

Optional on request  
- Ex 2/22

1) Output circuit "3" only in conjunction with interface "3",  
output circuit "4" only in conjunction with interface "4" or "5".

# Absolute encoders – singleturn

Standard magnetic	Sendix M5851A (shaft)	Analog
<b>Mounting accessory for shaft encoders</b>		Order no.
<b>Coupling</b>	Bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	<b>8.0000.1102.1010</b>
<b>Cables and connectors</b>		Order no.
<b>Preassembled cables</b>	M12 female connector with coupling nut, 5-pin, A coded, straight single ended 2 m [6.56'] PVC cable	<b>05.00.6081.2211.002M</b>
<b>Connector</b>	M12 female connector with coupling nut, 5-pin, A coded, straight (metal)	<b>8.0000.5116.0000</b>

Further Kübler accessories can be found at: [/accessories](#)

Further Kübler cables and connectors can be found at: [/connection-technology](#)

## Technical data

Electrical characteristics current interface 4 ... 20 mA		
<b>Supply voltage</b>	10 ... 30 V DC	
<b>Current consumption (no load)</b>	max. 30 mA	
<b>Reverse polarity protection of the supply voltage</b>	yes	
<b>Short-circuit proof outputs</b>	yes <sup>1)</sup>	
<b>Measuring range</b>	45°, 90°, 180° or 360°	
<b>DA converter resolution</b>	12 bit	
<b>Angular measurement deviation <sup>2)</sup></b>	±0,5°	
<b>Temperature coefficient</b>	< 100 ppm/K	
<b>Repeat accuracy, at 25°C [77°F]</b>	±0.2°	
<b>Output load</b>	at 10 V DC at 24 V DC at 30 V DC	max. 200 Ohm max. 900 Ohm max. 1200 Ohm
<b>Setting time</b>	< 1 ms, R <sub>Burden</sub> = 900 Ohm, 25°C [77°F]	
<b>LEDs (green/red)</b>	<ul style="list-style-type: none"> <li>- system status</li> <li>- current loop interruption – input load too high</li> <li>- reference point display (only with factory settings) at cw: betw. 0° and 1° at ccw: betw. 0° and -1°</li> </ul>	
<b>SET input</b>	level = +V for 1 s minimum	
<b>PowerON Time</b>	< 1 s	
<b>Update rate</b>	1 ms	

Electrical characteristics voltage interface 0 ... 10 V / 0 ... 5 V		
<b>Supply voltage</b>	output 0 ... 5 V output 0 ... 10 V	10 ... 30 V DC 15 ... 30 V DC
<b>Current consumption (no load)</b>	max. 30 mA	
<b>Reverse polarity protection of the supply voltage</b>	yes	
<b>Short-circuit proof outputs</b>	yes <sup>1)</sup>	
<b>Measuring range</b>	45°, 90°, 180° or 360°	
<b>DA converter resolution</b>	0 ... 10 V 0 ... 5 V	12 bit 11 bit
<b>Angular measurement deviation <sup>2)</sup></b>	±0,5°	
<b>Temperature coefficient</b>	< 100 ppm/K	
<b>Repeat accuracy, at 25°C [77°F]</b>	±0.2°	
<b>Current output</b>	max. 10 mA	
<b>Setting time</b>	< 1 ms, R <sub>Load</sub> = 1000 Ohm, 25°C [77°F]	
<b>LEDs (green/red)</b>	<ul style="list-style-type: none"> <li>- system status</li> <li>- reference point display (only with factory settings) at cw: betw. 0° and 1° at ccw: betw. 0° and -1°</li> </ul>	
<b>SET input</b>	level = +V for 1 s minimum	
<b>PowerON Time</b>	< 1 s	
<b>Update rate</b>	1 ms	

1) When the supply voltage is correctly applied.  
But not output to +V. Supply voltage and sensor output signal are not galvanically isolated.

2) Over the whole temperature range.

# Absolute encoders – singleturn

Standard magnetic	Sendix M5851A (shaft)	Analog
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Mechanical characteristics	
<b>Maximum speed</b>	4000 min <sup>-1</sup> 2000 min <sup>-1</sup> (continuous)
<b>Starting torque at 20 °C [68 °F]</b>	< 0.01 Nm
<b>Shaft load capacity</b>	radial 80 N axial 40 N
<b>Weight</b>	approx. 280 g [9.88 oz]
<b>Protection acc. to EN 60529/DIN 40050-9</b>	IP65
<b>Working temperature range</b>	-40 °C ... +85 °C [-40 °F ... +185 °F]
<b>Materials</b>	shaft V2A flange aluminum housing zinc die-cast cable PVC
<b>Shock resistance acc. to EN 60068-2-27</b>	5000 m/s <sup>2</sup> , 4 ms
<b>Vibration resistance acc. to EN 60068-2-6</b>	300 m/s <sup>2</sup> , 10 ... 2000 Hz

Approvals	
<b>E1 compliant</b> in accordance with	ECE guideline
<b>UL compliant</b> in accordance with	File no. E224618
<b>CE compliant</b> in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU (for Ex 2/22 variants)

SET input	
<b>Input</b>	active HIGH
<b>Input type</b>	comparator
<b>Signal level</b> (+V = supply voltage)	HIGH min. 60 % of +V, max: +V LOW max. 30 % of +V
<b>Input current</b>	< 0.5 mA
<b>Min. pulse duration (SET)</b>	10 ms
<b>Input delay</b>	1 ms
<b>New position data readable after</b>	1 ms
<b>Internal processing time</b>	200 ms

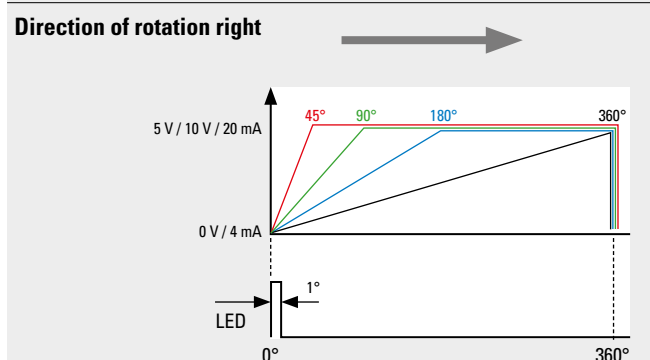
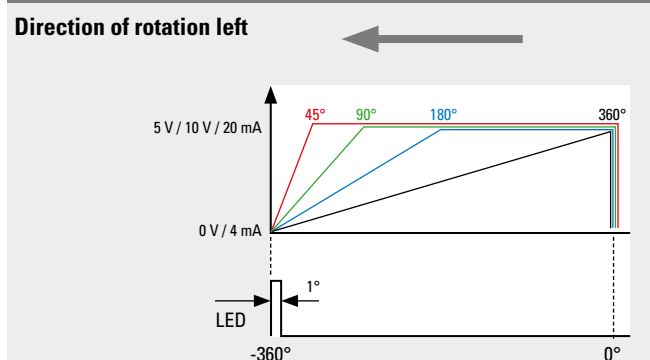
The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.

The SET function should be carried out whilst the encoder is at rest.

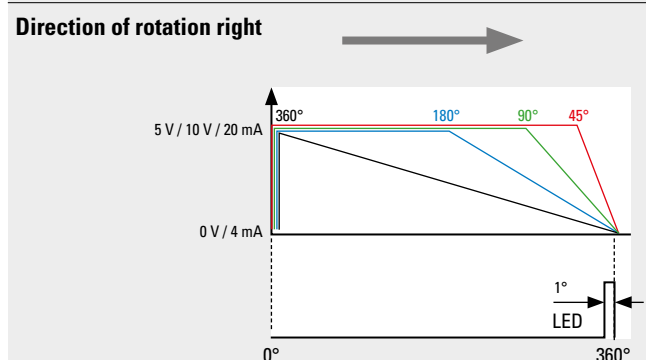
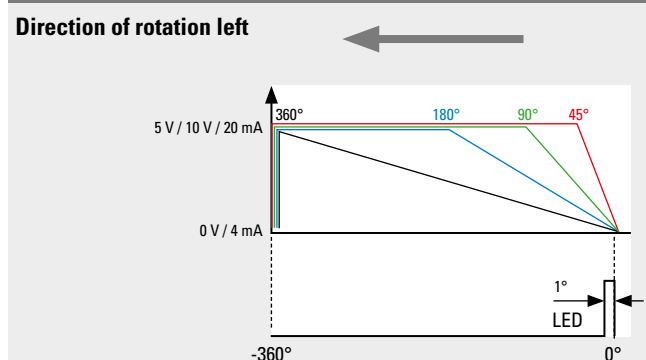
The number of preset value writing cycles is limited to 10,000.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

## Example (output signal evolution) Variante counting direction cw



## Example (output signal evolution) Variante counting direction ccw



# Absolute encoders – singleturn

<b>Standard magnetic</b>	<b>Sendix M5851A (shaft)</b>	<b>Analog</b>
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## Terminal assignment

Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)					
3 (current)	2, B	Signal:	0 V	+V	+I	SET	–
		Core color:	WH	BN	GN	GY	PK

Interface	Type of connection	M12 connector, 5 pin					
3 (current)	4	Signal:	0 V	+V	+I	SET	–
		Pin:	3	2	1	5	4

Interface	Type of connection	M12 connector, 5 pin					
3 (current)	D	Signal:	0 V	+V	+I	SET	–
		Pin:	3	1	2	4	5

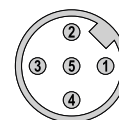
Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)					
4, 5 (voltage)	2, B	Signal:	0 V	+V	+U	SET	–
		Core color:	WH	BN	GN	GY	PK

Interface	Type of connection	M12 connector, 5 pin					
4, 5 (voltage)	4	Signal:	0 V	+V	+U	SET	–
		Pin:	3	2	1	5	4

Interface	Type of connection	M12 connector, 5 pin					
4, 5 (voltage)	D	Signal:	0 V	+V	+U	SET	–
		Pin:	3	1	2	4	5

+V: Supply voltage encoder +V DC  
 0 V: Supply voltage encoder ground GND (0 V)  
 +U: Voltage  
 +I: Current  
 SET: SET input

Top view of mating side, male contact base



M12 connector, 5-pin



# Absolute encoders – singleturn

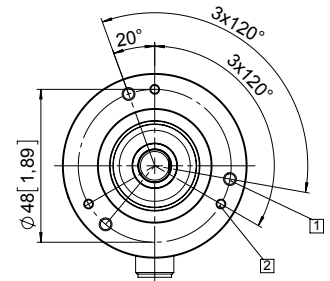
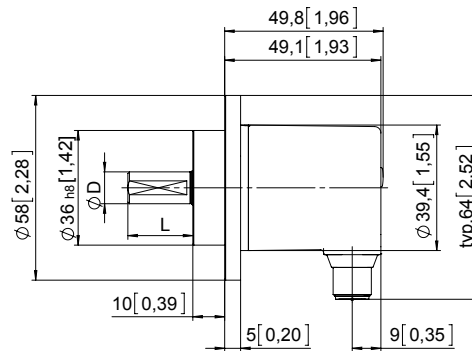
Standard magnetic	Sendix M5851A (shaft)	Analog
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## Dimensions

Dimensions in mm [inch]

### Clamping flange, ø 58 [2.28] Flange type 3

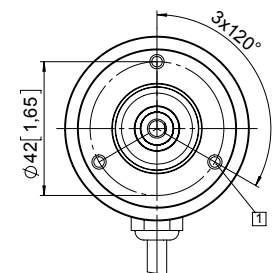
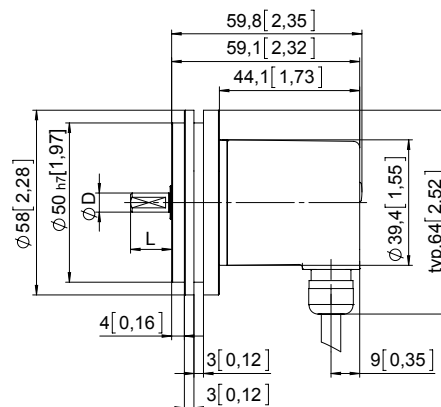
- 1 3 x M4
- 2 3 x M3



D	Fit	L
6 [0.24]	h7	12.5 [0.49]
10 [0.39]	h7	20 [0.79]

### Synchro flange, ø 58 [2.28] Flange type 4

- 1 3 x M4, 10 [0.39] deep



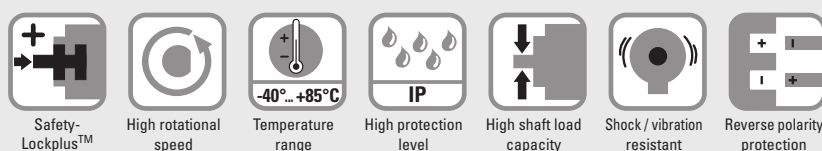
D	Fit	L
6 [0.24]	h7	12.5 [0.49]
10 [0.39]	h7	20 [0.79]

# Absolute encoders – singleturn

<b>Standard magnetic</b>	<b>Sendix M5853A (shaft)</b>	<b>SSI</b>
--------------------------	------------------------------	------------



The Sendix M5853A is a magnetic singleturn encoder in compact design. High robustness and high resolution make this encoder the ideal device for use in demanding applications.



## Highest robustness

- Sturdy bearing construction in Safety-Lockplus™ design for particularly high resistance.
- Extra large bearings.
- Mechanically protected shaft seal.
- Wide temperature range -40 °C ... +85 °C.

## Application oriented

- Angular measurement deviation  $\pm 0,5^\circ$ .
- Repeat accuracy  $\pm 0.2^\circ$ .
- Short control cycles, clock frequency with SSI up to 2 MHz.
- Max. resolution 14 bit.

Order code	8.M5853A	.XX2X.XX12	
Shaft version	Type	a b c d e f	
<b>a</b> Version		<b>d</b> Type of connection	<b>f</b> Resolution
3 = clamping flange, IP65, $\varnothing$ 58 mm [2.28"]		2 = radial cable, 1 m [3.28'] PUR	A = 10 bit
4 = synchro flange, IP65, $\varnothing$ 58 mm [2.28"]		B = radial cable, special length PUR *)	2 = 12 bit
		4 = radial M12 connector, 8-pin	3 = 13 bit
<b>b</b> Shaft ( $\varnothing \times L$ ), with flat		*) Available special lengths (connection types B):	4 = 14 bit
1 = $\varnothing$ 6 x 12.5 mm [0.24 x 0.49"]		2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']	
5 = $\varnothing$ 10 x 20 mm [0.39 x 0.79"]		order code expansion .XXXX = length in dm	<i>Optional on request</i>
<b>c</b> Interface / supply voltage		ex.: 8.M5853A.352B.G312.0030 (for cable length 3 m)	- Ex 2/22 (only for connection type 4)
2 = SSI / 10 ... 30 V DC		<b>e</b> Code	
		B = SSI, binary	
		G = SSI, gray	

Mounting accessory for shaft encoders		Order no.
<b>Coupling</b>	Bellows coupling $\varnothing$ 19 mm [0.75"] for shaft 10 mm [0.39"]	<b>8.0000.1102.1010</b>
Cables and connectors		Order no.
<b>Preassembled cables</b>	M12 female connector with coupling nut, 8-pin, A coded, straight single ended 2 m [6.56'] PUR cable	<b>05.00.6051.8211.002M</b>
<b>Connector</b>	M12 female connector with coupling nut, 8-pin, A coded, straight (metal)	<b>05.CMB 8181-0</b>

Further Kübler accessories can be found at: /accessories  
Further Kübler cables and connectors can be found at: /connection-technology

# Absolute encoders – singleturn

<b>Standard magnetic</b>	<b>Sendix M5853A (shaft)</b>	<b>SSI</b>
--------------------------	------------------------------	------------

## Technical data

Mechanical characteristics	
<b>Maximum speed</b>	4000 min <sup>-1</sup> 2000 min <sup>-1</sup> (continuous)
<b>Starting torque at 20 °C [68 °F]</b>	< 0.01 Nm
<b>Shaft load capacity</b>	radial 80 N axial 40 N
<b>Weight</b>	approx. 280 g [9.88 oz]
<b>Protection acc. to EN 60529/DIN 40050-9</b>	IP65
<b>Working temperature range</b>	-40 °C ... +85 °C [-40 °F ... +185 °F]
<b>Materials</b>	shaft V2A flange aluminum housing zinc die-cast cable PUR
<b>Shock resistance acc. to EN 60068-2-27</b>	5000 m/s <sup>2</sup> , 4 ms
<b>Vibration resistance acc. to EN 60068-2-6</b>	300 m/s <sup>2</sup> , 10 ... 2000 Hz

Electrical characteristics	
<b>Supply voltage</b>	10 ... 30 V DC
<b>Current consumption (no load)</b>	max. 30 mA
<b>Reverse polarity protection of the supply voltage</b>	yes
<b>Short-circuit proof outputs</b>	yes <sup>1)</sup>

SSI interface	
<b>Output driver</b>	RS485 transceiver type
<b>Permissible load / channel</b>	max. +/- 30 mA
<b>Signal level</b>	HIGH typ 3.8 V LOW with I <sub>Load</sub> = 20 mA typ 1.3 V
<b>Resolution</b>	10 ... 14 bit
<b>Angular measurement deviation <sup>2)</sup></b>	±0.5°
<b>Repeat accuracy</b>	±0.2°
<b>Code</b>	binary or gray
<b>SSI clock rate</b>	50 kHz ... 2 MHz
<b>Data refresh rate</b>	2 ms
<b>Monoflop time</b>	≤ 15 µs
<b>Note:</b> If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.	

SET input	
<b>Input</b>	active HIGH
<b>Input type</b>	comparator
<b>Signal level</b>	HIGH min. 60 % of +V, max: +V (+V = supply voltage) LOW max. 30 % of +V
<b>Input current</b>	< 0.5 mA
<b>Min. pulse duration (SET)</b>	10 ms
<b>Input delay</b>	1 ms
<b>New position data readable after</b>	1 ms
<b>Internal processing time</b>	200 ms
The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.	
The SET function should be carried out whilst the encoder is at rest.	
The number of preset value writing cycles is limited to 10,000.	
If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.	

DIR input	
Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.	
If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.	
<b>Response time (DIR input)</b>	1 ms

Power-ON	
After Power-ON the device requires a time of approx. 150 ms before valid data can be read.	
Hot plugging of the encoder should be avoided.	

Approvals	
<b>UL compliant</b> in accordance with	File no. E224618
<b>CE compliant</b> in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU (for Ex 2/22 variants)

1) Short circuit proof to 0 V or to output when supply voltage correctly applied.

2) Over the whole temperature range.

# Absolute encoders – singleturn

<b>Standard magnetic</b>	<b>Sendix M5853A (shaft)</b>	<b>SSI</b>
--------------------------	------------------------------	------------

## Terminal assignment

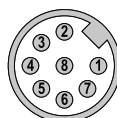
Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)									
2	2, B	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	shield

Interface	Type of connection	Features	M12 connector, 8-pin									
2	4	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥
			Pin:	1	2	3	4	5	6	7	8	PH

+V: Supply voltage encoder +V DC  
 0 V: Supply voltage encoder ground GND (0 V)  
 C+, C-: Clock signal  
 D+, D-: Data signal  
 SET: Set input  
 DIR: Direction input  
 PH ⊥: Plug connector housing (shield)

## Top view of mating side, male contact base



M12 connector, 8-pin

## Dimensions

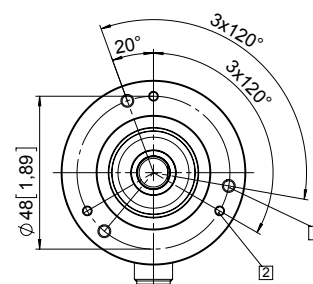
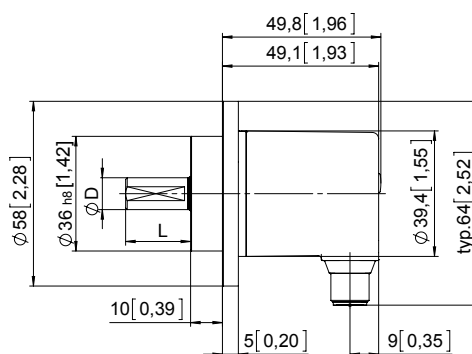
Dimensions in mm [inch]

### Clamping flange, ø 58 [2.28]

#### Flange type 3

- 1 3 x M4
- 2 3 x M3

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
10 [0.39]	h7	20 [0.79]

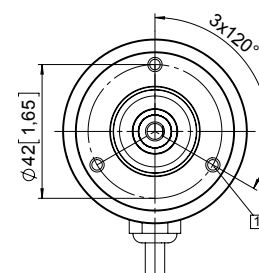
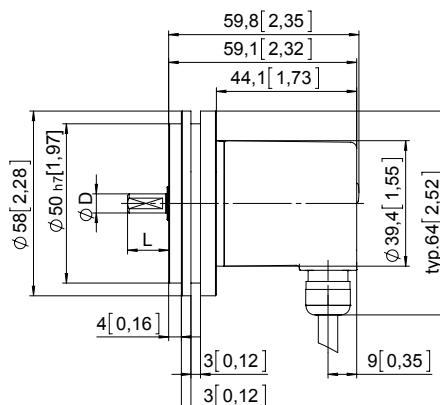


### Synchro flange, ø 58 [2.28]

#### Flange type 4

- 1 3 x M4, 10 [0.39] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
10 [0.39]	h7	20 [0.79]



# Absolute encoders – singleturn

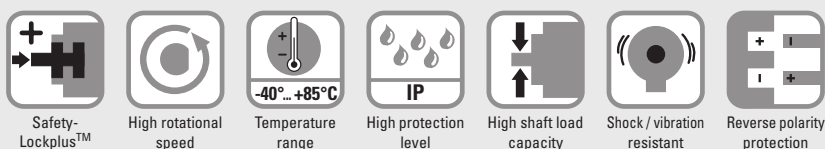
Standard  
magnetic

Sendix M5858A (shaft)

CANopen



The Sendix M5858A is a magnetic singleturn encoder in compact design. High robustness and high resolution make this encoder the ideal device for use in demanding applications.



## Highest robustness

- Sturdy bearing construction in Safety-Lockplus™ design for particularly high resistance.
- Extra large bearings.
- Mechanically protected shaft seal.
- Wide temperature range -40 °C ... +85 °C.

## Up-to-the-minute fieldbus performance

- LSS services for configuration of the node address and baud rate.
- Variable PDO mapping in the memory.
- Configuration management (bootloader).

Order code  
Shaft version

8.M5858A.XX2X.2122  
Type a b c d e

- a** Version  
3 = clamping flange, IP65, ø 58 mm [2.28"]  
4 = synchro flange, IP65, ø 58 mm [2.28"]

- b** Shaft (ø x L), with flat  
1 = ø 6 x 12.5 mm [0.24 x 0.49"]  
5 = ø 10 x 20 mm [0.39 x 0.79"]

- c** Interface / supply voltage  
2 = CANopen DS301 V4.2 / 10 ... 30 V DC

- d** Type of connection  
2 = radial cable, 1 m [3.28'] PVC  
B = radial cable, special length PVC \*)  
4 = radial M12 connector, 5-pin

\*) Available special lengths (connection types B):  
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']  
order code expansion .XXXX = length in dm  
ex.: 8.M5858A.312B.2122.0030 (for cable length 3 m)

- e** Fieldbus profile  
21 = CANopen

Optional on request  
- Ex 2/22 (only for connection type 4)

# Absolute encoders – singleturn

Standard magnetic		Sendix M5858A (shaft)	CANopen
Mounting accessory for shaft encoders			Order no.
Coupling	Bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]		8.0000.1102.1010
Cables and connectors			Order no.
Preassembled cables	M12 female connector with coupling nut, 5-pin, A coded, straight open ended 5 m [16.40'] PVC cable	Bus in	05.00.6091.A211.005M
	M12 female connector with coupling nut, 5-pin, A coded, straight Deutsch connector DT04, male contacts, 6-pin, straight 1 m [3.28'] PVC cable	Bus in	05.00.6091.22C7.001M
Connectors	M12 female connector with coupling nut, 5-pin, A coded, straight (metal)	Bus in	8.0000.5116.0000

Further Kübler accessories can be found at: /accessories  
Further Kübler cables and connectors can be found at: /connection-technology

Technical data	
Mechanical characteristics	
Maximum speed	4000 min <sup>-1</sup> 2000 min <sup>-1</sup> (continuous)
Starting torque at 20 °C [68 °F]	< 0.01 Nm
Shaft load capacity	radial 80 N axial 40 N
Weight	approx. 280 g [9.88 oz]
Protection acc. to EN 60529/DIN 40050-9	IP65
Working temperature range	-40 °C ... +85 °C [-40 °F ... +185 °F]
Materials	shaft V2A flange aluminum housing zinc die-cast cable PVC
Shock resistance acc. to EN 60068-2-27	5000 m/s <sup>2</sup> , 4 ms
Vibration resistance acc. to EN 60068-2-6	300 m/s <sup>2</sup> , 10 ... 2000 Hz
Electrical characteristics	
Supply voltage	10 ... 30 V DC
Current consumption (no load)	max. 30 mA
Reverse polarity protection of the supply voltage	yes
Short-circuit proof outputs	yes <sup>1)</sup>
Interface characteristics CANopen	
Resolution	1 ... 16.384 (14 bit), scalable default: 16.384 (14 bit)
Angular measurement deviation <sup>2)</sup>	±0,5°
Repeat accuracy	±0.2°
Interface	CAN high-speed acc. to ISO 11898, Basic- and Full-CAN, CAN specification 2.0 B
Protocol	CANopen profile DS406 V4.0 with manufacturer-specific add-ons, LSS-Service, bootloader
Power-ON time	< 1200 ms
SDO timeout	< 1000 ms
Baud rate	10 ... 1000 kbit/s software configurable
Node address	1 ... 127 software configurable
Termination	software configurable
LSS protocol	CIA LSS protocol DS305, global command support for node address and baud rate, selective commands via attributes of the identity object
Bootloader	configuration management CIA DS 302-3
Approvals	
E1 compliant in accordance with	ECE guideline
UL compliant in accordance with	File no. E224618
CE compliant in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU (for Ex 2/22 variants)

1) Short circuit proof to 0 V or to output when supply voltage correctly applied.  
2) Over the whole temperature range.

# Absolute encoders – singleturn

Standard magnetic	Sendix M5858A (shaft)	CANopen
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## General information about CANopen

The CANopen encoders support the latest CANopen communication profile according to DS301 V4.02. In addition, device-specific profiles like the encoder profile DS406 V3.2, DS305 (LSS) and DS302 (Bootloader) are available.

The following operating modes may be selected: Polled Mode, Cyclic Mode, Sync Mode. Moreover, scale factors, preset values, limit switch values and many other additional parameters can be programmed via the CANbus. When switching the device on, all parameters, which have been saved on a flash memory to protect them against power failure, are loaded again.

The following output values may be combined in a freely variable way as PDO (PDO mapping): **position, speed, acceleration** as well as the **status of the working area**.

The encoders are available with a connector or a cable connection.

The device address and baud rate can be set/modified by means of the software.

The two-color LED located on the back indicates the operating or fault status of the CAN-bus, as well as the status of the internal diagnostics.

## CANbus connection

The CANopen encoders are equipped with a bus trunk line in various lengths or a M12 connector and can be terminated in the device.

The devices do not have an integrated T-coupler nor they are looped internally and must therefore only be used as end devices.

## LSS layer setting services DS305 V2.0

- Global command support for node ID and baud rate configuration.
- Selective protocol via identity object (1018h).

## CANopen communication profile DS301 V4.2

Among others, the following functionality is integrated. (Class C2 functionality):

- NMT Slave.
- Heartbeat Protocol.
- Identity Object.
- Error Behavior Object.
- Variable PDO Mapping self-start programmable (Power on to operational), 3 Sending PDO's.
- Node address, baud rate and CANbus / programmable termination.

## CANopen encoder profile DS406 V4.0

The following parameters can be programmed:

- Event mode, start optional.
- 1 work area with upper and lower limit and the corresponding output states.
- Variable PDO mapping for position, speed, work area status, error and acceleration.
- Extended failure management for position sensing.
- User interface with visual display of bus and failure status 1 LED two colors.
- Customer-specific protocol.
- "Watchdog controlled" device.

## Bootloader functionality DS302-3

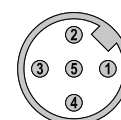
Configuration Management:

- Program download.
- Program start.
- Program erase.

## Terminal assignment

Interface	Type of connection	Cable (isolate unused wires individually before initial start-up)					
2	2, B	Signal:	+V	0 V	CAN_GND	CAN_H	CAN_L
		Cable color:	BN	WH	GY	GN	YE
Interface	Type of connection	M12 connector, 5-pin					
2	4	Signal:	+V	0 V	CAN_GND	CAN_H	CAN_L
		Pin:	2	3	1	4	5

Top view of mating side, male contact base



M12 connector, 5-pin

## CANopen



# Absolute encoders – singleturn

**Standard magnetic**

**Sendix M5858A (shaft)**

**SAE J1939**



The Sendix M5858A is a magnetic singleturn encoder in compact design. High robustness and high resolution make this encoder the ideal device for use in demanding applications.

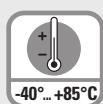
**SAE J1939**



Safety-Lockplus™



High rotational speed



Temperature range



High protection level



High shaft load capacity



Shock / vibration resistant



Reverse polarity protection

## Highest robustness

- Sturdy bearing construction in Safety-Lockplus™ design for particularly high resistance.
- Extra large bearings.
- Mechanically protected shaft seal.
- Wide temperature range -40 °C ... +85 °C.

## Up-to-the-minute fieldbus performance

- Up-to-the-minute fieldbus performance in the application: SAE J1939 with CAN-highspeed to ISO 11898.
- Fast determination of the operating status via two-color LED.

## Order code

### Shaft version

8.M5858A.XX3X.3222

#### a Version

- 3 = clamping flange, IP65, ø 58 mm [2.28"]
- 4 = synchro flange, IP65, ø 58 mm [2.28"]

#### b Shaft (ø x L), with flat

- 1 = ø 6 x 12.5 mm [0.24 x 0.49"]
- 5 = ø 10 x 20 mm [0.39 x 0.79"]

#### c Interface / supply voltage

- 3 = SAE J1939 / 10 ... 30 V DC

#### d Type of connection

- 2 = radial cable, 1 m [3.28'] PVC
- B = radial cable, special length PVC \*)
- 4 = radial M12 connector, 5-pin

\*) Available special lengths (connection types B):  
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']  
order code expansion .XXXX = length in dm  
ex.: 8.M5858A.313B.3222.0030 (for cable length 3 m)

#### e Fieldbus profile

- 32 = SAE J1939

Optional on request

- Ex 2/22 (only for connection type 4)

# Absolute encoders – singleturn

Standard magnetic		Sendix M5858A (shaft)	SAE J1939
Mounting accessory for shaft encoders			Order no.
Coupling	Bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]		8.0000.1102.1010
Cables and connectors			Order no.
Preassembled cables	M12 female connector with coupling nut, 5-pin, A coded, straight single ended 5 m [16.40'] PVC cable	Bus in	05.00.6091.A211.005M
	M12 female connector with coupling nut, 5-pin, A coded, straight Deutsch connector DT04, male contacts, 6-pin, straight 1 m [3.28'] PVC cable	Bus in	05.00.6091.22C7.001M
Connectors	M12 female connector with coupling nut, 5-pin, A coded, straight (metal)	Bus in	8.0000.5116.0000

Further Kübler accessories can be found at: /accessories  
Further Kübler cables and connectors can be found at: /connection-technology

Technical data			
Mechanical characteristics		Interface characteristics SAE J1939	
Maximum speed	4000 min <sup>-1</sup> 2000 min <sup>-1</sup> (continuous)	Resolution	1 ... 16.384 (14 bit), scalable default: 16.384 (14 bit)
Starting torque at 20 °C [68 °F]	< 0.01 Nm	Angular measurement deviation <sup>2)</sup>	±0,5°
Shaft load capacity	radial 80 N axial 40 N	Repeat accuracy	±0.2°
Weight	approx. 280 g [9.88 oz]	Interface	CAN high-speed acc. to ISO 11898, CAN specification 2.0 B
Protection acc. to EN 60529/DIN 40050-9	IP65	Protocol	SAE J1939
Working temperature range	-40 °C ... +85 °C [-40 °F ... +185 °F]	Power-ON time	< 1200 ms
Materials	shaft V2A flange aluminum housing zinc die-cast cable PVC	Baud rate	250 kbit/s switchable by software to 500 kbit/s
Shock resistance acc. to EN 60068-2-27	5000 m/s <sup>2</sup> , 4 ms	Node address	software configurable
Vibration resistance acc. to EN 60068-2-6	300 m/s <sup>2</sup> , 10 ... 2000 Hz	Termination	software configurable
Electrical characteristics		Approvals	
Supply voltage	10 ... 30 V DC	E1 compliant in accordance with	ECE guideline
Current consumption (no load)	max. 30 mA	UL compliant in accordance with	File no. E224618
Reverse polarity protection of the supply voltage	yes	CE compliant in accordance with	
Short-circuit proof outputs	yes <sup>1)</sup>	EMC Directive	2014/30/EU
		RoHS Directive	2011/65/EU
		ATEX Directive	2014/34/EU (for Ex 2/22 variants)

1) Short circuit proof to 0 V or to output when supply voltage correctly applied.  
2) Over the whole temperature range.

# Absolute encoders – singleturn

## Standard magnetic

## Sendix M5858A (shaft)

## SAE J1939

### General information concerning SAE J1939

The protocol J1939 originates from the international Society of Automotive Engineers (SAE) and operates on the physical layer with high speed CAN as per ISO11898. The application emphasis lies in the area of the power train and chassis of commercial vehicles. It serves to transfer diagnostic data (for example, motor speed, position, temperature) and control information. Type series M3658 and M3678 encoders support the total functionality of J1939.

This protocol is a multimaster system with decentralized network management that does not involve channel-based communication.

It supports up to 254 logic nodes and 30 physical control devices per segment. The information is described as parameters (signals) and combined on 4 memory pages (data pages) into parameter groups (PGs). Each parameter group can be identified via a unique number, the parameter group number (PGN). Independently of this, each signal is assigned a unique SPN (suspect parameter number).

The major part of the communication occurs cyclically and can be received by all control devices without the explicit request for data (Broadcast). Furthermore the parameter groups are optimized to a length of 8 data bytes. This enables very efficient utilization of the CAN protocol. If greater amounts of data need to be transferred, then transport protocols (TP) can be used: BAM (broadcast announce message) and CMTD (connection mode data transfer). With BAM TP the transfer of data occurs as a broadcast.

### Encoder implementation SAE J1939

- PGNs that are adaptable to the customer's application.
- Resolution of address conflicts -> Address Claiming (ACL).
- Continuous checking whether control addresses have been assigned twice within a network.
- Change of control device addresses during run-time.
- Unique identification of a control device with the help of a name that is unique worldwide. This name serves to identify the functionality of a control device in the network.
- Predefined PGs for position, speed and alarm.
- 250 kbit/s, 29 bit identifier.
- Watchdog controlled device.

A two-color LED, located on the rear of the encoder, signals the operating and fault status of the J1939 protocol, as well as the status of the internal sensor diagnostics.

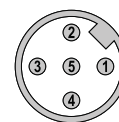
### Terminal assignment

Interface	Type of connection	Cable (isolate unused wires individually before initial start-up)					
2	2, B	Signal:	+V	0 V	CAN_GND	CAN_H	CAN_L
		Cable color:	BN	WH	GY	GN	YE

Interface	Type of connection	M12 connector, 5-pin					
2	4	Signal:	+V	0 V	CAN_GND	CAN_H	CAN_L
		Pin:	2	3	1	4	5

Top view of mating side, male contact base



M12 connector, 5-pin

# Absolute encoders – singleturn

Standard magnetic	Sendix M5858A (shaft)	SAE J1939
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## Dimensions

Dimensions in mm [inch]

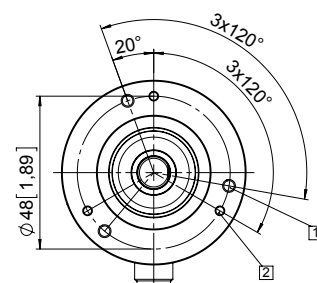
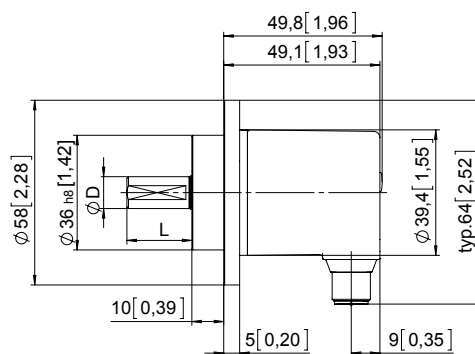
### Clamping flange, ø 58 [2.28]

#### Flange type 3

1 3 x M4

2 3 x M3

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
10 [0.39]	h7	20 [0.79]

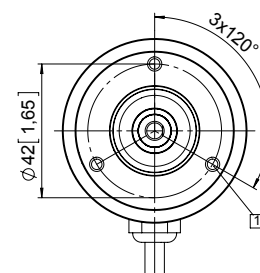
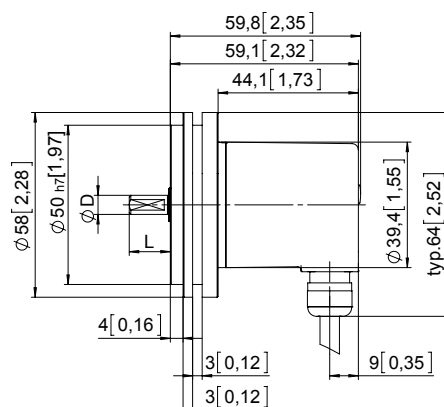


### Synchro flange, ø 58 [2.28]

#### Flange type 4

1 3 x M4, 10 [0.39] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
10 [0.39]	h7	20 [0.79]



# Absolute encoders – singleturn

Standard  
magnetic

Sendix M5858A (shaft)

IO-Link



The Sendix M58 is a magnetic singleturn encoder in compact design. High robustness and high resolution make this encoder the ideal device for use in demanding applications.

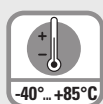
With Smart Sensor Profile for easy and fast integration into the application.



Safety-Lockplus™



High rotational speed



Temperature range



High protection level



High shaft load capacity



Shock / vibration resistant



Reverse polarity protection

## Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ design for resistance against vibration and installation errors.
- Reduced number of components ensures magnetic insensitivity.
- IP67 protection and wide temperature range -40°C ... +85°C.

## Up-to-the-minute performance

- Operation possible with any IO-Link master.
- Point-to-point communication in automation networks.
- Use of cost-effective unshielded cables possible.
- Automatic saving of device parameters.
- Firmware update via IO-Link.

## Order code

### Shaft version

8.M5858A.XX4X.41X2  
Type a b c d e f

#### a Flange

- 3 = clamping flange, ø 58 mm [2.28"]
- 4 = synchro flange, ø 58 mm [2.28"]

#### b Shaft (ø x L), with flat

- 1 = ø 6 x 12.5 mm [0.24 x 0.49"]
- 5 = ø 10 x 20 mm [0.39 x 0.79"]

#### c Interface / power supply

- 4 = IO-Link / 18 ... 30 V DC

#### d Type of connection

- 3 = axial M12 connector, 4-pin
- 4 = radial M12 connector, 4-pin

#### e Fieldbus profile

- 41 = IO-Link

#### f Profile

- 2 = Standard Profile <sup>1)</sup>
- 3 = Smart Sensor Profile <sup>2)</sup>

Optional on request  
- Ex 2/22

## Mounting accessory for shaft encoders

Order no.

### Coupling

Bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]

8.0000.1102.1010

## Cables and connectors

Order no.

### Preassembled cables

M12 female connector with coupling nut, 4-pin, A coded, straight single-ended  
2 m [6.56'] PUR cable

05.00.6061.6211.002M

### Connectors

M12 female connector with coupling nut, 4-pin, A coded, straight

05.B8141-0

Further Kübler accessories can be found at: /accessories

Further Kübler cables and connectors can be found at: /connection-technology

1) Delivered with default setting for Standard Profile (switchable to Smart Sensor Profile).

2) Delivered with default setting for Smart Sensor Profile (switchable to Standard Profile).

# Absolute encoders – singleturn

<b>Standard magnetic</b>	<b>Sendix M5858A (shaft)</b>	<b>IO-Link</b>
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## Technical data

### Mechanical characteristics

<b>Maximum speed</b>	4000 min <sup>-1</sup> 2000 min <sup>-1</sup> (continuous)
<b>Starting torque at 20°C [68°F]</b>	< 0.01 Nm
<b>Shaft load capacity</b>	radial 80 N axial 40 N
<b>Weight</b>	approx. 280 g [9.88 oz]
<b>Protection acc. to EN 60529/DIN 40050-9</b>	IP65
<b>Working temperature range</b>	-40 °C ... +85 °C [-40 °F ... +185 °F]
<b>Materials</b>	shaft V2A flange aluminum housing zinc die-cast
<b>Shock resistance acc. to EN 60068-2-27</b>	5000 m/s <sup>2</sup> , 4 ms
<b>Vibration resistance acc. to EN 60068-2-6</b>	300 m/s <sup>2</sup> , 10 ... 2000 Hz

### Electrical characteristics

<b>Power supply</b>	18 ... 30 V DC
<b>Current consumption (no load)</b>	max. 40 mA
<b>Reverse polarity protection of the power supply</b>	yes

### Interface characteristics IO-Link

<b>Resolution</b>	1 ... 16.384 (14 bit), scalable default: 16.384 (14 bit)
<b>Angular measurement deviation <sup>1)</sup></b>	±0,5°
<b>Repeat accuracy</b>	±0,2°
<b>Interface</b>	IO-Link version 1.1 acc. to IEC 61131-9
<b>Profile (details see manual)</b>	Kübler Standard Profile or Smart Sensor Profile
<b>Port classe</b>	Type A

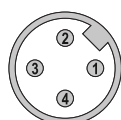
### Approvals

<b>UL compliant</b> in accordance with	File no. E224618
<b>CE compliant</b> in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU (for Ex 2/22 variants)

## Terminal assignment

Interface	Type of connection	M12 connector, 4-pin				
4	3, 4	Signal:	Power supply +V DC	Reserved (no function)	Power supply 0 V (GND)	IO-Link communication (Data line)
		Abbreviation:	L+	res.	L-	C/Q
		Pin:	1	2	3	4

### Top view of mating side, male contact base



M12 connector, 4-pin

<sup>1)</sup> Over the whole temperature range.

## Absolute encoders – singleturn

**Standard  
magnetic**

### Sendix M5858A (shaft)

## IO-Link

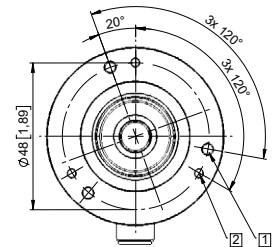
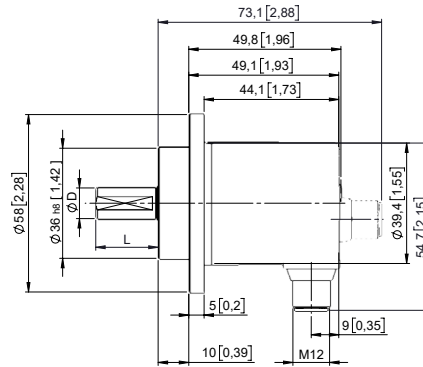
## Dimensions

Dimensions in mm [inch]

**Clamping flange, ø 58 [2.28]**

### Flange type 3

- ① 3 x M4  
② 3 x M3

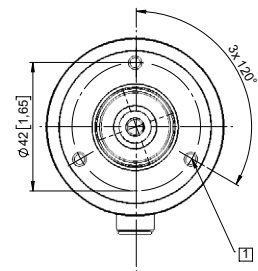
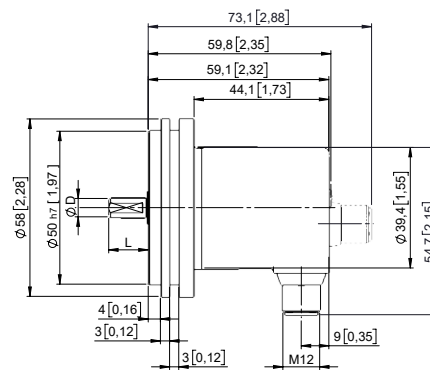


D	Fit	L
6 [0.24]	h7	12.5 [0.49]
10 [0.39]	f7	20 [0.79]

**Synchro flange, ø 58 [2.28]**

### Flange type 4

- ① 3 x M4, 10 [0.39] deep



D	Fit	L
6 [0.24]	h7	12.5 [0.49]
10 [0.39]	f7	20 [0.79]

# Absolute encoders - singleturn

**Standard  
optical**

**Sendix 5853 / 5873 (shaft / hollow shaft)**

**SSI / BiSS + incremental**



The Sendix 5853 and Sendix 5873 singleturn encoders with optical sensor technology can achieve a resolution of max. 21 bits.

Easy integration in the application thanks to the BiSS interface, with electronic data sheet.

This series offers special versions for use on direct drives for the lift technology.



Electronic data sheet



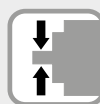
Safety-Lock™



Temperature range  
-40...+90 °C



High protection level  
IP



High shaft load capacity



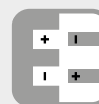
Shock / vibration resistant



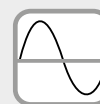
Magnetic field proof



Short-circuit proof



Reverse polarity protection



SinCos



Optical sensor

## Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ design for resistance against vibration and installation errors.
- Ideal for use outdoors thanks to IP67 protection and wide temperature range from -40 °C up to +90 °C.

## Versatile

- High-precision with a data refresh rate of the position value  $\leq 1\mu s$ .
- High-resolution feedback in real-time via 21 bit fully digital or incremental outputs SinCos and RS422.
- BiSS-C BP3 encoder profile.
- Short control cycles, clock rate with SSI up to 2 MHz / with BiSS up to 10 MHz.

## Order code

**Shaft version**

**8.5853**

Type

. XXXXX . XX2X  
a b c d e f g

### a Flange

- 1 = clamping flange, IP65,  $\varnothing$  58 mm [2.28"]**  
 3 = clamping flange, IP67  $\varnothing$  58 mm [2.28"]  
**2 = synchro flange, IP65,  $\varnothing$  58 mm [2.28"]**  
 4 = synchro flange, IP67  $\varnothing$  58 mm [2.28"]  
 5 = square flange, IP65  $\square$  63.5 mm [2.5"]  
 7 = square flange, IP67  $\square$  63.5 mm [2.5"]

### b Shaft ( $\varnothing \times L$ ), with flat

- 1 = 6 x 10 mm [0.24 x 0.39"]<sup>1)</sup>**  
**2 = 10 x 20 mm [0.39 x 0.79"]<sup>2)</sup>**  
 3 = 1/4" x 7/8"  
 4 = 3/8" x 7/8"

### c Interface / supply voltage

- 1 = SSI, BiSS / 5 V DC  
**2 = SSI, BiSS / 10 ... 30 V DC**  
 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC  
 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC  
 5 = SSI, BiSS / 5 V DC, with sensor output  
 6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output  
 7 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC  
 8 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 10 ... 30 V DC  
 9 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC, with sensor output

### d Type of connection

- 1 = axial cable, 1 m [3.28'] PVC  
 A = axial cable, special length PVC \*)  
**2 = radial cable, 1 m [3.28'] PVC**  
 B = radial cable, special length PVC \*)  
 3 = axial M23 connector, 12-pin  
**4 = radial M23 connector, 12-pin**  
 5 = axial M12 connector, 8-pin<sup>3)</sup>  
 6 = radial M12 connector, 8-pin<sup>3)</sup>

\*) Available special lengths (connection types A, B):  
 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']  
 order code expansion .XXXX = length in dm  
 ex.: 8.5853.112A.G323.0030 (for cable length 3 m)

### e Code

- B = SSI, binary  
 C = BiSS, binary  
**G = SSI, gray**

### f Resolution<sup>4)</sup>

- A = 10 bit  
 1 = 11 bit  
 2 = 12 bit  
**3 = 13 bit**  
 4 = 14 bit  
 7 = 17 bit  
 9 = 19 bit  
 C = 21 bit<sup>5)</sup>

### g Options (service)

- 1 = no option  
 2 = status LED  
**3 = SET button and status LED**

### Optional on request

- Ex 2/22<sup>6)</sup>  
 - surface protection  
 salt spray tested  
 - other resolutions

1) Preferred type only in conjunction with flange type 2.  
 2) Preferred type only in conjunction with flange type 1.  
 3) Can be combined only with interface 1 and 2.

4) Resolution, preset value and counting direction factory-programmable.  
 5) Only in conjunction with interface 1 or 2.  
 6) For the cable connection type, cable material PUR.



# Absolute encoders - singleturn

Standard optical	Sendix 5853 / 5873 (shaft / hollow shaft)	SSI / BiSS + incremental
Order code Hollow shaft	8.5873 . XXXX . XX2X Type	
<b>a</b> Flange 1 = with spring element, long, IP65 2 = with spring element, long, IP67 3 = with stator coupling, IP65 ø 65 mm [2.56"] 4 = with stator coupling, IP67 ø 65 mm [2.56"] <b>5 = with stator coupling, IP65 ø 63 mm [2.48"]</b> 6 = with stator coupling, IP67 ø 63 mm [2.48"] G = with stator coupling, IP65 ø 72 mm [2.83"] <sup>1)</sup> H = with expanding coupling, IP65 ø 65 mm [2.56"] <sup>1)</sup>	<b>c</b> Interface / supply voltage 1 = SSI, BiSS / 5 V DC <b>2 = SSI, BiSS / 10 ... 30 V DC</b> 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC 5 = SSI, BiSS / 5 V DC, with sensor output 6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output 7 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC 8 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 10 ... 30 V DC 9 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC, with sensor output	<b>e</b> Code B = SSI, binary C = BiSS, binary <b>G = SSI, gray</b>
<b>b</b> Through hollow shaft 3 = ø 10 mm [0.39"] <b>4 = ø 12 mm [0.47"]</b> 5 = ø 14 mm [0.55"] 6 = ø 15 mm [0.59"] 8 = ø 3/8" 9 = ø 1/2" Tapered shaft K = ø 10 mm [0.39"]	<b>d</b> Type of connection 2 = radial cable, 1 m [3.28'] PVC B = radial cable, special length PVC *) <b>E = tangential cable, 1 m [3.28'] PVC</b> F = tangential cable, special length PVC *) <b>4 = radial M23 connector, 12-pin</b> 6 = radial M12 connector, 8-pin <sup>2)</sup> *) Available special lengths (connection types B, F): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.5873.542B.G323.0030 (for cable length 3 m)	<b>g</b> Options (service) 1 = no option 2 = status LED <b>3 = SET button and status LED</b>
		<b>i</b> Resolution <sup>3)</sup> A = 10 bit 1 = 11 bit 2 = 12 bit <b>3 = 13 bit</b> 4 = 14 bit 7 = 17 bit 9 = 19 bit C = 21 bit <sup>4)</sup>
		Optional on request - Ex 2/22 (not with type of connection E or F) <sup>5)</sup> - surface protection salt spray tested - other resolutions

Mounting accessory for shaft encoders	Order no.
<b>Coupling</b> bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"] bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1102.0606 8.0000.1102.1010
Mounting accessory for hollow shaft encoders Dimensions in mm [inch]	Order no.
<b>Torque pin, ø 4 mm</b> for flange with spring element (flange type 1)	8.0010.4700.0000
Cables and connectors	Order no.
<b>Preassembled cables</b> M12 female connector with coupling nut, 8-pin, A coded, straight single-ended 2 m [6.56'] PVC cable M23 female connector with coupling nut, 12-pin, cw single-ended 2 m [6.56'] PVC cable	05.00.6041.8211.002M 8.0000.6901.0002.0031
<b>Connectors</b> M12 female connector with coupling nut, 8-pin, A coded, straight (metal) M23 female connector with coupling nut, 12-pin, cw	05.CMB 8181-0 8.0000.5012.0000

Further Kübler accessories can be found at: [/accessories](#)  
 Further Kübler cables and connectors can be found at: [/connection-technology](#)

1) Can be combined only with shaft K and type of connection E or F.  
 2) Can be combined only with interface 1 and 2.  
 3) Resolution, preset value and counting direction factory-programmable.

4) Only in conjunction with interface 1 or 2.  
 5) For the cable connection type, cable material PUR.

# Absolute encoders - singleturn

<b>Standard optical</b>	<b>Sendix 5853 / 5873 (shaft / hollow shaft)</b>	<b>SSI / BiSS + incremental</b>
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## Technical data

Mechanical characteristics			BiSS interface		
<b>Maximum speed shaft version</b>			<b>Output driver</b>		
IP65 up to 70 °C [158 °F]	12000 min <sup>-1</sup> , 10000 min <sup>-1</sup> (continuous)		RS485 transceiver type		
IP65 up to T <sub>max</sub>	8000 min <sup>-1</sup> , 5000 min <sup>-1</sup> (continuous)		<b>Permissible load / channel</b>		
IP67 up to 70 °C [158 °F]	11000 min <sup>-1</sup> , 9000 min <sup>-1</sup> (continuous)		max. +/- 20 mA		
IP67 up to T <sub>max</sub>	8000 min <sup>-1</sup> , 5000 min <sup>-1</sup> (continuous)		<b>Signal level</b>		
			HIGH typ. 3.8 V		
			LOW at I <sub>Load</sub> = 20 mA typ. 1.3 V		
<b>Maximum speed hollow shaft version</b>			<b>Resolution</b>		
IP65 up to 70 °C [158 °F]	9000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous)		10 ... 14 bit; 17, 19 and 21 bit		
IP65 up to T <sub>max</sub>	6000 min <sup>-1</sup> , 3000 min <sup>-1</sup> (continuous)		<b>Code</b>		
IP67 up to 70 °C [158 °F]	8000 min <sup>-1</sup> , 4000 min <sup>-1</sup> (continuous)		binary		
IP67 up to T <sub>max</sub>	4000 min <sup>-1</sup> , 2000 min <sup>-1</sup> (continuous)		<b>Clock rate</b>		
			50 kHz ... 10 MHz		
<b>Starting torque</b>			<b>Max. update rate</b>		
at 20 °C [68 °F]	IP65 < 0.01 Nm		< 15 µs, depends on the clock rate and the data length		
	IP67 < 0.05 Nm		<b>Data refresh rate</b>		
<b>Mass moment of inertia</b>			ST resolution ≤ 14 bit ≤ 1 µs		
shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup>		ST resolution > 14 bit ≤ 4 µs		
hollow shaft version	6.0 x 10 <sup>-6</sup> kgm <sup>2</sup>		<b>Protocol</b>		
<b>Load capacity of shaft</b>			BiSS-C BP3 encoder profile		
radial	80 N		<b>Note:</b>		
axial	40 N		– Bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings		
<b>Weight</b>			– CRC data verification		
	approx. 0.35 kg [12.35 oz]		– EDS (electronic data sheet)		
<b>Protection</b>			<b>Status output and LED</b>		
acc. to EN 60529	housing side IP67		<b>Output driver</b>		
	shaft side IP65, opt. IP67		open collector, internal pull up resistor 22 kOhm		
<b>Working temperature range</b>			<b>Permissible load</b>		
	-40 °C ... +90 °C [-40 °F ... +194 °F] <sup>1)</sup>		max. 20 mA		
<b>Materials</b>			<b>Signal level</b>		
shaft/hollow shaft	stainless steel		HIGH +V		
flange	aluminum		LOW < 1 V		
housing	zinc die-cast		<b>Active</b>		
cable	PVC (PUR for Ex 2/22)		LOW		
<b>Shock resistance</b> acc. EN 60068-2-27			The optional LED (red) and the status output serve to display various alarm or error messages. In normal operation the LED is OFF and the status output is HIGH (Open Collector with int. pull-up 22 kOhm).		
	2500 m/s <sup>2</sup> , 6 ms		An active status output (LOW) displays:		
<b>Vibration resistance</b> acc. EN 60068-2-6			– Sensor error, singleturn or multiturn (soiling, glass breakage etc.)		
	100 m/s <sup>2</sup> , 55 ... 2000 Hz		– LED fault (failure or ageing)		
			– over- or under-temperature		
<b>Electrical characteristics</b>			In the SSI mode, the fault indication can only be reset by switching off the supply voltage to the device.		
<b>Supply voltage</b>			<b>Incremental outputs (A/B)</b>		
	5 V DC (+5 %) or 10 ... 30 V DC		<b>SinCos</b>		<b>RS422 TTL compatible</b>
<b>Current consumption</b> (no load)			<b>Max. frequency -3dB</b>		<b>400 kHz</b>
5 V DC	max. 70 mA		<b>Signal level</b>		<b>1 Vpp (±20 %)</b>
10 ... 30 V DC	max. 45 mA		<b>Short circuit proof</b>		<b>yes <sup>2)</sup></b>
<b>Reverse polarity protection of the supply voltage</b>			<b>Pulse rate</b>		<b>2048 ppr</b>
	yes				
<b>Short circuit proof outputs</b>					
	yes <sup>2)</sup>				
<b>SSI interface</b>					
<b>Output driver</b>					
RS485 transceiver type					
<b>Permissible load / channel</b>					
max. +/- 20 mA					
<b>Signal level</b>					
HIGH	typ. 3.8 V				
LOW at I <sub>Load</sub> = 20 mA	typ. 1.3 V				
<b>Resolution</b>					
10 ... 14 bit; 17, 19 and 21 bit					
<b>Code</b>					
binary or gray					
<b>SSI clock rate</b>					
50 kHz ... 2 MHz					
<b>Data refresh rate</b>					
ST resolution ≤ 14 bit ≤ 1 µs					
ST resolution > 14 bit ≤ 4 µs					
<b>Monoflop time</b>					
≤ 15 µs					
<b>Note:</b> If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the data transfer starts with the new values. The update rate is dependent on the clock speed, data length and monoflop-time.					

1) Cable version: -30 °C ... +75 °C [-22 °F ... +167 °F].

2) Short circuit to 0 V or to output, one channel at a time, supply voltage correctly applied.

## Absolute encoders - singleturn

Standard optical	Sendix 5853 / 5873 (shaft / hollow shaft)	SSI / BiSS + incremental
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SET input or SET button		
Input	active HIGH	
Input type	comparator	
Signal level	HIGH	min: 60 % of +V (supply voltage) max: +V
	LOW	max: 25 % of +V (supply voltage)
Input current	< 0.5 mA	
Min. pulse duration (SET)	10 ms	
Timeout after SET signal	14 ms	
<p>The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point pen or similar).</p> <p>Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approx. 15 ms before the new position data can be read. During this time the status output is at LOW.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>		

DIR input	
<p>Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed. If DIR is changed when the device is already switched on, then this will be interpreted as an error. The status output will switch to LOW.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	
Response time (DIR input)	1 ms

Power-ON	
<p>After Power-ON the device requires a time of approx. 150 ms before valid data can be read.</p>	
<p>Hot plugging of the encoder should be avoided.</p>	

Approvals		
UL compliant in accordance with	File no. E224618	
CE compliant in accordance with		
	EMC Directive	2014/30/EU
	RoHS Directive	2011/65/EU
	ATEX Directive	2014/34/EU (for Ex 2/22 variants)

# Absolute encoders - singleturn

Standard optical	Sendix 5853 / 5873 (shaft / hollow shaft)	SSI / BiSS + incremental
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## Terminal assignment

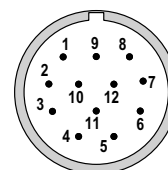
Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)													
1, 2	1, 2, A, B, E, F	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	N/C	N/C	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	-	-	-	shield
Interface	Type of connection	Features	M23 connector, 12-pin													
1, 2	3, 4	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	N/C	N/C	⊥
			Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)													
5	1, 2, A, B, E, F	SET, DIR, Status sensor output	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	0Vsens	+Vsens	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	-	GY-PK	RD-BU	shield
Interface	Type of connection	Features	M23 connector, 12-pin													
5	3, 4	SET, DIR, Status sensor output	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	N/C	0Vsens	+Vsens	⊥
			Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)													
3, 4, 7, 8	1, 2, A, B, E, F	SET, DIR, SinCos or incr. RS422	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	$\bar{A}$	B	$\bar{B}$	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield
Interface	Type of connection	Features	M23 connector, 12-pin													
3, 4, 7, 8	3, 4	SET, DIR, SinCos or incr. RS422	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	$\bar{A}$	B	$\bar{B}$	⊥
			Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)													
6, 9	1, 2, A, B, E, F	SinCos o. incr. RS422 sensor output	Signal:	0 V	+V	C+	C-	D+	D-	A	$\bar{A}$	B	$\bar{B}$	0Vsens	+Vsens	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield
Interface	Type of connection	Features	M23 connector, 12-pin													
6, 9	3, 4	SinCos o. incr. RS422 sensor output	Signal:	0 V	+V	C+	C-	D+	D-	A	$\bar{A}$	B	$\bar{B}$	0Vsens	+Vsens	⊥
			Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH
Interface	Type of connection	Features	M12 connector, 8-pin													
1, 2	5, 6	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥				
			Pin:	1	2	3	4	5	6	7	8	PH				

+V: Supply voltage encoder +V DC  
 0 V: Supply voltage encoder ground GND (0 V)  
 0 Vsens / +Vsens: Using the sensor outputs of the encoder, the voltage present can be measured and if necessary increased accordingly.  
 C+, C-: Clock signal  
 D+, D-: Data signal  
 A,  $\bar{A}$ : Incremental output channel A (cosine)  
 B,  $\bar{B}$ : Incremental output channel B (sine)  
 SET: Set input  
 DIR: Direction input  
 Stat: Status output  
 PH ⊥: Plug connector housing (shield)

## Top view of mating side, male contact base



M12 connector, 8-pin



M23 connector, 12-pin

# Absolute encoders - singleturn

Standard optical	Sendix 5853 / 5873 (shaft / hollow shaft)	SSI / BiSS + incremental
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## Dimensions shaft version

Dimensions in mm [inch]

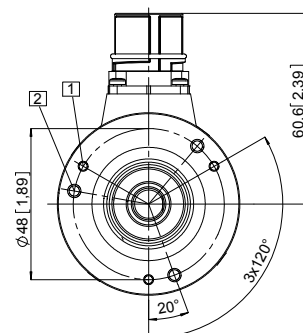
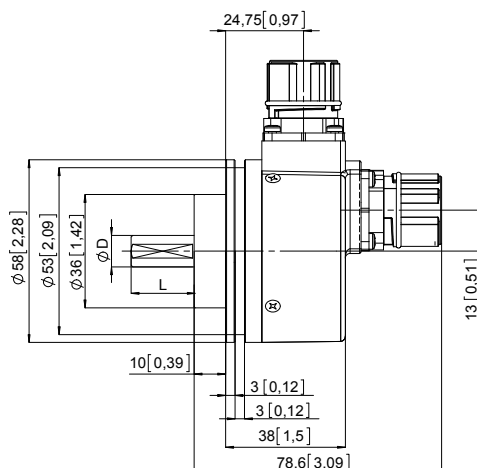
### Clamping flange, ø 58 [2.28]

#### Flange type 1 and 3

(drawing with M23 connector)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



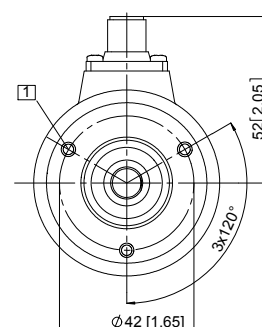
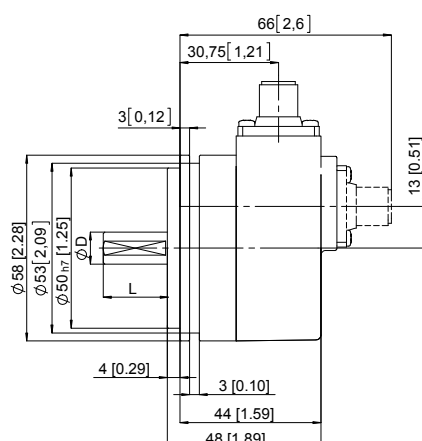
### Synchro flange, ø 58 [2.28]

#### Flange type 2 and 4

(drawing with M12 connector)

- 1 3 x M4, 6 [0.24] deep

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"

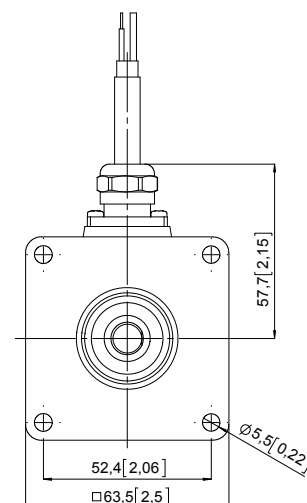
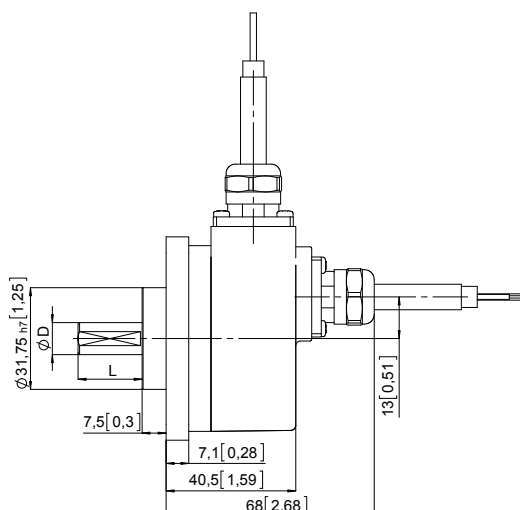


### Square flange, □ 63.5 [2.5]

#### Flange type 5 and 7

(drawing with cable)

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



# Absolute encoders - singleturn

## Standard optical

Sendix 5853 / 5873 (shaft / hollow shaft)

SSI / BiSS + incremental

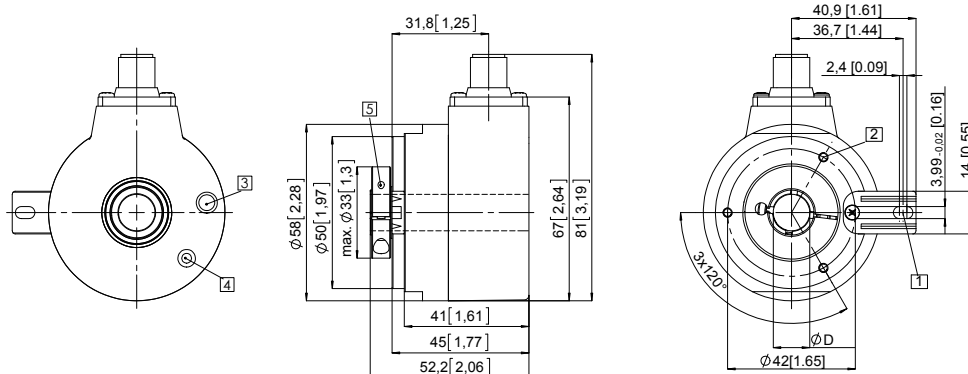
### Dimensions hollow shaft version

Dimensions in mm [inch]

#### Flange with spring element, long Flange type 1 and 2

(drawing with M12 connector)

- 1 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing$  4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Status-LED
- 4 SET button
- 5 Recommended torque for the clamping ring 0.6 Nm



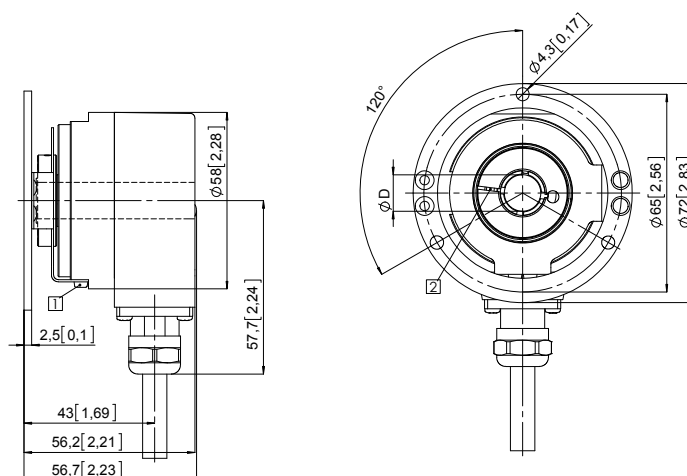
D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7
15 [0.59]	H7
3/8"	H7
1/2"	H7

#### Flange with stator coupling, $\varnothing$ 65 [2.56]

##### Flange type 3 and 4

Pitch circle diameter for fixing screws  
65 [2.56]  
(drawing with cable)

- 1 Fixing screws DIN 912 M3 x 8 (washer included in delivery)
- 2 Recommended torque for the clamping ring 0.6 Nm



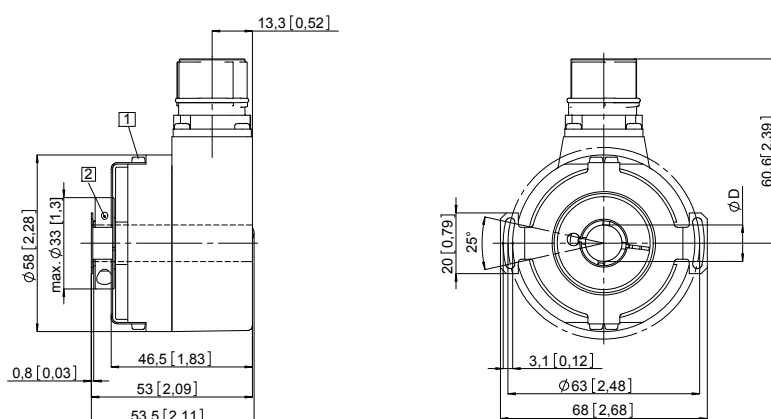
D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7
15 [0.59]	H7
3/8"	H7
1/2"	H7

#### Flange with stator coupling, $\varnothing$ 63 [2.48]

##### Flange type 5 and 6

Pitch circle diameter for fixing screws  
63 [2.48]  
(drawing with M23 connector)

- 1 Fixing screws DIN 912 M3 x 8 (washer included in delivery)
- 2 Recommended torque for the clamping ring 0.6 Nm



D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7
15 [0.59]	H7
3/8"	H7
1/2"	H7

# Absolute encoders - singleturn

Standard optical	Sendix 5853 / 5873 (shaft / hollow shaft)	SSI / BiSS + incremental
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## Dimensions hollow shaft version

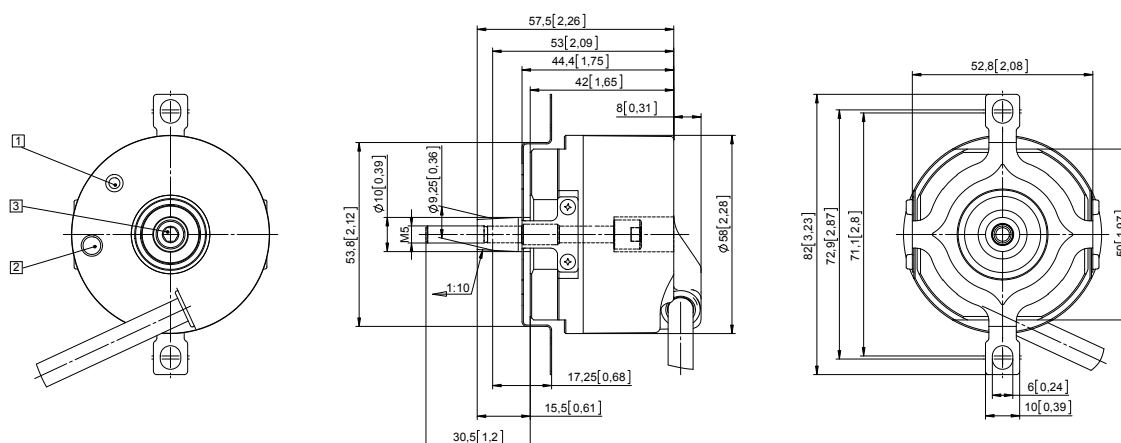
Dimensions in mm [inch]

### Flange with stator coupling, $\varnothing 72$ [2.83]

#### Flange type G

(with tapered shaft K and tangential cable)

- 1 Status LED
- 2 SET Button
- 3 Recommended torque for (SW 4) tightening screw  $3^{+0.5}$  Nm



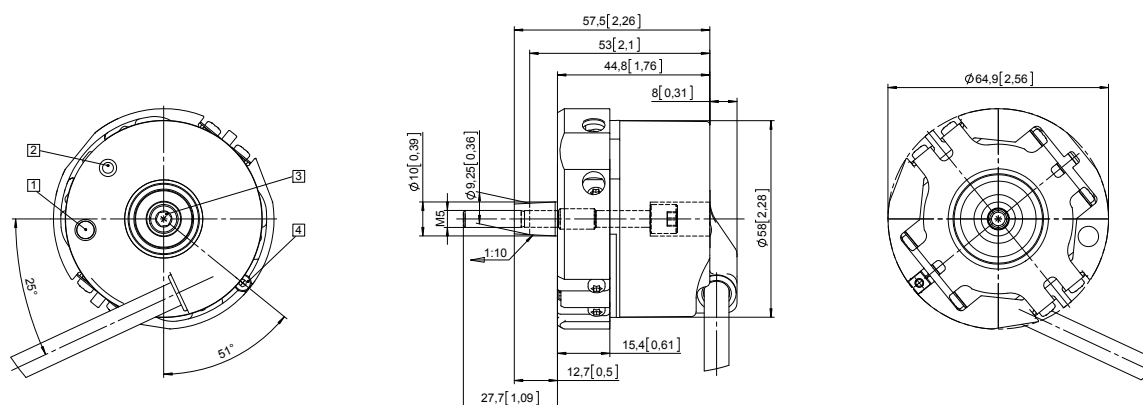
## Dimensions hollow shaft version

Dimensions in mm [inch]

### Flange with expanding coupling, $\varnothing 65$ [2.56"]

#### Flange type H

- 1 Status-LED
- 2 SET button
- 3 Recommended torque for (SW 4) tightening screw  $3^{+0.5}$  Nm
- 4 Recommended torque for (SW 2) tightening screw 1 Nm



# Absolute encoders - singleturn

**Standard**  
**SIL3/PLe, optical**

**Sendix 5853FS3 / 5873FS3 (shaft / hollow shaft)**

**SSI / BiSS + SinCos**



**SIL3**  
Functional Safety  
**PLe**

The absolute singleturn encoders 5853FS3 and 5873FS3 of the Sendix family are suited for use in safety-related applications up to SIL3 according to EN 61800-5-2 or PLe to EN ISO 13849-1.

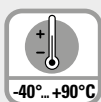
The extra strong Safety-Lock™ Design interlocked bearings, the high integration density of the components based on OptoASIC technology and the rugged die-cast housing make these devices ideal also for demanding applications outdoors up to IP67.



Safety-Lock™



High rotational speed



Temperature range  
-40°C...+90°C



High protection level  
IP



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Reverse polarity protection



SinCos



Optical sensor

## Functional Safety

- Encoder with individual certificate from TÜV.
- Suitable for applications up to SIL3 acc. to EN 61800-5-2.
- Suitable for applications up to PLe acc. to EN ISO 13849-1.
- SSI or BiSS interface with incremental SinCos tracks with 2048 ppr.
- Certified mechanical mounting + electronic.

## Flexible

- Shaft and hollow shaft versions.
- Cable and connector variants.
- Various mounting options available.

## Order code

**8.5853FS3**

## Shaft version

Type

. XXXX . XX2X  
a b c d e f g

### a Flange

- 1 = clamping flange, IP65, ø 58 mm [2.28"]
- 3 = clamping flange, IP67, ø 58 mm [2.28"]

### b Shaft (ø x L)

- 2 = 10 x 20 mm [0.39 x 0.79"], with flat
- A = 10 x 20 mm [0.39 x 0.79"], with feather key

### c Interface / supply voltage

- 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC
- 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC

### d Type of connection

- 1 = axial cable, 1 m [3.28'] PVC
- A = axial cable, special length PVC \*)
- 2 = radial cable, 1 m [3.28'] PVC
- B = radial cable, special length PVC \*)
- 3 = axial M23 connector, 12-pin
- 4 = radial M23 connector, 12-pin

\*) Available special lengths (connection types A, B):  
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']  
order code expansion .XXXX = length in dm  
ex.: 8.5853FS33.124A.G322.0030 (for cable length 3 m)

### e Code

- B = SSI, binary
- C = BiSS, binary
- G = SSI, gray

### f Resolution <sup>1)</sup>

- A = 10 bit
- 1 = 11 bit
- 2 = 12 bit
- 3 = 13 bit
- 4 = 14 bit
- 7 = 17 bit

### g Options (service)

- 1 = no option
- 2 = status LED
- 3 = SET button and status LED

### Optional on request

- Ex 2/22 (only for variants with IP67) <sup>2)</sup>
- other resolutions
- surface protection salt spray

1) Resolution, preset value and count direction are factory-programmable.

2) For the cable connection type, cable material PUR.



# Absolute encoders - singleturn

Standard SIL3/PLe, optical	Sendix 5853FS3 / 5873FS3 (shaft / hollow shaft)	SSI/BiSS + SinCos
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Order code Hollow shaft	8.5873FS3 Type	. XXXXX . XX2X a b c d e f g
<p><b>a Flange</b>            9 = with torque stop FS, flexible, IP65            J = with torque stop FS, flexible, IP67            A = with torque stop FS, rigid, IP65 (incl. torque pin FS)            K = with torque stop FS, rigid, IP67 (incl. torque pin FS)            B = with stator coupling FS, ø 63 mm [2.48"], IP65            L = with stator coupling FS, ø 63 mm [2.48"], IP67</p> <p><b>b Through hollow shaft</b>            3 = ø 10 mm [0.39"]            4 = ø 12 mm [0.47"]            5 = ø 14 mm [0.55"]  <i>Tapered shaft</i>            K = ø 10 mm [0.39"]</p> <p><b>c Interface / supply voltage</b>            3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC            4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC</p> <p><b>d Type of connection</b>            2 = radial cable, 1 m [3.28'] PVC            B = radial cable, special length PVC *)            E = tangential cable, 1 m [3.28'] PVC            F = tangential cable, special length PVC *)            4 = radial M23 connector, 12-pin</p> <p>*) Available special lengths (connection types B, F):            2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']            order code expansion .XXXX = length in dm            ex.: 8.5873FS3.B44B.G322.0030 (for cable length 3 m)</p> <p><b>e Code</b>            B = SSI, binary            C = BiSS, binary            G = SSI, gray</p> <p><b>f Resolution <sup>1)</sup></b>            A = 10 bit            1 = 11 bit            2 = 12 bit            3 = 13 bit            4 = 14 bit            7 = 17 bit</p> <p><b>g Options (service)</b>            1 = no option            2 = status LED            3 = SET button and status LED</p> <p><i>Optional on request</i>            - Ex 2/22 (only for variants with IP67) <sup>2)</sup>              not for type of connection E, F            - other resolutions            - surface protection salt spray</p>		

Accessories		Order no.
<b>EMC shield terminal</b>	for top-hat rail mounting	8.0000.4G06.0312
<b>Screw retention</b>	Loctite 243, 5 ml	8.0000.4G05.0000
<b>Bellows coupling, safety-oriented</b>	You will find an overview of our couplings for Sendix shaft encoders under /accessories.	
<b>Safety modules Safety-M compact</b>	You will find an overview of our systems and components for Functional Safety and the corresponding software under /safety.	
<b>LED SSI display 570 / 575</b>	Electronic position display up to 32 bit. You will find an overview or under /position_display	
Connection technology		Order no.
<b>Cordset, pre-assembled</b>	M23 female connector with coupling nut, 12-pin, cw single ended 2 m [6.56'] PVC cable <sup>3)</sup>	8.0000.6901.0002.0031
	M23 female connector with coupling nut, 12-pin, cw M23 male connector with external thread, 12-pin, ccw 2 m [6.56'] PVC cable <sup>3)</sup>	8.0000.6905.0002.0032
<b>Connector, self-assembly</b>	M23 female connector with coupling nut, 12-pin, cw	8.0000.5012.0000

Further Kübler accessories can be found at: [/accessories](#)  
 Further Kübler cables and connectors can be found at: [/connection-technology](#)

1) Resolution, preset value and count direction are factory-programmable.  
 2) For the cable connection type, cable material PUR.  
 3) Other lengths available.

# Absolute encoders - singleturn

<b>Standard SIL3/PLe, optical</b>	<b>Sendix 5853FS3 / 5873FS3 (shaft / hollow shaft)</b>	<b>SSI/BiSS + SinCos</b>
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## Technical data

<b>Notes regarding "Functional Safety"</b>	
These encoders are suitable for use in safety-related systems up to SIL3 acc. to EN 61800-5-2 and PLe to EN ISO 13849-1 in conjunction with controllers or evaluation units, which possess the necessary functionality. Additional functions can be found in the operating manual.	

<b>Safety characteristics</b>	
<b>Classification</b>	PLe / SIL3
<b>System structure</b>	2 channel (Cat. 4)
<b>PFH<sub>d</sub> value <sup>1)</sup></b>	1.09 x 10 <sup>-8</sup> h <sup>-1</sup>
<b>Mission time / Proof test interval</b>	20 years
<b>Relevant standards</b>	EN ISO 13849-1:2015; EN ISO 13849-2:2012; EN 61800-5-2:2007

<b>Electrical characteristics</b>	
<b>Supply voltage</b>	5 V DC (±5 %) or 10 ... 30 V DC
<b>Current consumption</b>	5 V DC max. 70 mA (no load) 10 ... 30 V DC max. 45 mA
<b>Reverse polarity protection of the supply voltage</b>	yes
<b>Short circuit proof outputs</b>	yes <sup>2)</sup>

<b>Mechanical characteristics</b>	
<b>Maximum speed shaft version</b>	up to 70 °C [158 °F] 12000 min <sup>-1</sup> , 10000 min <sup>-1</sup> (continuous) up to T <sub>max</sub> 8000 min <sup>-1</sup> , 5000 min <sup>-1</sup> (continuous)
<b>Maximum speed hollow shaft version</b>	up to 70 °C [158 °F] 9000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous) up to T <sub>max</sub> 6000 min <sup>-1</sup> , 3000 min <sup>-1</sup> (continuous)
<b>Starting torque - at 20 °C [68 °F]</b>	shaft version < 0.01 Nm hollow shaft version < 0.03 Nm
<b>Mass moment of inertia</b>	shaft version 4.0 x 10 <sup>-6</sup> kgm <sup>2</sup> hollow shaft version 7.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
<b>Insertion depth for shaft</b>	hollow shaft version min. 34 mm [1.34"]
<b>Load capacity of shaft</b>	radial 80 N axial 40 N
<b>Weight</b>	approx. 0.45 kg [15.87 oz]
<b>Protection acc. to EN 60529</b>	IP65, IP67
<b>Working temperature range</b>	-40 °C ... +90 °C [-40 °F ... +194 °F] <sup>3)</sup>
<b>Material</b>	shaft / hollow shaft stainless steel flange aluminum housing zinc die-cast cable PVC (PUR for Ex 2/22)
<b>Shock resistance acc. to EN 60068-2-27</b>	500 m/s <sup>2</sup> , 11 ms
<b>Vibration resistance acc. to EN 60068-2-6</b>	200 m/s <sup>2</sup> , 5 ... 2000 Hz

<b>EMC</b>	
<b>Relevant standards</b>	EN 55011 class B :2009 / A1:2010 EN 61326-1:2013 EN 61326-3-1:2008

<b>SSI interface</b>	
<b>Output driver</b>	RS485 transceiver type
<b>Permissible load / channel</b>	max. +/- 20 mA
<b>Signal level</b>	HIGH typ. 3.8 V LOW at I <sub>Load</sub> = 20 mA typ. 1.3 V
<b>Resolution</b>	10 ... 14 bit and 17 bit
<b>Code</b>	binary or gray
<b>SSI clock rate</b>	50 kHz ... 2 MHz
<b>Data refresh rate</b>	ST resolution ≤ 14 bit ≤ 1 μs ST resolution ≥ 15 bit 4 μs
<b>Monoflop time</b>	≤ 15 μs

**Note:** If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the data transfer starts with the new values. The update rate is dependent on the clock speed, data length and monoflop-time.

<b>BiSS interface</b>	
<b>Output driver</b>	RS485 transceiver type
<b>Permissible load / channel</b>	max. +/- 20 mA
<b>Signal level</b>	HIGH typ. 3.8 V LOW at I <sub>Load</sub> = 20 mA typ. 1.3 V
<b>Resolution</b>	10 ... 14 bit and 17 bit
<b>Code</b>	binary
<b>Clock rate</b>	up to 10 MHz
<b>Max. update rate</b>	< 10 μs, depends on the clock rate and the data length
<b>Data refresh rate</b>	ST resolution ≤ 14 bit ≤ 1 μs ST resolution 17 bit 2.4 μs
<b>Note:</b>	<ul style="list-style-type: none"> <li>bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings</li> <li>CRC data verification</li> </ul>

<b>SinCos interface</b>	
<b>Max. frequency -3dB</b>	400 kHz
<b>Signal level</b>	1 V <sub>pp</sub> (±10 %)
<b>Short circuit proof</b>	yes <sup>2)</sup>
<b>Pulse rate</b>	2048 ppr

<b>LED</b>	
The optional LED (red) serves to display various alarm or error messages. In normal operation the LED is OFF.	
If the LED is ON (status output LOW) this indicates:	
<ul style="list-style-type: none"> <li>sensor error, singleturn or multiturn (soiling, glass breakage etc.)</li> <li>LED error, failure or ageing</li> <li>Over- or under-temperature</li> </ul>	
In the SSI mode, the fault indication can only be reset by switching off the supply voltage to the device.	

1) The specified value is based on a diagnostic coverage of 99 %, that must be achieved with an encoder evaluation unit.  
The encoder evaluation unit must meet at least the requirements for SIL3.  
2) Short circuit to 0 V or to output, one channel at a time, supply voltage correctly applied.  
3) Cable version: -30 °C ... +90 °C [-22 °F ... +194 °F].

# Absolute encoders - singleturn

Standard SIL3/PLe, optical	Sendix 5853FS3 / 5873FS3 (shaft / hollow shaft)	SSI/BiSS + SinCos
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SET input or SET button	
Input	HIGH active
Input type	comparator
Signal level	HIGH min: 60 % of +V, max: +V LOW max: 25 % of +V (supply voltage)
Input current	< 0.5 mA
Min. pulse duration (SET)	10 ms
Timeout after SET signal	14 ms
<p>The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point pen or similar). Other preset values can be factory-programmed.</p> <p>The SET input has a signal delay time of approx. 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approx. 15 ms before the new position data can be read. During this time the LED is ON.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	

DIR input	
<p>Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This function can also be factory-programmed to be inverted. If DIR is changed when the device is already switched on, then this will be interpreted as an error.</p> <p>The LED will come ON and the status output will switch to LOW.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	
Response time (DIR input)	1 ms

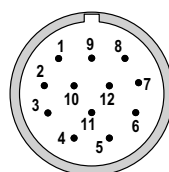
Power-ON	
<p>After Power-ON the device requires a time of approx. 150 ms before valid data can be read.</p> <p>Hot plugging of the encoder should be avoided.</p>	

## Terminal assignment

Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)													
3, 4	1, 2, A, B, E, F	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	$\bar{A}$	B	$\bar{B}$	$\perp$
		Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield
Interface	Type of connection	M23 connector, 12-pin													
3, 4	3, 4	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	$\bar{A}$	B	$\bar{B}$	$\perp$
		Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH

+V: Supply voltage encoder +V DC  
0 V: Supply voltage encoder ground GND (0 V)  
C+, C-: Clock signal  
D+, D-: Data signal  
SET: Set input  
DIR: Direction input  
A,  $\bar{A}$ : Cosine signal  
B,  $\bar{B}$ : Sine signal  
PH  $\perp$ : Plug connector housing (shield)

## Top view of mating side, male contact base



M23 connector, 12-pin

# Absolute encoders - singleturn

**Standard**  
**SIL3/PLc, optical**

**Sendix 5853FS3 / 5873FS3 (shaft / hollow shaft)**

**SSI / BiSS + SinCos**

## Dimensions shaft version

Dimensions in mm [inch]

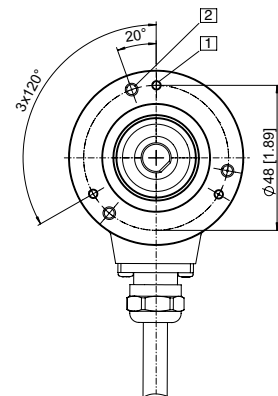
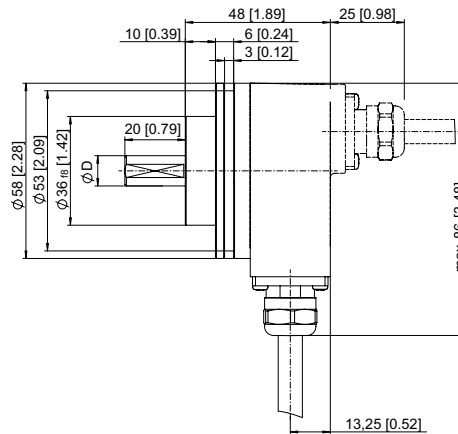
**Clamping flange,  $\varnothing$  58 [2.28]**

**Flange type 1 + 3 with shaft type 2**

(drawing with cable)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep



D	Fit	L
10 [0.39]	f7	20 [0.79]

**Clamping flange,  $\varnothing$  58 [2.28]**

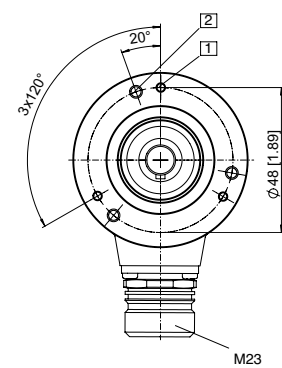
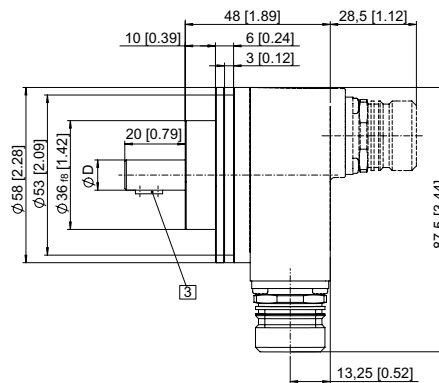
**Flange type 1 + 3 with shaft type A**

(drawing with M23 connector)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep

3 Feather key DIN 6885 - A - 3x3x6



D	Fit	L
10 [0.39]	f7	20 [0.79]

# Absolute encoders - singleturn

Standard SIL3/PLe, optical	Sendix 5853FS3 / 5873FS3 (shaft / hollow shaft)	SSI/BiSS + SinCos
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## Dimensions hollow shaft version

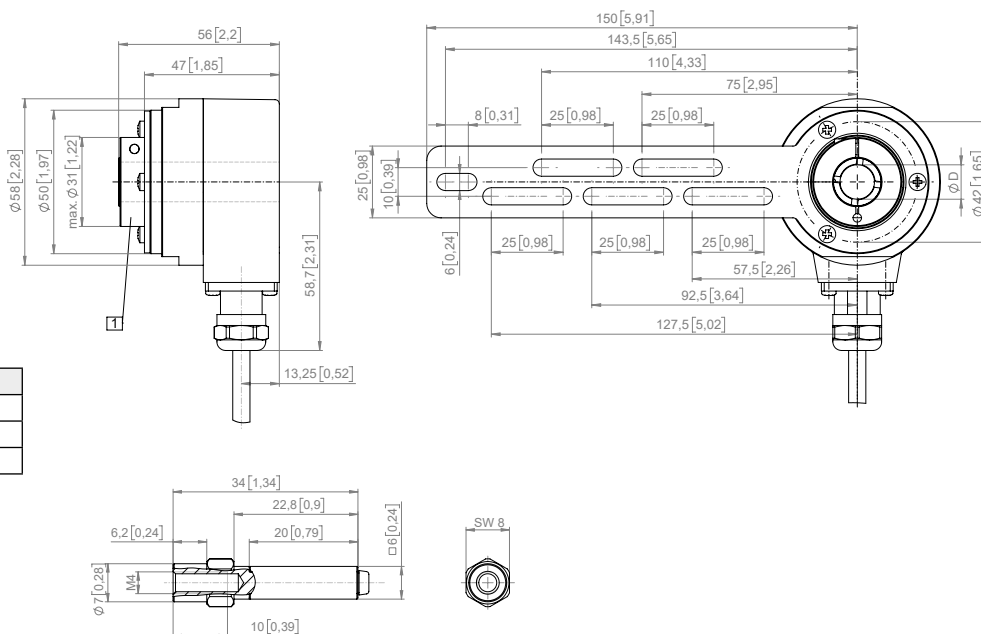
Dimensions in mm [inch]

**Flange with torque stop FS, rigid**  
**Flange type A + K**  
**Through hollow shaft**  
 (drawing with cable)

- 1 SW 3, recommended torque for the clamping ring 2.5 Nm

D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7

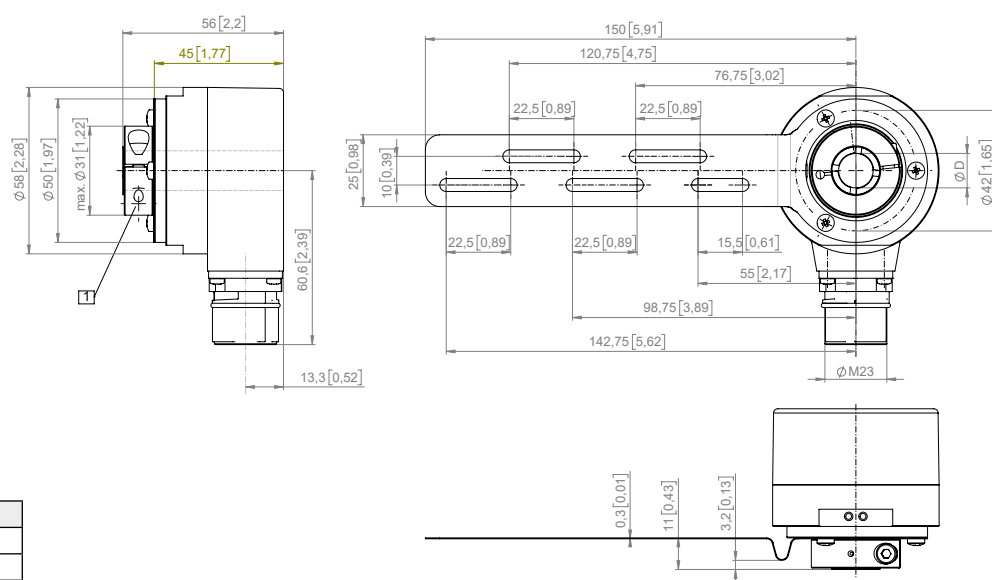
Torque pin with rectangular sleeve with M4 thread



**Flange with torque stop FS, flexible**  
**Flange type 9 + J**  
**Through hollow shaft**  
 (drawing with M23 connector)

- 1 Recommended torque for the clamping ring 2.5 Nm

D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7



# Absolute encoders - singleturn

**Standard**  
**SIL3/PLe, optical**

**Sendix 5853FS3 / 5873FS3 (shaft / hollow shaft)**

**SSI / BiSS + SinCos**

## Dimensions hollow shaft version

Dimensions in mm [inch]

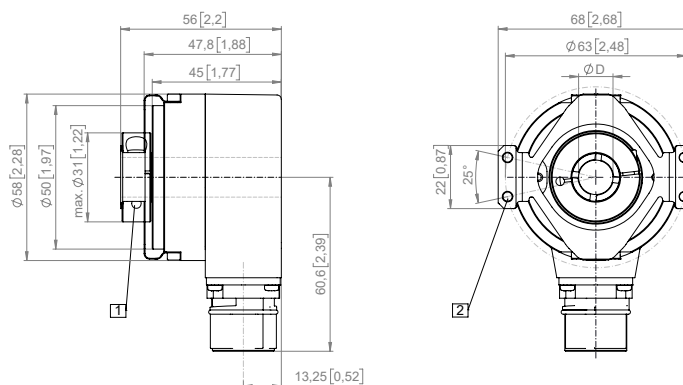
**Flange with stator coupling FS, ø 63 [2.48]**

**Flange type B + L**

**Through hollow shaft**

(drawing with M23 connector)

- 1 SW 3, recommended torque for the clamping ring 2.5 Nm
- 2 For (4x) M3 screw



D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7

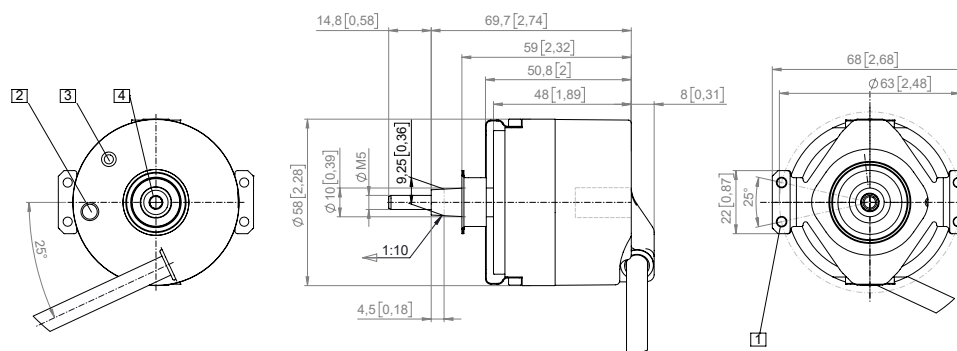
**Flange with stator coupling FS, ø 63 [2.48]**

**Flange type B + L**

**Tapered shaft**

(drawing with tangential cable outlet)

- 1 For (4x) M3 screw
- 2 Status-LED
- 3 SET button
- 4 Recommended torque for central screw M5 (SW 4) 3.0 <sup>+0.5</sup> Nm (tapered shaft)



# Absolute encoders - singleturn

**Standard  
optical**

**5852 / 5872 (shaft / hollow shaft)**

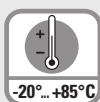
**Parallel, highspeed**



The singleturn encoders 5852 and 5872 with parallel interface and optical technology achieve a very high refresh rate of the position data of 40 kHz with a resolution of max. 14 bits.



High rotational speed



Temperature range  
-20°...+85°C



High protection level  
IP



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Optical sensor

## Adaptable

- Supply voltage 5 V DC or 10 ... 30 V DC.
- Cable or connector M23.

## Fast

- Refresh rate of the position data 40 kHz.

**Order code  
Shaft version**

**8.5852 . XX XX . XXX 1**  
Type      a      b      c      d

### a Flange, shaft

12 = clamping flange, ø 58 mm [2.28"]  
with shaft 10 x 20 mm [0.39 x 0.79"]  
21 = synchro flange, ø 58 mm [2.28"]  
with shaft 6 x 10 mm [0.24 x 0.39"]

### b Interface / supply voltage

1 = parallel (CMOS-TTL) / 5 V DC  
3 = parallel / 10 ... 30 V DC

### c Type of connection

1 = axial cable, 1 m [3.28'] PVC  
A = axial cable, special length PVC \*)  
2 = radial cable, 1 m [3.28'] PVC  
B = radial cable, special length PVC \*)  
3 = axial M23 connector, 17-pin  
5 = radial M23 connector, 17-pin

\*) Available special lengths (connection types A, B):  
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']  
order code expansion .XXXX = length in dm  
ex.: 8.5852.121A.E031.0030 (for cable length 3 m)

### d Code type and division

E03 = 360 gray-excess  
E01 = 1000 gray-excess  
E14 = 1440 gray-excess  
E20 = 2000 gray-excess  
G10 = 1024 (10 bit) gray  
G12 = 4096 (12 bit) gray  
G13 = 8192 (13 bit) gray  
G14 = 16384 (14 bit) gray

### Optional on request

- other code types
- other divisions

# Absolute encoders - singleturn

Standard optical	5852 / 5872 (shaft / hollow shaft)	Parallel, highspeed
<b>Order code</b> <b>Hollow shaft</b>	<b>8.5872</b> . <b>XXXXX</b> . <b>XXX 1</b> Type	
<b>a</b> Flange 1 = with spring element, short 3 = with stator coupling, ø 65 mm [2.56"]	<b>c</b> Interface / supply voltage 1 = parallel (CMOS-TTL) / 5 V DC 3 = parallel / 10 ... 30 V DC	<b>e</b> Code type and division E03 = 360 gray-excess E01 = 1000 gray-excess E14 = 1440 gray-excess E20 = 2000 gray-excess G10 = 1024 (10 bit) gray G12 = 4096 (12 bit) gray G13 = 8192 (13 bit) gray G14 = 16384 (14 bit) gray
<b>b</b> Through hollow shaft 6 = ø 10 mm [0.39"] 8 = ø 12 mm [0.47"]	<b>d</b> Type of connection 1 = radial cable, 1 m [3.28'] PVC 2 = radial M23 connector, 17-pin	Optional on request - other code types - other divisions

## Reverse count direction

(Only with output type 3 and up to 13 bit gray code available)

## Normal operation:

Rising code values when shaft turning clockwise (cw). Falling code values when shaft turning counterclockwise (ccw), top view of shaft.

## Reverse operation:

Output MSB inverted (pin 16) instead of output MSB (pin 3) connected. Falling code values when shaft turning clockwise (cw). Rising code values when shaft turning counterclockwise (ccw), top view of shaft.

Mounting accessory for shaft encoders		Order no.
<b>Coupling</b>	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]	<b>8.0000.1102.0606</b>
	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	<b>8.0000.1102.1010</b>
Mounting accessory for hollow shaft encoders Dimensions in mm [inch]		Order no.
<b>Torque pin, ø 4 mm</b> for flange with spring element (flange type 1)	with fixing thread 	<b>8.0010.4700.0000</b>
Cables and connectors		Order no.
<b>Preassembled cables</b>	M23 female connector with coupling nut, 17-pin, ccw single-ended 2 m [6.56'] PVC cable	<b>8.0000.6741.0002</b>
<b>Connectors</b>	M23 female connector with coupling nut, 17-pin, ccw	<b>8.0000.5042.0000</b>

Further Kübler accessories can be found at: /accessories  
Further Kübler cables and connectors can be found at: /connection-technology



# Absolute encoders - singleturn

<b>Standard optical</b>	<b>5852 / 5872 (shaft / hollow shaft)</b>	<b>Parallel, highspeed</b>
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## Technical data

Mechanical characteristics			Approvals	
<b>Maximum speed</b>	shaft version	12000 min <sup>-1</sup>	<b>UL compliant</b> in accordance with	File no. E224618
	hollow shaft version	6000 min <sup>-1</sup> 1)		
<b>Mass moment of inertia</b>	shaft version	approx. 1.8 x 10 <sup>-6</sup> kgm <sup>2</sup>	<b>CE compliant</b> in accordance with	
	hollow shaft version	approx. 6 x 10 <sup>-6</sup> kgm <sup>2</sup>		
<b>Starting torque</b> at 20 °C [68 °F]	shaft version	< 0.01 Nm	EMC Directive	2014/30/EU
	hollow shaft version	< 0.05 Nm		
<b>Load capacity of shaft</b>	radial	80 N	RoHS Directive	2011/65/EU
	axial	40 N		
<b>Weight</b>		approx. 0.4 kg [14.11 oz]		
<b>Protection</b> acc. to EN 60529	shaft version	IP65		
	hollow shaft version	IP66		
<b>Working temperature range</b>		-20 °C ... +85 °C 2) [-4 °F ... +185 °F] 2)		
<b>Material</b>	shaft / hollow shaft	stainless steel		
<b>Shock resistance</b> acc. EN 60068-2-27		2500 m/s <sup>2</sup> , 6 ms		
<b>Vibration resistance</b> acc. EN 60068-2-6		100 m/s <sup>2</sup> , 10 ... 2000 Hz		

Electrical characteristics (parallel interface)		
<b>Supply voltage</b> (+V)	5 V DC (±5 %)	10 ... 30 V DC
<b>Output driver</b>	CMOS-TTL	Push-pull
<b>Power consumption</b> (no load)	typ.	40 mA
	max.	75 mA
<b>Permissible load / channel</b>	max. +0.5 / -2.0 mA	max. +/- 10 mA
<b>Refresh rate of the position data</b>	40000/s	40000/s
<b>Signal level</b>	HIGH	min. 3.4 V
	LOW	max. 0.3 V
<b>Rising edge time</b> t <sub>r</sub> (without cable)	max. 0.2 µs	max. 1µs
<b>Falling edge time</b> t <sub>f</sub> (without cable)	max. 0.2 µs	max. 1µs
<b>Short circuit proof outputs</b> 3)	yes	yes
<b>Reverse polarity protection of the supply voltage</b>	no	yes

## Terminal assignment

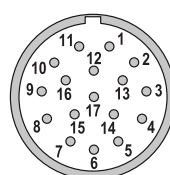
Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)																
1, 3	5852: 1, 2, A, B	Signal	0 V	+V	1	2	3	4	5	6	7	8	9	10	11	12	13	14 (MSB)
	5872: 1	Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY PK	RD BU	WH GN	BN GN	WH YE	YE BN

Interface	Type of connection	M23 connector, 17-pin																
1, 3	5852: 3, 5	Signal	0 V	+V	1	2	3	4	5	6	7	8	9	10	11	12	13	14 (MSB)
	5872: 2	Pin:	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16

+V: Supply voltage encoder +V DC  
0 V: Supply voltage encoder ground GND (0 V)  
Signal : 1 = MSB; 2 = MSB-1; 3 = MSB-2 usw.  
MSB: MSB inverted  
PH ⊥: Plug connector housing (shield)

Top view of mating side, male contact base



M23 connector, 17-pin (parallel)

1) For continuous operation max. 1500 min<sup>-1</sup>.  
2) 70 °C [158 °F] for 14 bit version.  
3) If supply voltage +V correctly applied.

# Absolute encoders - singleturn

Standard optical	5852 / 5872 (shaft / hollow shaft)	Parallel, highspeed
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## Dimensions shaft version

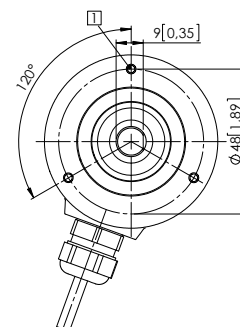
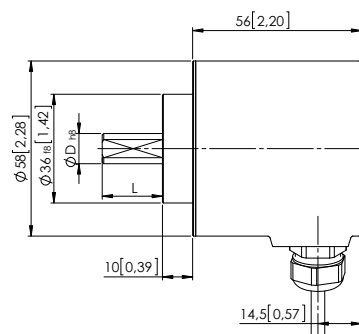
Dimensions in mm [inch]

Clamping flange,  $\varnothing 58$  [2.28]

with shaft,  $\varnothing 10$  [0.39]

Flange type 12

1 3 x M3, 5 [0.20] deep



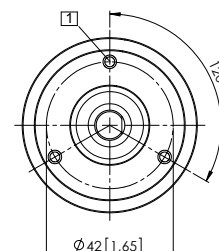
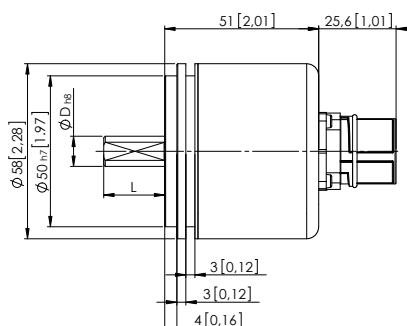
D	Fit	L
6 [0.24]	h8	10 [0.39]
10 [0.39]	f7	20 [0.79]

Synchro flange,  $\varnothing 58$  [2.28]

with shaft,  $\varnothing 6$  [0.24]

Flange type 21

1 3 x M4, 10 [0.39] deep



D	Fit	L
6 [0.24]	h8	10 [0.39]
10 [0.39]	f7	20 [0.79]

## Standard optical

**5852 / 5872 (shaft / hollow shaft)**

## Parallel, highspeed

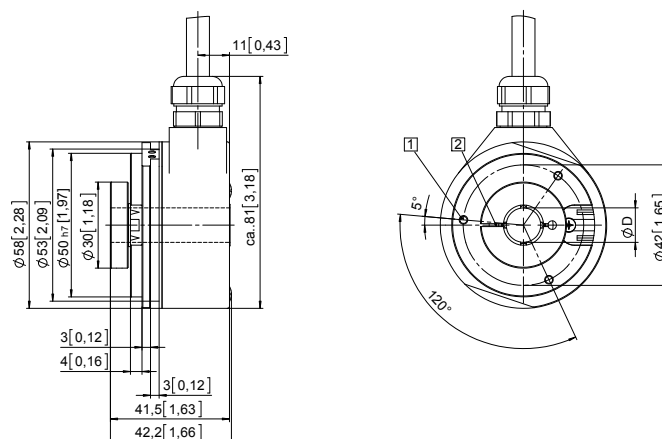
### Dimensions hollow shaft version

Dimensions in mm [inch]

### Flange with spring element, short Flange type 1

- 1 3 x M3, 5 [0.20] deep
- 2 Recommended torque for the clamping ring 0.6 Nm

D	Fit
10 [0.39]	H7
12 [0.47]	H7

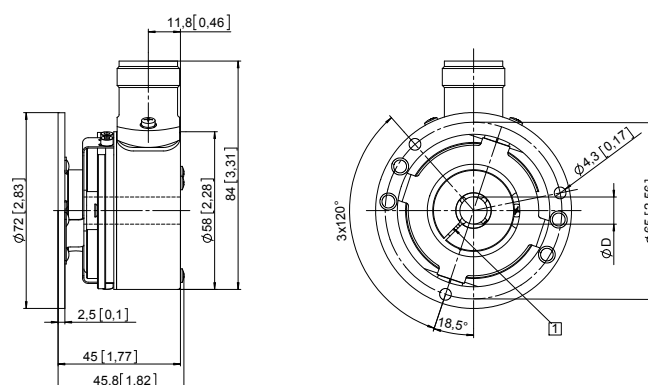


**Flange with stator coupling, ø 65 [2.56]**

### Flange type 3

- 1** Recommended torque for the clamping ring 0.6 Nm

D	Fit
10 [0.39]	H7
12 [0.47]	H7



# Absolute encoders - singleturn

Standard  
optical

Sendix 5858 / 5878 (shaft / hollow shaft)

PROFINET IO



The singleturn encoders 5858 and 5878 with PROFINET interface and optical sensor technology are ideal for use in all applications with a PROFINET interface.

The encoder supports the IRT mode and is therefore ideal for real-time applications.



Safety-Lock™



High rotational speed



Temperature range



High protection level



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Short-circuit proof



Reverse polarity protection



Optical sensor



Surface protection salt spray-tested optional

## Reliable

- Ideally suited for all PROFINET applications thanks to the use of encoder profile 4.1.
- Perfect for use in harsh outdoor environments, as a result of IP67 protection and rugged housing construction.

## Flexible

- Easy setting of a preset value using a control bit (telegram 860).
- IRT-Mode.
- Cycle time  $\geq 1$  ms.
- Firmware updater allows for easy expansion of characteristics without having to disassemble the encoder.

Order code  
Shaft version

8.5858

Type

.XXC2.C212

a b c d e

### a Flange

- 1 = clamping flange, IP65  $\varnothing$  58 mm [2.28"]  
 3 = clamping flange, IP67  $\varnothing$  58 mm [2.28"]  
 2 = synchro flange, IP65  $\varnothing$  58 mm [2.28"]  
 4 = synchro flange, IP67  $\varnothing$  58 mm [2.28"]  
 5 = square flange, IP65  $\square$  63.5 mm [2.5"]  
 7 = square flange, IP67  $\square$  63.5 mm [2.5"]

### b Shaft ( $\varnothing \times L$ ), with flat

- 1 = 6 x 10 mm [0.24 x 0.39"]<sup>1)</sup>  
 2 = 10 x 20 mm [0.39 x 0.79"]<sup>2)</sup>  
 3 = 1/4" x 7/8"  
 4 = 3/8" x 7/8"

### c Interface / supply voltage

C = PROFINET IO / 10 ... 30 V DC

### e Field bus profile

C2 = PROFINET IO

### d Type of connection

removable bus terminal cover  
 2 = 3 x M12 connector, 4-pin

### Optional on request

- Ex 2/22
- surface protection salt spray tested

Order code  
Hollow shaft

8.5878

Type

.XXC2.C212

a b c d e

### a Flange

- 1 = with spring element, long, IP65  
 2 = with spring element, long, IP67  
 3 = with stator coupling, IP65  $\varnothing$  65 mm [2.56"]  
 4 = with stator coupling, IP67  $\varnothing$  65 mm [2.56"]  
 5 = with stator coupling, IP65  $\varnothing$  63 mm [2.48"]  
 6 = with stator coupling, IP67  $\varnothing$  63 mm [2.48"]

### b Blind hollow shaft

- (insertion depth max. 30 mm [1.18"])  
 3 =  $\varnothing$  10 mm [0.39"]  
 4 =  $\varnothing$  12 mm [0.47"]  
 5 =  $\varnothing$  14 mm [0.55"]  
 6 =  $\varnothing$  15 mm [0.59"]  
 8 =  $\varnothing$  3/8"  
 9 =  $\varnothing$  1/2"

### c Interface / supply voltage

C = PROFINET IO / 10 ... 30 V DC

### e Field bus profile

C2 = PROFINET IO

### d Type of connection

removable bus terminal cover  
 2 = 3 x M12 connector, 4-pin

### Optional on request

- Ex 2/22
- surface protection salt spray tested


1) Preferred type only in conjunction with flange type 2.

2) Preferred type only in conjunction with flange type 1.

## Absolute encoders - singleturn

<b>Standard optical</b>	<b>Sendix 5858 / 5878 (shaft / hollow shaft)</b>	<b>PROFINET IO</b>
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Mounting accessory for shaft encoders		Order no.
Coupling	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]	8.0000.1102.0606
	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1102.1010

Mounting accessory for hollow shaft encoders		Dimensions in mm [inch]	Order no.
<b>Torque pin, <math>\varnothing</math> 4 mm</b>	with fixing thread		<b>8.0010.4700.0000</b>
for flange with spring element (flange type 1 + 2)			

Cables and connectors			Order no.
Preassembled cables	M12 male connector with external thread, 4-pin, D coded, straight single-ended 2 m [6.56'] PUR cable	Bus IN + Bus OUT	05.00.6031.4411.002M
	M12 female connector with coupling nut, 4-pin, A coded, straight single-ended 2 m [6.56'] PUR cable	supply voltage	05.00.6061.6211.002M
Connectors	M12 male connector with external thread, 4-pin, D coded, straight (metal)	Bus IN + Bus OUT	05.WASCSY4S
	M12 female connector with coupling nut, 4-pin, A coded, straight (plastic)	supply voltage	05.B8141-0

Further Kübler accessories can be found at: [/accessories](#)  
Further Kübler cables and connectors can be found at: [/connection-technology](#)

## Technical data

Mechanical characteristics		
<b>Maximum speed</b>	IP65 up to 70 °C [158 °F]	9000 min <sup>-1</sup> , 7000 min <sup>-1</sup> (continuous)
	IP65 up to T <sub>max</sub>	7000 min <sup>-1</sup> , 4000 min <sup>-1</sup> (continuous)
	IP67 up to 70 °C [158 °F]	8000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous)
	IP67 up to T <sub>max</sub>	6000 min <sup>-1</sup> , 3000 min <sup>-1</sup> (continuous)
<b>Starting torque</b> - at 20 °C [68 °F]	IP65	< 0.01 Nm
	IP67	< 0.05 Nm
<b>Mass moment of inertia</b>	shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
	hollow shaft version	6.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
<b>Load capacity of shaft</b>	radial	80 N
	axial	40 N
<b>Weight</b>		approx. 0.50 kg [17.64 oz]
<b>Protection</b> acc. to EN 60529		
	housing side	IP67
	shaft side	IP65, opt. IP67
<b>Working temperature range</b>		-40 °C ... +85 °C [-40 °F ... +185 °F]
<b>Material</b>	shaft/hollow shaft	stainless steel
	flange	aluminum
	housing	zinc die-cast
<b>Shock resistance</b> acc. to EN 60068-2-27		2500 m/s <sup>2</sup> , 6 ms
<b>Vibration resistance</b> acc. to EN 60068-2-6		100 m/s <sup>2</sup> , 55 ... 2000 Hz

Electrical characteristics	
Supply voltage	10 ... 30 V DC
Power consumption (no load)	max. 200 mA
Reverse polarity protection of the supply voltage	yes

Interface characteristics PROFINET IO	
Resolution	1 ... 65535 (16 bit), scalable default: 8192 (13 bit)
Protocol	PROFINET IO

Link 1 and 2, LED (green / yellow)		
Two colored	green	active link
	yellow	data transfer

<b>Error LED (red) / PWR LED (green)</b>
Functionality see manual

Approvals	
<b>UL compliant</b> in accordance with	File no. E224618
<b>CE compliant</b> in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU (for Ex 2/22 variants)

# Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	PROFINET IO
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## General information about PROFINET IO

The PROFINET encoder implements the encoder profile 4.1. (according to the specification Encoder Version 4.1 Dec 2008")

It permits scaling and preset values, as well as many other additional parameters to be programmed via the PROFINET bus.

When switching on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure, or taken over by the controller in the start-up phase.

Position, speed and many other states of the encoder can be transmitted.




## PROFINET IO

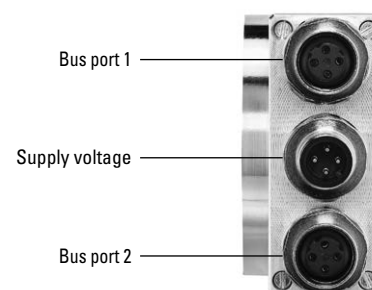
The complete encoder profile according to profile encoder version 4.1 as well as the identification & maintenance functionality version 1.16 has been implemented. IM blocks 0, 1, 2, 3 and 4 are supported.

The **M**edia **R**edundancy **P**rotocol is implemented here.

Basically, the advantage of MRP is that the functionality of the components, which are wired in a ring structure, is maintained in case of a failure or of a breakage of the wires in any location.

## Terminal assignment bus

Interface	Type of connection	Function	M12 connector, 4-pin					
C	2 (3 x M12 connector)	Bus port 1	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	 D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	
		Power supply	Signal:	Voltage +	—	Voltage —	—	
			Abbreviation:	+ V	—	0 V	—	
			Pin:	1	2	3	4	
		Bus port 2	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	 D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	



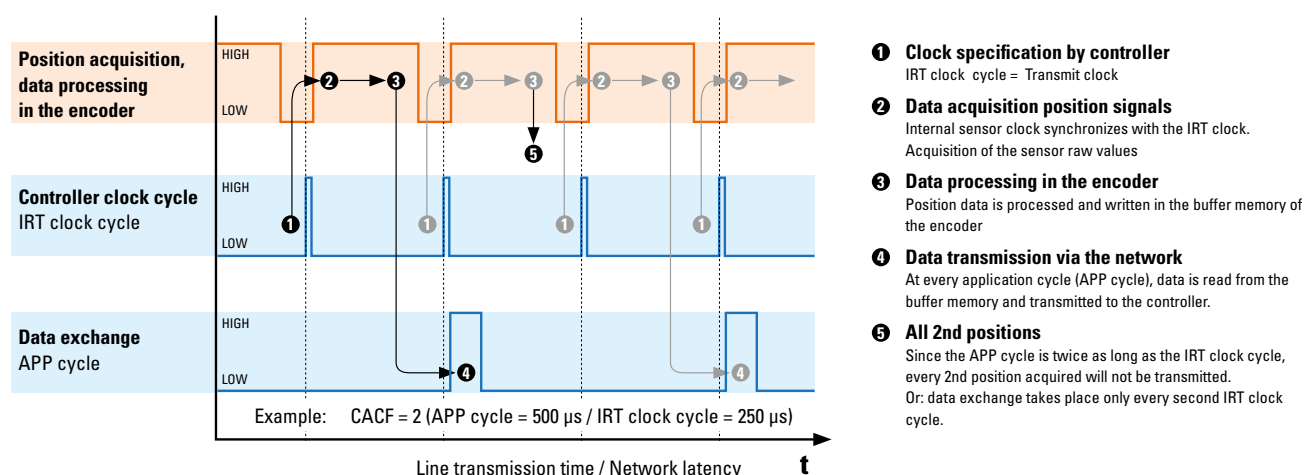
<b>Standard optical</b>	<b>Sendix 5858 / 5878 (shaft / hollow shaft)</b>	<b>PROFINET IO</b>
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## Technology in detail

### Clock synchronicity – Isochronous Real Time (IRT) in position sensor technology

In general, for time-critical applications, focus is set on very short sensor cycle times. However, in order to achieve high control performance, simply accelerating data acquisition and processing by shortest cycle times is not sufficient. All sensors and actuators are to operate according to the same clock.

This is achieved thanks to a clock used for the whole network, defined by the controller. This transmit clock cycle (IRT clock) is however not necessarily the clock cycle used for process data exchange. Another cycle (application cycle) is used for this purpose, which can also be defined by the customer controller. The illustration below represents the connection between the different clock cycles.



When receiving the IRT clock signal, the sensor starts reading its current measured point. This raw value is processed internally (e.g. scaling, speed calculation, etc.) and stored in a buffer memory.

The buffer memory is read at every application cycle. If it contains a value, this value is transmitted to the controller via the network.

If the application cycle is a multiple of the IRT clock cycle, it may happen that the buffered process data is not sent directly, but is overwritten, because, even though this data is acquired with every IRT clock cycle, it is sent only with every application cycle.

The ratio between application cycle and IRT clock cycle represents the CACF (Controller Application Cycle Factor).

In this example, the CACF = 2. This indicates that only every 2nd acquired position will be transmitted to the controller.

The described methodology guarantees a determinism: since the controller defines a clock cycle for the whole network, this allows ensuring that all measured values transmitted by the sensors to the controller are never older than the selected IRT cycle! Therefore, all downstream actuators can always be regulated on the basis of the latest available measured values.

# Absolute encoders - singleturn

## Standard optical

## Sendix 5858 / 5878 (shaft / hollow shaft)

## PROFINET IO

### Dimensions shaft version, with removable bus terminal cover

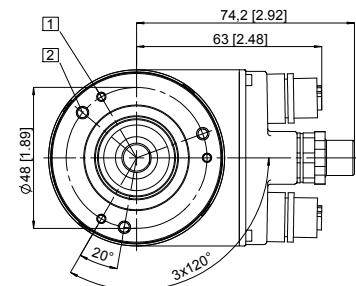
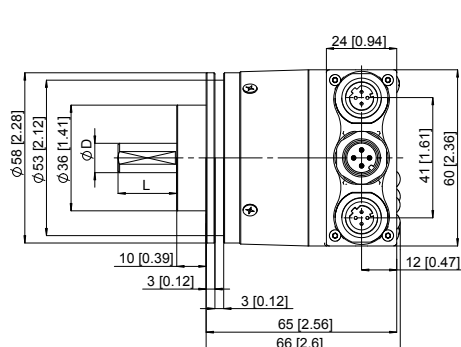
Dimensions in mm [inch]

#### Clamping flange, $\varnothing$ 58 [2.28]

#### Flange type 1 and 3

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"

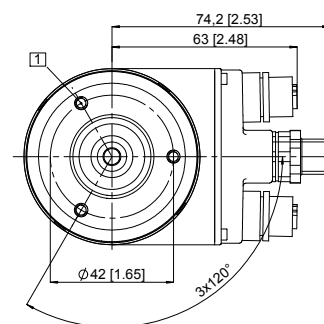
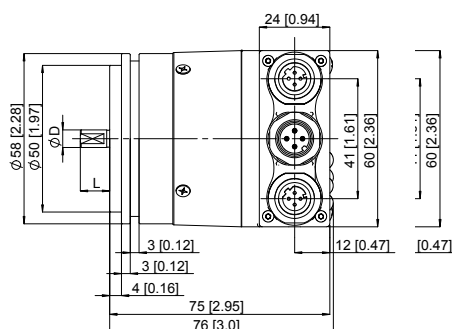


#### Synchro flange, $\varnothing$ 58 [2.28]

#### Flange type 2 and 4

- 1 3 x M4, 6 [0.24] deep

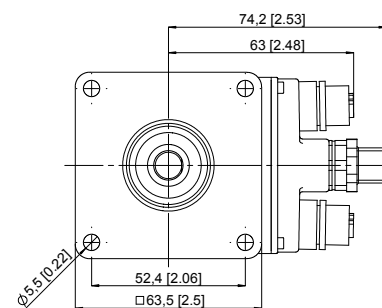
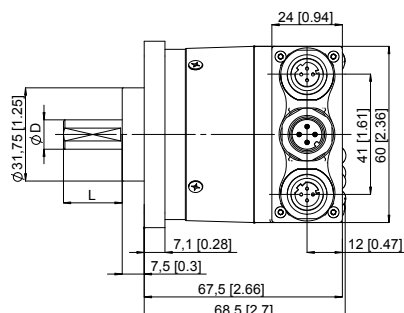
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



#### Square flange, $\square$ 63.5 [2.5]

#### Flange type 5 and 7

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"





# Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	PROFINET IO
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## Dimensions hollow shaft version (blind hollow shaft), with removable bus terminal cover

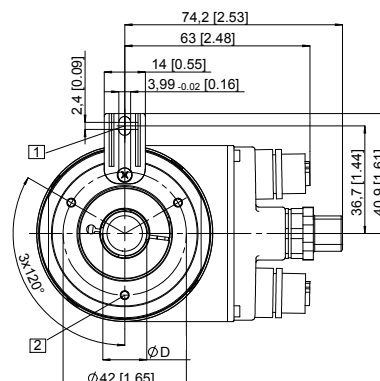
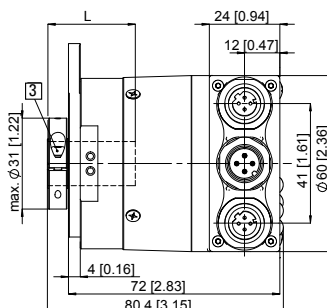
Dimensions in mm [inch]

### Flange with spring element, long Flange type 1 and 2

- 1 Slot spring element, recommendation: cylindrical pin DIN 7,  $\varnothing 4$  [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

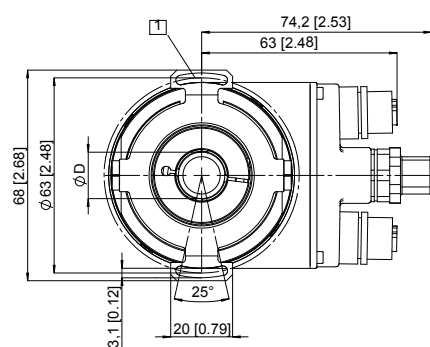
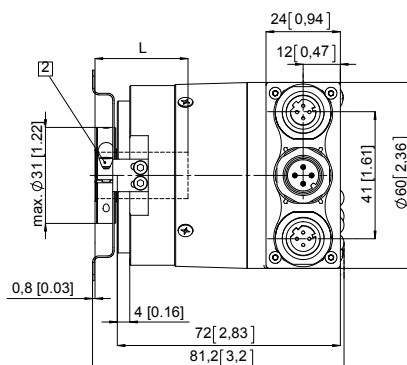


### Flange with stator coupling, $\varnothing 63$ [2.48] Flange type 5 and 6

- 1 Fixing screws DIN 912 M3 x 8 (washer included in delivery)
- 2 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

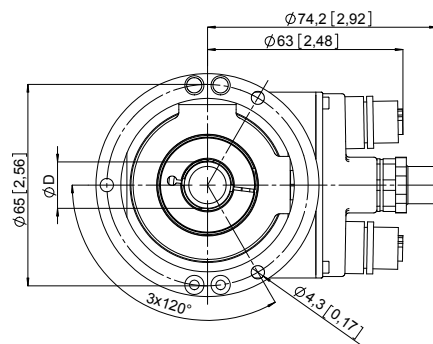
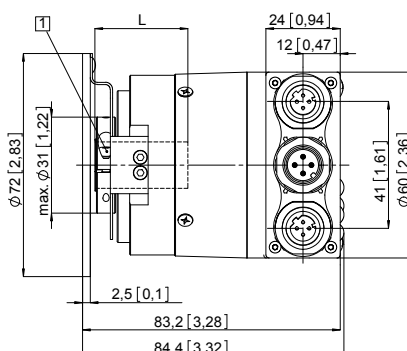


### Flange with stator coupling, $\varnothing 65$ [2.56] Flange type 3 and 4

- 1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



# Absolute encoders - singleturn

**Standard optical**

**Sendix 5858 / 5878 (shaft / hollow shaft)**

**CANopen**



The singleturn encoders 5858 and 5878 with CANopen interface and optical sensor technology are ideal for use in all CANopen applications.

They offer a maximum resolution of 16 bits, divided over 360°. These encoders are available with blind hollow shaft up to 15 mm.



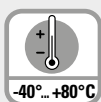
**CANopen**



Safety-Lock™



High rotational speed



Temperature range  
-40°C...+80°C



High protection level  
IP



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Magnetic field proof



Reverse polarity protection



Optical sensor



Surface protection  
salt spray-tested  
optional

## Reliable

- Tried-and-tested in applications with the highest demands, such as in mobile automation or medical technology.
- Ideal for use outdoors thanks to IP67 protection and wide temperature range from -40 °C up to +80 °C.

## Flexible

- Node address can be set via rotary switches or software.
- Baud rate and termination can be set via DIP switches or software.
- With bus terminal cover or fixed connection, as well as M12 connectors or cable connection.

## Order code Shaft version

**8.5858**

Type

**. XX 2X . 21 1 X**  
a b c d e f

### a Flange

- 1** = clamping flange, IP65 ø 58 mm [2.28"]  
**3** = clamping flange, IP67 ø 58 mm [2.28"]  
**2** = synchro flange, IP65 ø 58 mm [2.28"]  
**4** = synchro flange, IP67 ø 58 mm [2.28"]  
**5** = square flange, IP65 □ 63.5 mm [2.5"]  
**7** = square flange, IP67 □ 63.5 mm [2.5"]

### b Shaft (ø x L), with flat

- 1** = 6 x 10 mm [0.24 x 0.39"]<sup>1)</sup>  
**2** = 10 x 20 mm [0.39 x 0.79"]<sup>2)</sup>  
**3** = 1/4" x 7/8"  
**4** = 3/8" x 7/8"

### c Interface / supply voltage

- 2** = CANopen DS301 V4.02 / 10 ... 30 V DC

### d Type of connection

- removable bus terminal cover  
**1** = radial cable gland  
**2** = 2 x M12 connector, 5-pin  
*Fixed connection without bus terminal cover*  
**A** = radial cable, 2 m [6.56'] PVC  
**B** = radial cable, special length PVC \*)  
**E** = 1 x radial M12 connector, 5-pin  
**F** = 2 x radial M12 connector, 5-pin  
**I** = 1 x radial M23 connector, 12-pin  
**J** = 2 x radial M23 connector, 12-pin  
 \*) Available special lengths (connection type B):  
 3, 5, 8, 10, 15 m [9.84, 16.40, 26.25, 32.80, 49.21']  
 order code expansion .XXXX = length in dm  
 ex.: 8.5858.112B.2113.0030 (for cable length 3 m)

### e Fieldbus profile

- 21** = CANopen

### f Options (service)

- 2** = no options  
**3** = SET button

### Optional on request

- Ex 2/22<sup>3)</sup>
- surface protection salt spray tested

1) Preferred type only in conjunction with flange type 2.  
 2) Preferred type only in conjunction with flange type 1.

3) For the cable connection type, cable material PUR.

# Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	CANopen
Order code Hollow shaft	8.5878 . XX2X . 211X Type a b c d e i	
<b>a Flange</b> 1 = with spring element, long, IP65 2 = with spring element, long, IP67 3 = with stator coupling, IP65 ø 65 mm [2.56"] 4 = with stator coupling, IP67 ø 65 mm [2.56"] <b>5 = with stator coupling, IP65 ø 63 mm [2.48"]</b> 6 = with stator coupling, IP67 ø 63 mm [2.48"]  <b>b Blind hollow shaft</b> (insertion depth max. 30 mm [1.18"]) 3 = ø 10 mm [0.39"] <b>4 = ø 12 mm [0.47"]</b> 5 = ø 14 mm [0.55"] 6 = ø 15 mm [0.59"] 8 = ø 3/8" 9 = ø 1/2"  <b>c Interface / supply voltage</b> <b>2 = CANopen DS301 V4.02 / 10 ... 30 V DC</b>	<b>d Type of connection</b> removable bus terminal cover 1 = radial cable gland <b>2 = 2 x M12 connector, 5-pin</b> Fixed connection without bus terminal cover A = radial cable, 2 m [6.56'] PVC B = radial cable, special length PVC *) E = 1 x radial M12 connector, 5-pin F = 2 x radial M12 connector, 5-pin I = 1 x radial M23 connector, 12-pin J = 2 x radial M23 connector, 12-pin  *) Available special lengths (connection type B): 3, 5, 8, 10, 15 m [9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.5878.542B.2113.0030 (for cable length 3 m)	<b>e Fieldbus profile</b> <b>21 = CANopen</b>  <b>i Options (service)</b> 2 = no options <b>3 = SET button</b>  Optional on request - Ex 2/22 <sup>1)</sup> - surface protection salt spray tested

Mounting accessory for shaft encoders		Order no.
<b>Coupling</b>	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]	8.0000.1102.0606
	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1102.1010
Mounting accessory for hollow shaft encoders Dimensions in mm [inch]		Order no.
<b>Torque pin, ø 4 mm</b> for flange with spring element (flange type 1)	with fixing thread 	8.0010.4700.0000
Cables and connectors		Order no.
<b>Preassembled cables</b>	M12 female connector with coupling nut, 5-pin, A coded, straight – Bus in single-ended 5 m [16.40'] PVC cable	05.00.6091.A211.005M
	M12 male connector with external thread, 5-pin, A coded, straight – Bus out single-ended 5 m [16.40'] PVC cable	05.00.6091.A411.005M
<b>Connectors</b>	M12 female connector with coupling nut, 5-pin, A coded, straight (metal) – Bus in	8.0000.5116.0000
	M12 male connector with external thread, 5-pin, A coded, straight (metal) – Bus out	8.0000.5111.0000

Further Kübler accessories can be found at: [/accessories](#)  
 Further Kübler cables and connectors can be found at: [/connection-technology](#)

1) For the cable connection type, cable material PUR.

# Absolute encoders - singleturn

<b>Standard optical</b>	<b>Sendix 5858 / 5878 (shaft / hollow shaft)</b>	<b>CANopen</b>
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## Technical data

Mechanical characteristics			Electrical characteristics	
<b>Maximum speed</b>			<b>Supply voltage</b>	10 ... 30 V DC
	IP65 up to 70 °C [158 °F]	9000 min <sup>-1</sup> , 7000 min <sup>-1</sup> (continuous)	<b>Power consumption (no load)</b>	max. 90 mA
	IP65 up to T <sub>max</sub>	7000 min <sup>-1</sup> , 4000 min <sup>-1</sup> (continuous)	<b>Reverse polarity protection of the supply voltage</b>	yes
	IP67 up to 70 °C [158 °F]	8000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous)		
	IP67 up to T <sub>max</sub>	6000 min <sup>-1</sup> , 3000 min <sup>-1</sup> (continuous)		
<b>Starting torque - at 20 °C [68 °F]</b>				
	IP65	< 0.01 Nm		
	IP67	< 0.05 Nm		
<b>Mass moment of inertia</b>				
	shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup>		
	hollow shaft version	6.0 x 10 <sup>-6</sup> kgm <sup>2</sup>		
<b>Load capacity of shaft</b>				
	radial	80 N		
	axial	40 N		
<b>Weight</b>				
	with bus terminal cover	approx. 0.53 kg [18.69 oz]		
	with fixed connection	approx. 0.50 kg [17.64 oz]		
<b>Protection acc. to EN 60529</b>				
	housing side	IP67		
	shaft side	IP65, opt. IP67		
<b>Working temperature range</b>				
		-40 °C ... +80 °C [-40 °F ... +176 °F] <sup>1)</sup>		
<b>Material</b>				
	shaft/hollow shaft	stainless steel		
	flange	aluminum		
	housing	zinc die-cast		
	cable	PVC (PUR for Ex 2/22)		
<b>Shock resistance acc. to EN 60068-2-27</b>				
		2500 m/s <sup>2</sup> , 6 ms		
<b>Vibration resistance acc. to EN 60068-2-6</b>				
		100 m/s <sup>2</sup> , 55 ... 2000 Hz		

## General information about CANopen

The CANopen encoders support the latest CANopen communication profile according to DS301 V4.02. In addition, device specific profiles such as encoder profile DS406 V3.2 are available.

The following operating modes may be selected: Polled Mode, Cyclic Mode, Sync Mode and a High Resolution Sync Protocol. Moreover, scale factors, preset values, limit switch values and many other additional parameters can be programmed via the CAN bus.

When switching the device on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure.

The following output values may be combined in a freely variable way as PDO (PDO mapping): **position, speed, acceleration** as well as the **status of the working area**.

As competitively priced alternatives, encoders are also available with a connector or a cable connection, where the device address and baud rate can be changed and configured by means of the software. The models with bus terminal cover and integrated T-coupler allow for extremely simple installation: the bus and supply voltage can be easily connected via M12 connectors. The device address can be set via 2 rotary hex switches. Furthermore, another DIP switch allows for the setting of the baud rate and switching on a termination resistor. Three LEDs located on the back indicate the operating or fault status of the CAN bus, as well as the status of an internal diagnostic.

## CANopen communication profile DS301 V4.02

Among others, the following functionality is integrated.

Class C2 functionality

- NMT slave.
- Heartbeat protocol.
- High resolution sync protocol.
- Identity object.
- Error behavior object.
- Variable PDO mapping self-start programmable (power on to operational), 3 Sending PDO's.
- Node address, baud rate and CANbus.
- Programmable termination.

## CANopen encoder profile DS406 V3.2

The following parameters can be programmed:

- Event mode.
- Units for speed selectable (steps/sec or min<sup>-1</sup>).
- Factor for speed calculation (e.g. circumference of measuring wheel).
- Integration time for the speed value from 1 ... 32.
- 2 working areas with 2 upper and lower limits and the corresponding output states.
- Variable PDO mapping for position, speed, work area status.
- Extended failure management for position sensing with integrated temperature control.
- User interface with visual display of bus and failure status - 3 LED's.
- Optional - 32 CAMs programmable.
- Customer-specific memory - 16 Bytes.
- "Watchdog controlled" device.

All profiles stated here: key-features

The object 6003h "Preset" is assigned to an integrated key, accessible from the outside.

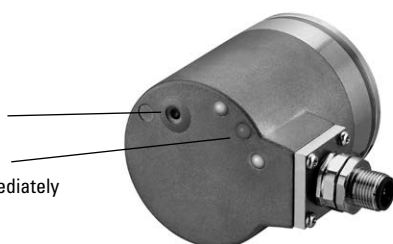
1) Cable version: -30 °C ... +75 °C [-22 °F ... +167 °F].

## Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	CANopen
<b>SET button (zero or defined value, option)</b> Protection against accidental activation. Button can only be operated with a ball-pen or pencil.		
<b>Diagnostic LED (yellow)</b> <b>LED is ON with the following fault conditions</b> sensor error (internal code or LED error), voltage too low, over-temperature		
<b>Approvals</b> <b>UL compliant</b> in accordance with      File no. E224618 <b>CE compliant</b> in accordance with EMC Directive      2014/30/EU RoHS Directive      2011/65/EU ATEX Directive      2014/34/EU (for Ex 2/22 variants)		

**SET button**  
for fast, simple  
on-site start-up

**Green, red, yellow LEDs**  
Fault-free operation immediately  
visible on the bus.



# Absolute encoders - singleturn

<b>Standard optical</b>	<b>Sendix 5858 / 5878 (shaft / hollow shaft)</b>	<b>CANopen</b>
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## Terminal assignment

Interface	Type of connection	Cable gland (bus terminal cover with terminal box)									
2	1	Signal:	Bus OUT					Bus IN			
			CAN_GND	CAN_L	CAN_H	0 V supply voltage	+V supply voltage	0 V supply voltage	+V supply voltage	CAN_L	CAN_H
		Abbreviation:	CG	CL	CH	0 V	+V	0 V	+V	CL	CH

Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)									
2	A, B	Signal:	Bus IN								
			0 V supply voltage	+V supply voltage	CAN_L	CAN_H	CAN_GND				
		Core color:	WH	BN	YE	GN	GY				

Interface	Type of connection	2 x M12 connector, 5-pin									
2	2, F	Signal:	Bus OUT								
			0 V supply voltage	+V supply voltage	CAN_L	CAN_H	CAN_GND				
		Pin:	3	2	5	4	1				
		Signal:	Bus IN								
			0 V supply voltage	+V supply voltage	CAN_L	CAN_H	CAN_GND				
		Pin:	3	2	5	4	1				

Interface	Type of connection	1 x M12 connector, 5-pin									
2	E	Signal:	Bus IN								
			0 V supply voltage	+V supply voltage	CAN_L	CAN_H	CAN_GND				
		Pin:	3	2	5	4	1				

Interface	Type of connection	2 x M23 connector, 12-pin									
2	J	Signal:	Bus OUT								
			0 V supply voltage	+V supply voltage	CAN_L	CAN_H	CAN_GND				
		Pin:	10	12	2	7	3				
		Signal:	Bus IN								
			0 V supply voltage	+V supply voltage	CAN_L	CAN_H	CAN_GND				
		Pin:	10	12	2	7	3				

Interface	Type of connection	1 x M23 connector, 12-pin									
2	I	Signal:	Bus IN								
			0 V supply voltage	+V supply voltage	CAN_L	CAN_H	CAN_GND				
		Pin:	10	12	2	7	3				

# Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	CANopen
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## Dimensions shaft version, with removable bus terminal cover

Dimensions in mm [inch]

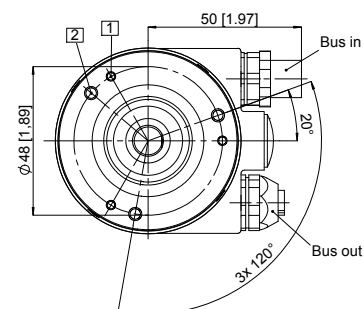
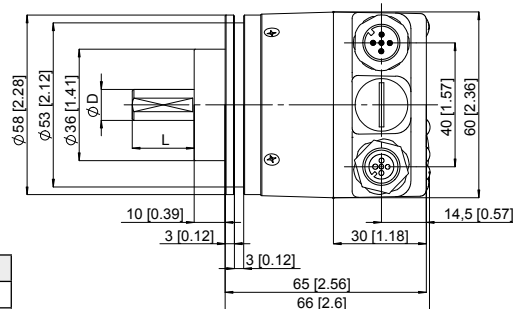
### Clamping flange, $\varnothing 58$ [2.28]

#### Flange type 1 and 3

(drawing with 2 x M12 connector)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



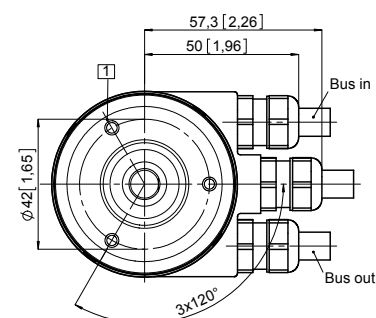
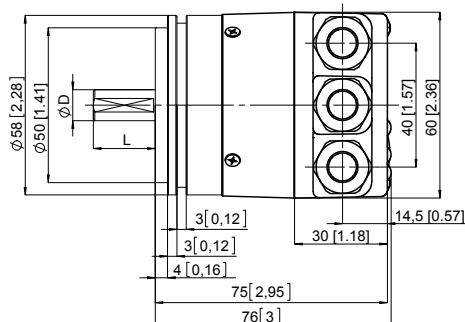
### Synchro flange, $\varnothing 58$ [2.28]

#### Flange type 2 and 4

(drawing with cable)

- 1 3 x M4, 6 [0.24] deep

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"

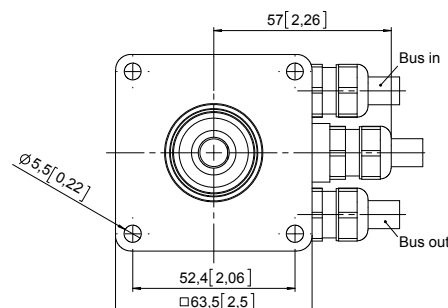
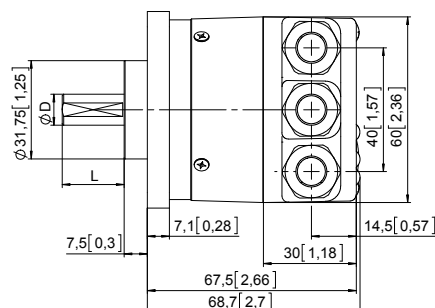


### Square flange, $\square 63.5$ [2.5]

#### Flange type 5 and 7

(drawing with cable)

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



# Absolute encoders - singleturn

## Standard optical

## Sendix 5858 / 5878 (shaft / hollow shaft)

## CANopen

### Dimensions shaft version, with fixed connection

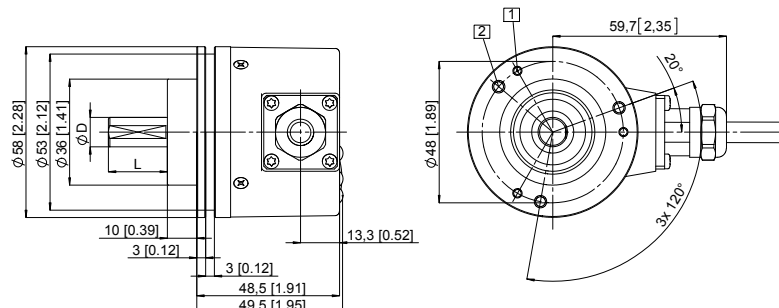
Dimensions in mm [inch]

#### Clamping flange, $\varnothing 58$ [2.28]

##### Flange type 1 and 3

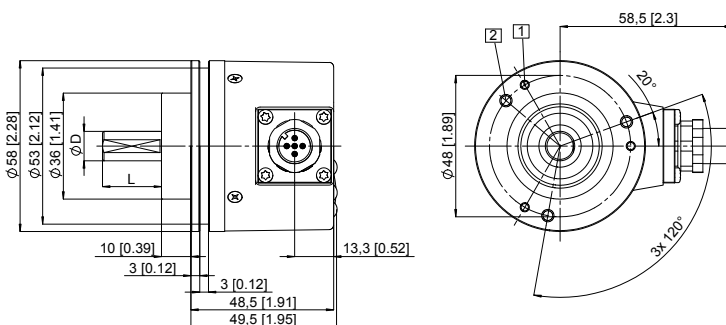
(drawing with cable)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep



(drawing with M12 connector)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep



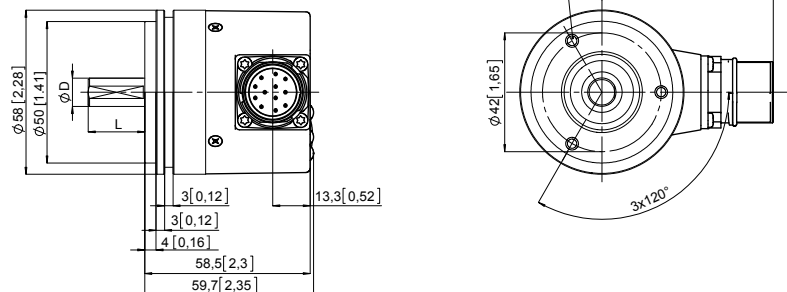
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"

#### Synchro flange, $\varnothing 58$ [2.28]

##### Flange type 2 and 4

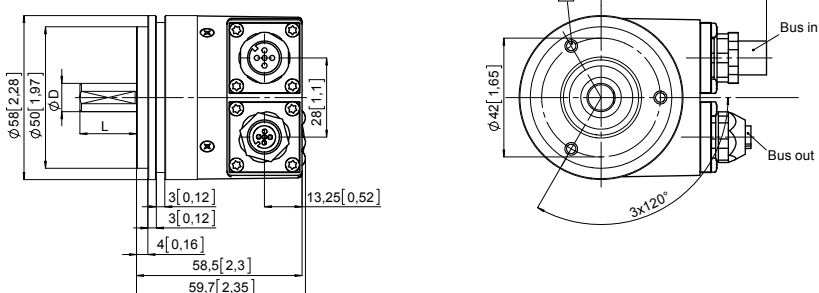
(drawing with M23 connector)

- 1 3 x M4, 6 [0.24] deep



(drawing with M12 connector)

- 1 3 x M4, 6 [0.24] deep

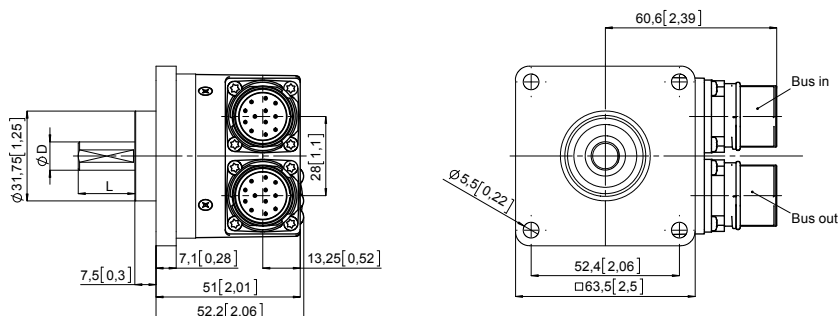


D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"

#### Square flange, $\square 63.5$ [2.5]

##### Flange type 5 and 7

(drawing with 2 x M23 connector)



D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



# Absolute encoders - singleturn

## Standard optical

## Sendix 5858 / 5878 (shaft / hollow shaft)

## CANopen

### Dimensions hollow shaft version (blind hollow shaft), with removable bus terminal cover

Dimensions in mm [inch]

#### Flange with spring element, long

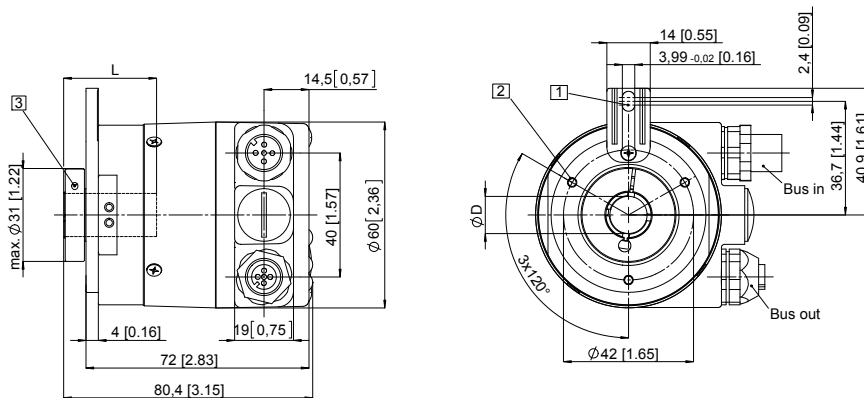
#### Flange type 1 and 2

(drawing with 2 x M12 connector)

- 1 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing$  4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



#### Flange with stator coupling, $\varnothing$ 63 [2.48]

#### Flange type 5 and 6

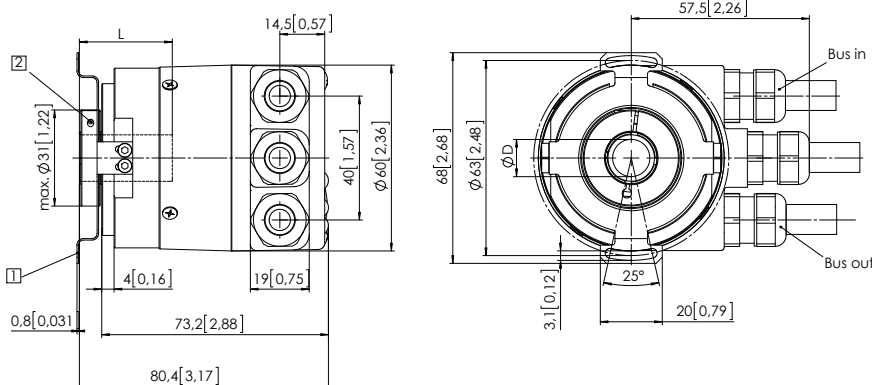
Pitch circle diameter for fixing screws 63 [2.48]

(drawing with cable)

- 1 Fixing screws DIN 912 M3 x 8 (washer included in delivery)
- 2 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



#### Flange with stator coupling, $\varnothing$ 65 [2.56]

#### Flange type 3 and 4

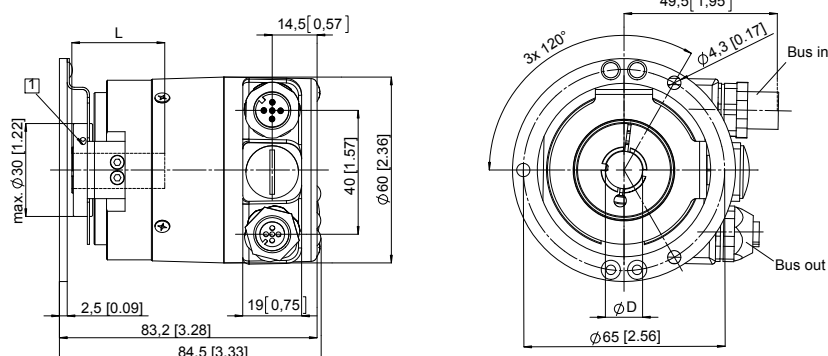
Pitch circle diameter for fixing screws 65 [2.56]

(drawing with 2 x M12 connector)

- 1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



# Absolute encoders - singleturn

## Standard optical

## Sendix 5858 / 5878 (shaft / hollow shaft)

## CANopen

### Dimensions hollow shaft version (blind hollow shaft), with fixed connection

Dimensions in mm [inch]

#### Flange with spring element, long

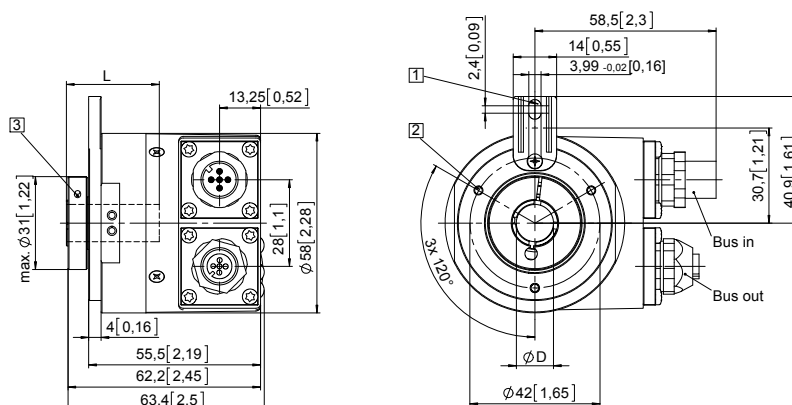
#### Flange type 1 and 2

(drawing with 2 x M12 connector)

- 1 Slot spring element, recommendation: cylindrical pin DIN 7,  $\varnothing$  4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



#### Flange with stator coupling, $\varnothing$ 65 [2.56]

#### Flange type 3 and 4

Pitch circle diameter for fixing screws

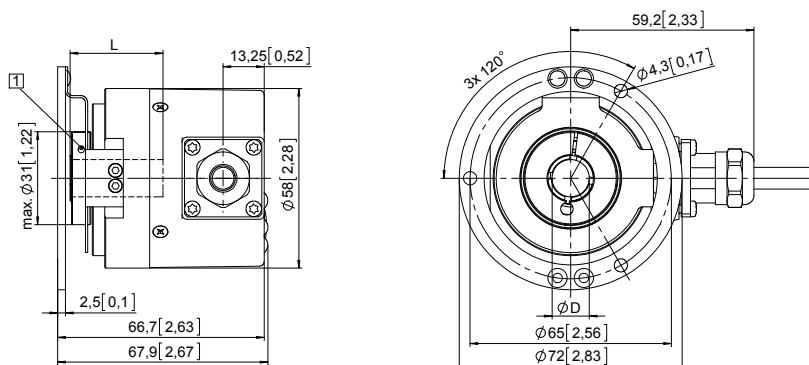
65 [2.56]

(drawing with cable)

- 1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



# Absolute encoders - singleturn

**Standard  
optical**

**Sendix 5858 / 5878 (shaft / hollow shaft)**

**PROFIBUS DP**



The singleturn encoders 5858 and 5878 with Profibus interface and optical sensor technology are the ideal solution for all Profibus applications.

They offer a maximum resolution of 16 bits, divided over 360°. These encoders are available with blind hollow shaft up to 15 mm.



Safety-Lock™



High rotational speed



Temperature range  
-40...+80 °C



High protection level  
IP



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Short-circuit proof



Reverse polarity protection



Optical sensor



Surface protection salt spray-tested optional

## Reliable

- Tried-and-tested in applications with the highest demands, such as in wind energy or mobile automation.
- Ideal for use outdoors thanks to IP67 protection and wide temperature range from -40 °C up to +80 °C.

## Flexible

- Fast, simple, error-free connection using versions with M12 connector.
- Wide-ranging programming options thanks to latest encoder profile.

## Order code Shaft version

**8.5858**

Type

**. XX3X . 311X**

### a Flange

- 1** = clamping flange, IP65 ø 58 mm [2.28"]  
**3** = clamping flange, IP67 ø 58 mm [2.28"]  
**2** = synchro flange, IP65 ø 58 mm [2.28"]  
**4** = synchro flange, IP67 ø 58 mm [2.28"]  
**5** = square flange, IP65 □ 63.5 mm [2.5"]  
**7** = square flange, IP67 □ 63.5 mm [2.5"]

### b Shaft (ø x L), with flat

- 1** = 6 x 10 mm [0.24 x 0.39"]<sup>1)</sup>  
**2** = 10 x 20 mm [0.39 x 0.79"]<sup>2)</sup>  
**3** = 1/4" x 7/8"  
**4** = 3/8" x 7/8"

### c Interface / supply voltage

- 3** = PROFIBUS DP V0  
encoder profile V 1.1, 10 ... 30 V DC

### d Type of connection

- removable bus terminal cover  
**1** = with radial cable gland fitting  
**2** = with 3 x radial M12 connectors

### e Fieldbus profile

- 31** = PROFIBUS DP V0  
encoder profile class 2

### f Options (Service)

- 2** = no option  
**3** = SET button  
Optional on request  
- Ex 2/22  
- surface protection salt spray tested

## Order code Hollow shaft

**8.5878**

Type

**. XX3X . 311X**

### a Flange

- 1** = with spring element, long, IP65  
**2** = with spring element, long, IP67  
**3** = with stator coupling, IP65 ø 65 mm [2.56"]  
**4** = with stator coupling, IP67 ø 65 mm [2.56"]  
**5** = with stator coupling, IP65 ø 63 mm [2.48"]  
**6** = with stator coupling, IP67 ø 63 mm [2.48"]

### b Blind hollow shaft

- (insertion depth max. 30 mm [1.18"])  
**3** = ø 10 mm [0.39"]  
**4** = ø 12 mm [0.47"]  
**5** = ø 14 mm [0.55"]  
**6** = ø 15 mm [0.59"]  
**8** = ø 3/8"  
**9** = ø 1/2"

### c Interface / supply voltage

- 3** = PROFIBUS DP V0  
encoder profile V 1.1, 10 ... 30 V DC

### d Type of connection

- removable bus terminal cover  
**1** = with radial cable gland fitting  
**2** = with 3 x radial M12 connectors

### e Fieldbus profile

- 31** = PROFIBUS DP V0  
encoder profile class 2

### f Options (Service)

- 2** = no option  
**3** = SET button  
Optional on request  
- Ex 2/22  
- surface protection salt spray tested

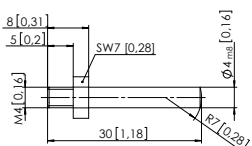
1) Preferred type only in conjunction with flange type 2

2) Preferred type only in conjunction with flange type 1

## Absolute encoders - singleturn

<b>Standard optical</b>	<b>Sendix 5858 / 5878 (shaft / hollow shaft)</b>	<b>PROFIBUS DP</b>
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Mounting accessory for shaft encoders		Order no.
Coupling	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]	8.0000.1102.0606
	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1102.1010

Mounting accessory for hollow shaft encoders		Dimensions in mm [inch]	Order no.
<b>Torque pin, <math>\varnothing</math> 4 mm</b> for flange with spring element (flange type 1)	with fixing thread 		<b>8.0010.4700.0000</b>

Cables and connectors			Order no.
Preassembled cables	M12 female connector with coupling nut, 5-pin, B coded, straight single-ended 5 m [16.40'] PUR cable	Bus in	05.00.6011.3211.005M
	M12 male connector with external thread, 5-pin, B coded, straight single-ended 5 m [16.40'] PUR cable	Bus out	05.00.6011.3411.005M
	M12 female connector with coupling nut, 4-pin, A coded, straight Ende offen 2 m PUR-Kabel	supply voltage	05.00.6061.6211.002M
Connectors	M12 female connector with coupling nut, 5-pin, B coded, straight (metal)	Bus in	05.BMWS 8151-8.5
	M12 male connector with external thread, 5-pin, B coded, straight (metal)	Bus out	05.BMSWS 8151-8.5
	M12 female connector with coupling nut, 4-pin, A coded, straight (plastic)	supply voltage	05.B8141-0

Further Kübler accessories can be found at: [/accessories](#)  
Further Kübler cables and connectors can be found at: [/connection-technology](#)

## Technical data

Mechanical characteristics		
<b>Maximum speed</b>		
IP65 up to 70 °C [158 °F]	9000 min <sup>-1</sup> , 7000 min <sup>-1</sup> (continuous)	
IP65 up to T <sub>max</sub>	7000 min <sup>-1</sup> , 4000 min <sup>-1</sup> (continuous)	
IP67 up to 70 °C [158 °F]	8000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous)	
IP67 up to T <sub>max</sub>	6000 min <sup>-1</sup> , 3000 min <sup>-1</sup> (continuous)	
<b>Starting torque - at 20 °C [68 °F]</b>		
IP65	< 0.01 Nm	
IP67	< 0,05 Nm	
<b>Mass moment of inertia</b>		
shaft version	3,0 x 10 <sup>-6</sup> kgm <sup>2</sup>	
hollow shaft version	6.0 x 10 <sup>-6</sup> kgm <sup>2</sup>	
<b>Load capacity of shaft</b>		
radial	80 N	
axial	40 N	
<b>Weight</b>		
with bus terminal cover	approx. 0.53 kg [18.69 oz]	
with fixed connection	approx. 0.50 kg [17.64 oz]	
<b>Protection acc. to EN 60529</b>		
housing side	IP67	
shaft side	IP65, opt. IP67	
<b>Working temperature range</b>		
	-40 °C ... +80 °C [-40 °F ... +176 °F]	
<b>Material</b>		
shaft/hollow shaft	stainless steel	
flange	aluminum	
housing	zinc die-cast	
<b>Shock resistance acc. to EN 60068-2-27</b>		
	2500 m/s <sup>2</sup> , 6 ms	
<b>Vibration resistance acc. to EN 60068-2-6</b>		
	100 m/s <sup>2</sup> , 55 ... 2000 Hz	

Electrical characteristics	
Supply voltage	10 ... 30 V DC
Power consumption (no load)	max. 110 mA
Reverse polarity protection of the supply voltage	yes

**SET button (zero or defined value, option)**

Protection against accidental activation.  
Button can only be operated with a ball-pen or pencil.

**Diagnostic LED (yellow)**

<b>LED is ON with following errors</b>	sensor error (Profibus error)
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# Absolute encoders - singleturn

<b>Standard optical</b>	<b>Sendix 5858 / 5878 (shaft / hollow shaft)</b>	<b>PROFIBUS DP</b>
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Interface characteristics PROFIBUS DP	
<b>Resolution</b>	1 ... 65536 (16 bit), scalable default: 8192 (13 bit)
<b>Interface</b>	interface specification acc. to PROFIBUS DP 2.0 / standard (DIN 19245 part 3) / RS485 driver galvanically isolated
<b>Protocol</b>	Profibus encoder profile V1.1 class 1 and class 2 with manufacturer-specific add-ons
<b>Baud rate</b>	max. 12 Mbit/s
<b>Device address</b>	1 ... 127 set by rotary switches
<b>Termination switchable</b>	set by DIP switches
Approvals	
<b>UL compliant</b> in accordance with	File no. E224618
<b>CE compliant</b> in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU (for Ex 2/22 variants)

## Profibus encoder profile V1.1

The PROFIBUS DP device profile describes the functionality of the communication and the user-specific component within the Profibus field bus system. For encoders, the encoder profile is definitive. Here the individual objects are defined independent of the manufacturer. Furthermore, the profiles offer space for additional manufacturer-specific functions; this means that Profibus-compliant device systems can be used now with the guarantee that they are ready for the future too.




### The following parameters can be programmed

- Direction of rotation.
- Scaling (Number of steps per revolution).
- Preset value.
- Diagnostics mode.

### The following functionality is integrated

- Galvanic isolation of the bus stage with DC/DC converter.
- Line driver acc. to RS485 max. 12 MB.
- Address programmable via DIP switches.
- Diagnostics LED.
- Full Class 1 and Class 2 functionality.

## Terminal assignment terminal box

Interface	Type of connection		BUS IN				BUS OUT				
3	1 (terminal box)	Signal:	B	A	0 V	+V	0 V	+V	B	A	The shield of the connection cable must be connected over a large area via the cable gland.
		Terminal:	1	2	3	4	5	6	7	8	
Interface	Type of connection	Funktion	3 x M12 connector								
3	2 (3 x M12 connector)	Bus in	Signal:	–	PB_A	–	PB_B	Shield			
			Pin:	1	2	3	4	5			
		Power supply	Signal:	+V	–	0 V	–				
			Pin:	1	2	3	4				
		Bus out	Signal:	BUS_VDC <sup>1)</sup>	PB_A	BUS_GND <sup>1)</sup>	PB_B	Shield			
			Pin:	1	2	3	4	5			

1) For supplying an external Profibus termination resistor.

# Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	PROFIBUS DP
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## Dimensions shaft version, with removable bus terminal cover

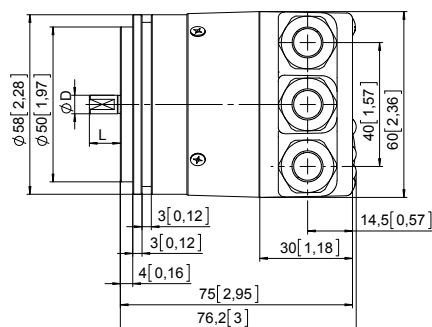
Dimensions in mm [inch]

### Synchro flange, ø 58 [2.28]

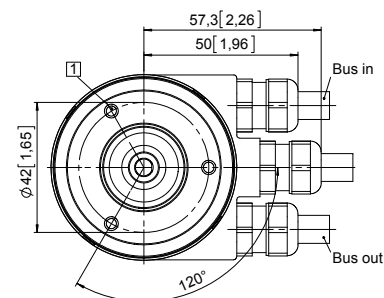
#### Flange type 2 and 4

(drawing with cable)

1 3 x M4, 6 [0.24] deep



D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



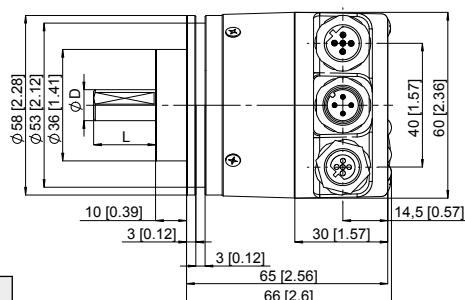
### Clamping flange, ø 58 [2.28]

#### Flange type 1 and 3

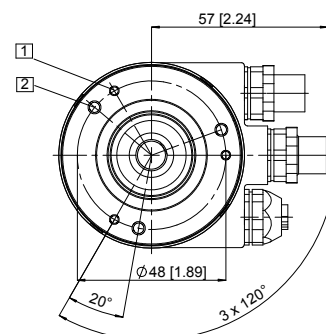
(drawing with 3 x M12 connector)

1 3 x M3, 6 [0.24] deep

2 3 x M4, 8 [0.32] deep



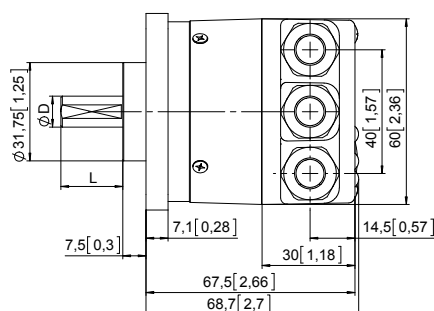
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



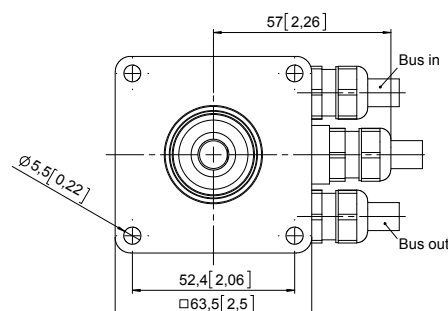
### Square flange, □ 63.5 [2.5]

#### Flange type 5 and 7

(drawing with cable)



D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



# Absolute encoders - singleturn

## Standard optical

## Sendix 5858 / 5878 (shaft / hollow shaft)

## PROFIBUS DP

### Dimensions hollow shaft version (blind hollow shaft), with removable bus terminal cover

Dimensions in mm [inch]

#### Flange with spring element, long

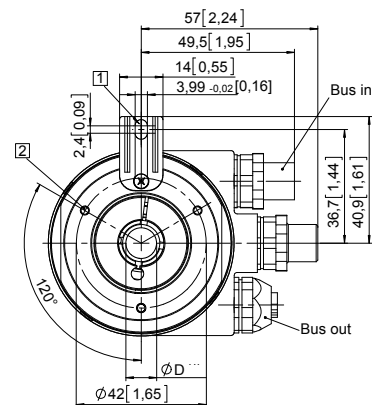
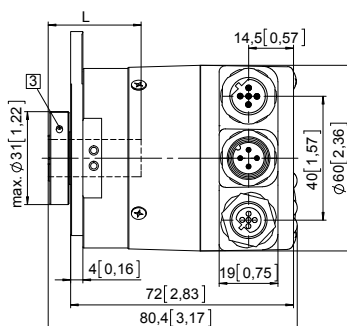
#### Flange type 1 and 2

(drawing with 3 x M12 connector)

- 1 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing$  4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



#### Flange with stator coupling, $\varnothing$ 63 [2.48]

#### Flange type 5 and 6

Pitch circle diameter for fixing screws

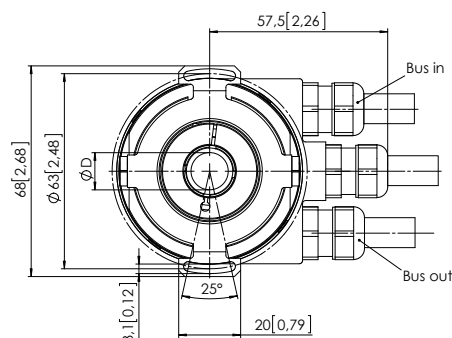
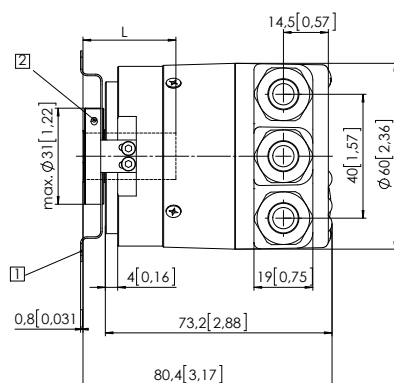
63 [2.48]

(drawing with cable)

- 1 Fixing screws DIN 912 M3 x 8 (washer included in delivery)
- 2 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



#### Flange with stator coupling, $\varnothing$ 65 [2.56]

#### Flange type 3 and 4

Pitch circle diameter for fixing screws,

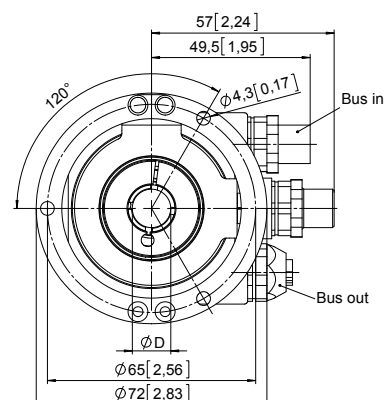
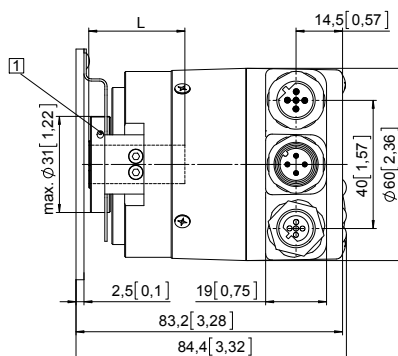
65 [2.56]

(drawing 3 x M12 connector)

- 1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



# Absolute encoders - singleturn

Standard  
optical

Sendix 5858 / 5878 (shaft / hollow shaft)

EtherCAT



The singleturn encoders 5858 and 5878 with second-generation EtherCAT interface and optical sensor technology are ideal for use in all applications with an EtherCAT interface.

The data communication is based on CAN over EtherNet and ideally suited for use in real time applications.

These encoders are available with a solid shaft up to a maximum of 10 mm or a blind hollow shaft up to 15 mm.



**EtherCAT**  
Conformance tested



Safety-Lock™



High rotational speed



Temperature range



High protection level



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Short-circuit proof



Reverse polarity protection



Optical sensor



Surface protection salt spray-tested optional

## Reliable

- EtherCAT conformance tested.
- Integration of the latest slave – EtherCAT stack from Beckhoff, version 5.01.
- Ideally suited for use in harsh outdoor environments, thanks to IP67 protection and rugged housing construction.

## Flexible

- Use of CoE (CAN over EtherNet).
- Genuine new position information as a result of minimal cycle time of 62.5 µs in the DC mode.
- Faster, easier error-free connection thanks to M12 connectors.
- Supports Hot-Connect.

Order code  
Shaft version

8.5858

Type

. XXB2 . B2 12

a

b

c

d

e

### a Flange

- 1 = clamping flange, IP65 ø 58 mm [2.28"]**  
 3 = clamping flange, IP67 ø 58 mm [2.28"]  
**2 = synchro flange, IP65 ø 58 mm [2.28"]**  
 4 = synchro flange, IP67 ø 58 mm [2.28"]  
 5 = square flange, IP65 □ 63.5 mm [2.5"]  
 7 = square flange, IP67 □ 63.5 mm [2.5"]

### b Shaft (ø x L), with flat

- 1 = 6 x 10 mm [0.24 x 0.39"]<sup>1)</sup>**  
**2 = 10 x 20 mm [0.39 x 0.79"]<sup>2)</sup>**  
 3 = 1/4" x 7/8"  
 4 = 3/8" x 7/8"

### c Interface / supply voltage

**B = EtherCAT / 10 ... 30 V DC**

### d Type of connection

removable bus terminal cover  
**2 = 3 x M12 connector, 4-pin**

### e Fieldbus profile

**B2 = EtherCAT with CoE (CAN over EtherNet)**

Optional on request  
 - Ex 2/22  
 - surface protection salt spray tested

Order code  
Hollow shaft

8.5878

Type

. XXB2 . B2 12

a

b

c

d

e

### a Flange

- 1 = with spring element, long, IP65  
 2 = with spring element, long, IP67  
 3 = with stator coupling, IP65 ø 65 mm [2.56"]  
 4 = with stator coupling, IP67 ø 65 mm [2.56"]  
**5 = with stator coupling, IP65 ø 63 mm [2.48"]**  
 6 = with stator coupling, IP67 ø 63 mm [2.48"]

### b Blind hollow shaft

- (insertion depth max. 30 mm [1.18"])  
 3 = ø 10 mm [0.39"]  
**4 = ø 12 mm [0.47"]**  
 5 = ø 14 mm [0.55"]  
 6 = ø 15 mm [0.59"]  
 8 = ø 3/8"  
 9 = ø 1/2"

### c Interface / supply voltage

**B = EtherCAT / 10 ... 30 V DC**

### d Type of connection

removable bus terminal cover  
**2 = 3 x M12 connector, 4-pin**

### e Fieldbus profile

**B2 = EtherCAT with CoE (CAN over EtherNet)**

Optional on request  
 - Ex 2/22  
 - surface protection salt spray tested

1) Preferred type only in conjunction with flange type 2.

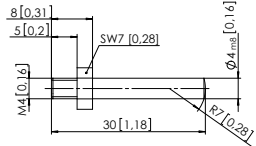
2) Preferred type only in conjunction with flange type 1.



# Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	EtherCAT
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Mounting accessory for shaft encoders		Order no.
Coupling	bellows coupling $\varnothing$ 19 mm [0.75"] for shaft 6 mm [0.24"]	8.0000.1102.0606
	bellows coupling $\varnothing$ 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1102.1010

Mounting accessory for hollow shaft encoders		Order no.
Torque pin, $\varnothing$ 4 mm for flange with spring element (flange type 1 + 2)		8.0010.4700.0000
with fixing thread 		

Cables and connectors		Order no.
Preassembled cables	M12 male connector with external thread, 4-pin, D coded, straight single-ended 2 m [6.56'] PUR cable	Bus IN + Bus OUT 05.00.6031.4411.002M
	M12 female connector with coupling nut, 4-pin, A coded, straight single-ended 2 m [6.56'] PUR cable	supply voltage 05.00.6061.6211.002M
Connectors	M12 male connector with external thread, 4-pin, D coded, straight (metal)	Bus IN + Bus OUT 05.WASCSY4S
	M12 female connector with coupling nut, 4-pin, A coded, straight (plastic)	supply voltage 05.B8141-0

Further Kübler accessories can be found at: [/accessories](#)  
Further Kübler cables and connectors can be found at: [/connection-technology](#)

## Technical data

Mechanical characteristics		
Maximum speed	IP65 up to 70 °C [158 °F]	9000 min <sup>-1</sup> , 7000 min <sup>-1</sup> (continuous)
	IP65 up to T <sub>max</sub>	7000 min <sup>-1</sup> , 4000 min <sup>-1</sup> (continuous)
	IP67 up to 70 °C [158 °F]	8000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous)
	IP67 up to T <sub>max</sub>	6000 min <sup>-1</sup> , 3000 min <sup>-1</sup> (continuous)
Starting torque - at 20 °C [68 °F]	IP65	< 0.01 Nm
	IP67	< 0.05 Nm
Mass moment of inertia		
	shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
	hollow shaft version	6.9 x 10 <sup>-6</sup> kgm <sup>2</sup>
Load capacity of shaft	radial	80 N
	axial	40 N
Weight		approx. 0.50 kg [17.64 oz]
Protection acc. to EN 60529		
	housing side	IP67
	shaft side	IP65, opt. IP67
Working temperature range		-40 °C ... +80 °C [-40 °F ... +176 °F]
Material	shaft/hollow shaft	stainless steel
	flange	aluminum
	housing	zinc die-cast
Shock resistance acc. to EN 60068-2-27		2500 m/s <sup>2</sup> , 6 ms
Vibration resistance acc. to EN 60068-2-6		100 m/s <sup>2</sup> , 55 ... 2000 Hz

Electrical characteristics	
Supply voltage	10 ... 30 V DC
Power consumption (no load)	max. 110 mA
Reverse polarity protection of the supply voltage	yes

Interface characteristics EtherCAT	
Resolution	1 ... 65535 (16 bit), scalable default: 8192 (13 bit)
Protocol	EtherNet / EtherCAT

Approvals	
UL compliant in accordance with	File no. E224618
CE compliant in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU (for Ex 2/22 variants)

# Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	EtherCAT
<b>Diagnostic LED (red)</b> LED is ON with the following fault conditions: Sensor error (internal code or LED error), low voltage, over-temperature		<b>2 x Link LEDs (yellow)</b> LED is ON with the following conditions (port IN and port OUT): Link detected
<b>Run LED (green)</b> LED is ON with the following conditions: Preop-, Safeop and Op-State (EtherCAT status machine)		<b>Modes</b> Freerun, Distributed Clock

## General information about CoE (CAN over EtherNet)

The EtherCAT encoders support the CANopen communication profile according to DS301. In addition device-specific profiles like the encoder profile DS406 are available.

Scaling, preset values, limit switch values and many other parameters can be programmed via the EtherCAT bus.

When switching the device on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure.




The following output values may be combined as PDO (PDO mapping): **position, speed, temperature values** and **working area state** as well as other process values.

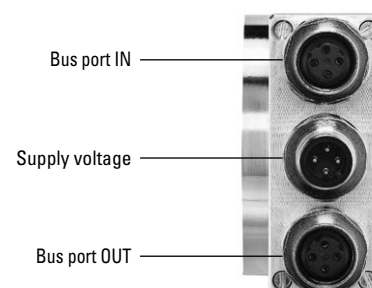
## CANopen encoder profile 3.2.10 CoE (CAN over EtherNet)

The following parameters are programmable:

- Position update time of 62.5 µs.
- EtherCAT certificate of conformity.
- Speed with sign.
- Four units for speed calculation: steps/sec, steps/100 ms, steps/10 ms, rotation/min.
- Time stamp as system time at the point in time when the position is read out.
- Two working area state registers.
- Along with the scaled position, the raw data – position as process value – is also mappable.
- Dynamic mapping.
- Gating time: setting of the time interval, via which the speed value can be interpolated.
- Sensor temperature in degrees Celsius.
- Comprehensive plausibility test when downloading parameters to the encoder.
- Alarm and warning messages.
- User interface with visual display of bus and fault status – 4 LEDs.
- Extended error management for position sensing with integrated temperature control.
- Implementation of the latest CANopen profile 3.2.10 from the 18th February 2011.
- Hot-Connect – Support for rapid change of Bus-topology.

## Terminal assignment bus

Interface	Type of connection	Function	M12 connector, 4-pin					
B	2 (3 x M12 connector)	Bus port IN	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	 D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	
		Power supply	Signal:	Voltage +	–	Voltage –	–	 D coded
			Abbreviation:	+ V	–	0 V	–	
			Pin:	1	2	3	4	
		Bus port OUT	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	 D coded
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	



# Absolute encoders - singleturn

Standard optical	Sendix 5858 / 5878 (shaft / hollow shaft)	EtherCAT
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## Dimensions shaft version, with removable bus terminal cover

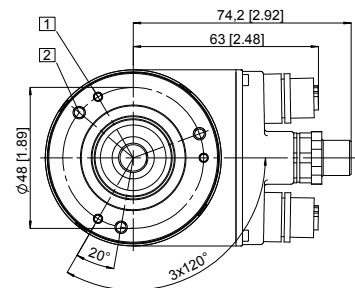
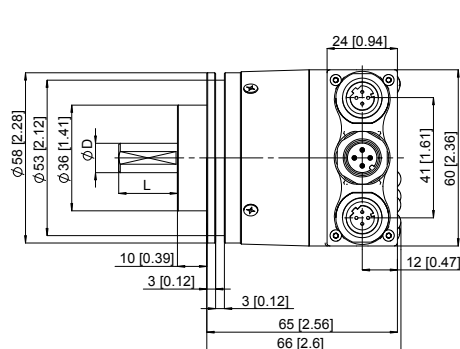
Dimensions in mm [inch]

### Clamping flange, ø 58 [2.28]

#### Flange type 1 and 3

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"

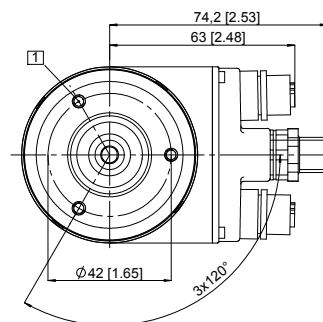
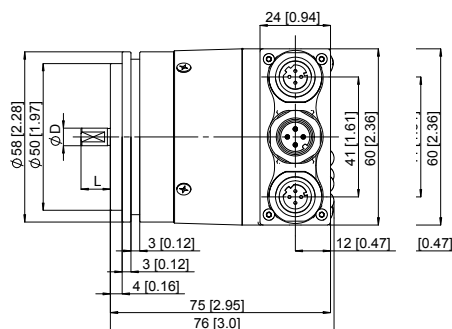


### Synchro flange, ø 58 [2.28]

#### Flange type 2 and 4

- 1 3 x M4, 6 [0.24] deep

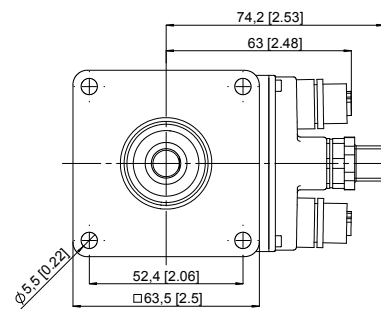
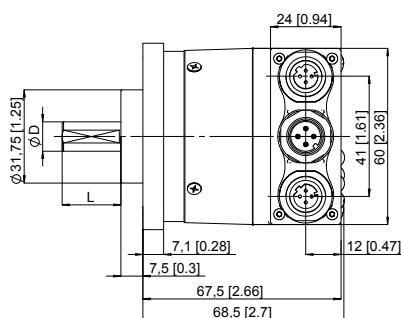
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



### Square flange, □ 63.5 [2.5]

#### Flange type 5 and 7

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h8	7/8"
3/8"	h8	7/8"



# Absolute encoders - singleturn

## Standard optical

## Sendix 5858 / 5878 (shaft / hollow shaft)

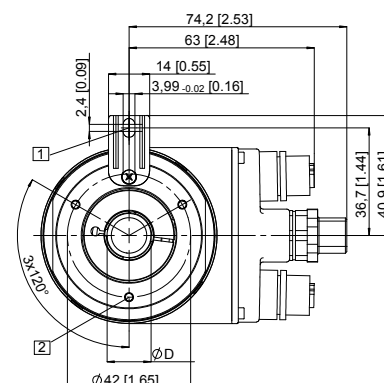
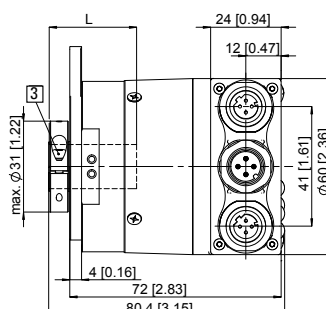
## EtherCAT

### Dimensions hollow shaft version (blind hollow shaft), with removable bus terminal cover

Dimensions in mm [inch]

#### Flange with spring element, long Flange type 1 and 2

- 1 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing$  4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

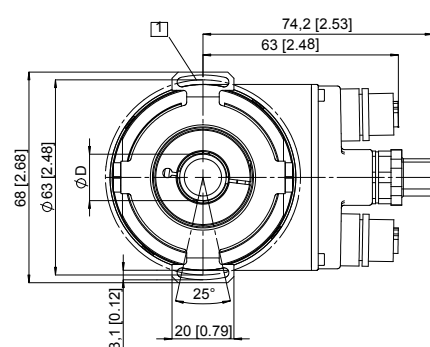
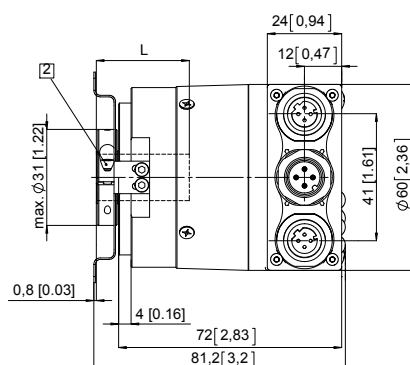


D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

#### Flange with stator coupling, $\varnothing$ 63 [2.48] Flange type 5 and 6

- 1 Fixing screws DIN 912 M3 x 8 (washer included in delivery)
- 2 Recommended torque for the clamping ring 0.6 Nm

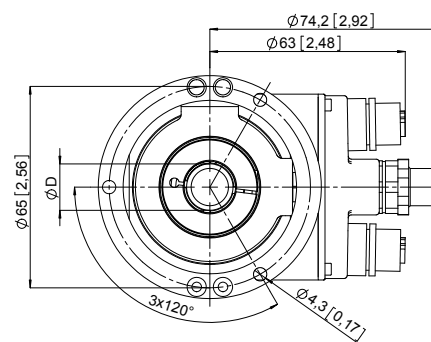
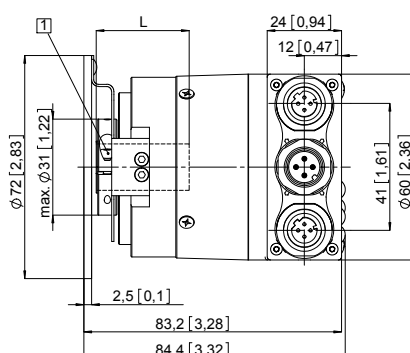


D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

#### Flange with stator coupling, $\varnothing$ 65 [2.56] Flange type 3 and 4

- 1 Recommended torque for the clamping ring 0.6 Nm



D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

# Absolute encoders - singleturn

Standard, ATEX/IECEx – zone 1/21  
optical

Sendix 7053 / 7073 (shaft / hollow shaft)

SSI / BiSS



The Sendix 7053 / 7073 absolute encoders – singleturn offer Ex protection in a compact 70 mm seawater durable aluminum housing, with an SSI or BiSS interface and optical sensor technology.

These shock and vibration-resistant encoders operate flexibly with a resolution of up to 17 bits; they are also available with axial and radial cable outlets.



## Compact and safe

- Can be used even when space is tight.
- Minimal installation depth, diameter 70 mm.
- Compact cable outlet axial or radial.
- Can be operated in marine environments – housing and flange manufactured from seawater durable aluminum.
- Remains sealed even in harsh everyday use and ensures highest safety against field breakdowns (IP67 protection).

## Explosion protection

- “Flameproof-enclosure” version.
- ATEX with EU type examination certificate.
- IECEx with certificate of conformity (CoC).

Order code  
Shaft version

8.7053 . 1 X 2 X . X X 2 1 . XXXX  
Type a b c d e f g h i <sup>1)</sup>

**a** Flange  
1 = clamping / synchronous flange, ø 70 mm [2.76"]

**b** Shaft (ø x L)  
2 = 10 x 20 mm [0.39 x 0.79"], with flat  
1 = 12 x 25 mm [0.47 x 0.98"], with keyway  
for 4 x 4 mm [0.16 x 0.16"] key

**c** Interface / supply voltage  
2 = SSI, BiSS / 10 ... 30 V DC

**d** Type of connection  
1 = axial cable, 2 m [6.56'] PUR  
2 = radial cable, 2 m [6.56'] PUR  
A = axial cable, length > 2 m [6.56']  
B = radial cable, length > 2 m [6.56']

**e** Code  
B = SSI, binary  
C = BiSS, binary  
G = SSI, gray

**f** Resolution <sup>2)</sup>  
A = 10 bit  
1 = 11 bit  
2 = 12 bit  
3 = 13 bit  
4 = 14 bit  
7 = 17 bit

**g** Inputs / outputs <sup>2)</sup>  
2 = SET, DIR input  
additional status output

**h** Options  
1 = no option

**i** Cable length in dm <sup>1)</sup>  
0050 = 5 m [16.40']  
0100 = 10 m [32.81']  
0150 = 15 m [49.21']

Optional on request  
- special cable length  
- other resolutions  
- seawater resistant (stainless steel V4A)

1) Not applicable with connection types 1 and 2.

2) Resolution, preset value and counting direction factory-programmable.

# Absolute encoders - singleturn

<b>Standard, ATEX/IECEX – zone 1/21 optical</b>	<b>Sendix 7053 / 7073 (shaft / hollow shaft)</b>	<b>SSI / BiSS</b>
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<b>Order code</b> <b>Hollow shaft</b>	<b>8.7073</b> Type	<b>.XX2X.XX21.XXXX</b> a b c d e f g h i <sup>1)</sup>	
<b>a</b> Flange 1 = with spring element, short 5 = with stator coupling, ø 65 mm [2.56"]	<b>e</b> Code B = SSI, binary C = BiSS, binary G = SSI, gray	<b>i</b> Cable length in dm <sup>1)</sup> 0050 = 5 m [16.40'] 0100 = 10 m [32.81'] 0150 = 15 m [49.21']	
<b>b</b> Blind hollow shaft (insertion depth max. 41.5 mm [1.63"]) 1 = ø 12 mm [0.47"] 2 = ø 14 mm [0.55"]	<b>f</b> Resolution <sup>2)</sup> A = 10 bit 1 = 11 bit 2 = 12 bit 3 = 13 bit 4 = 14 bit 7 = 17 bit	<b>Optional on request</b> - special cable length - other resolutions - seawater resistant (stainless steel V4A)	
<b>c</b> Interface / supply voltage 2 = SSI, BiSS / 10 ... 30 V DC	<b>g</b> Inputs / outputs <sup>2)</sup> 2 = SET, DIR input additional status output		
<b>d</b> Type of connection 1 = axial cable, 2 m [6.56'] PUR 2 = radial cable, 2 m [6.56'] PUR A = axial cable, length > 2 m [6.56'] B = radial cable, length > 2 m [6.56']	<b>h</b> Options 1 = no option		

<b>Mounting accessory for shaft encoders</b>	<b>Order no.</b>
<b>Coupling</b>	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]
	<b>8.0000.1102.1010</b>

Further Kübler accessories can be found at: [/accessories](#)  
Further Kübler cables and connectors can be found at: [/connection-technology](#)

## Technical data

Explosion protection		Electrical characteristics	
<b>ATEX</b>		<b>Supply voltage</b>	10 ... 30 V DC
<b>EU type-examination certificate</b>	IBExU 15 ATEX 1091 X	<b>Current consumption (no load)</b>	max. 45 mA
<b>Category (gas)</b>	Sendix 7053 – 6000 rpm  II 2G Ex db IIC T4 Gb Sendix 7053 – 2000 rpm  II 2G Ex db IIC T5 Gb Sendix 7073 – 3000 rpm  II 2G Ex db IIC T4 Gb Sendix 7073 – 2000 rpm  II 2G Ex db IIC 120°C (T4) Gb	<b>Reverse polarity protection for supply voltage</b>	yes
<b>Category (dust)</b>	Sendix 7053 – 6000 rpm  II 2D Ex tb IIIC T135°C Db Sendix 7053 – 2000 rpm  II 2D Ex tb IIIC T100°C Db Sendix 7073 – 3000 rpm  II 2D Ex tb IIIC T135°C Db Sendix 7073 – 2000 rpm  II 2D Ex tb IIIC T120°C Db	<b>Short-circuit proof outputs</b>	yes <sup>3)</sup>
<b>Relevant standards</b>	EN 60079-0:2018 ATEX guideline 2014/34/EU EN 60079-1:2014 EN 60079-31:2014	<b>EMC</b>	
<b>IECEX</b>		<b>Relevant standards</b>	EN 55011 class B EN (IEC) 61326-1
<b>Certificate of Conformity (CoC)</b>	IECEX IBE 15.0020 X		
<b>Category (gas)</b>	Sendix 7053 – 6000 rpm Ex db IIC T4 Gb Sendix 7053 – 2000 rpm Ex db IIC T5 Gb Sendix 7073 – 3000 rpm Ex db IIC T4 Gb Sendix 7073 – 2000 rpm Ex db IIC 120°C (T4) Gb		
<b>Category (dust)</b>	Sendix 7053 – 6000 rpm Ex tb IIIC T135°C Db Sendix 7053 – 2000 rpm Ex tb IIIC T100°C Db Sendix 7073 – 3000 rpm Ex tb IIIC T135°C Db Sendix 7073 – 2000 rpm Ex tb IIIC T120°C Db		
<b>Relevant standards</b>	IEC 60079-0:2017 IEC 60079-1:2014 IEC 60079-31:2013		

1) Not applicable with connection types 1 and 2.  
2) Resolution, preset value and counting direction factory-programmable.  
3) Short-circuit with 0 V or output, only one channel at a time, supply voltage correctly applied.

# Absolute encoders - singleturn

Standard, ATEX/IECEx – zone 1/21 optical			Sendix 7053 / 7073 (shaft / hollow shaft)			SSI / BiSS		
<b>Mechanical characteristics</b>								
<b>Maximum speed</b>		shaft	6000 min <sup>-1</sup> (continuous)			open collector, internal pull-up resistor 22 kOhm		
		hollow shaft	3000 min <sup>-1</sup> (continuous)					
<b>Starting torque - at 20 °C [68 °F]</b>			< 0.05 Nm			<b>Permissible load</b>		
<b>Mass moment of inertia</b>			4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>			max. 20 mA		
<b>Load capacity of shaft</b>		radial	80 N			<b>Signal level</b>		
		axial	40 N			HIGH +V		
						LOW < 1 V		
<b>Weight</b>		approx. 1.5 kg [52.91 oz]			<b>Active at</b>			
<b>Protection acc. to EN 60529</b>		IP67			LOW			
<b>Ambient temperature</b>		-40 °C ... +60 °C [-40 °F ... +140 °F] Please note the specifications for temperature class in EU type-examination certificate!			The status output serves to display various alarm or error messages. The status output is HIGH (open collector with internal pull-up 22 kOhm) in normal operation.			
<b>Material</b>		shaft	stainless steel			The status output serves to display various alarm or error messages. The status output is HIGH (open collector with internal pull-up 22 kOhm) in normal operation.		
		flange / housing	seawater durable Al, type AlSiMgMn (EN AW-6082)					
		cable	PUR					
<b>Shock resistance to EN/IEC 60068-2-27</b>			2500 m/s <sup>2</sup> , 6 ms			<b>SET input</b>		
<b>Vibration resistance to EN/IEC 60068-2-6</b>			100 m/s <sup>2</sup> , 55 ... 2000 Hz			<b>Input</b>		
						HIGH active		
						<b>Input type</b>		
						comparator		
						<b>Signal level</b>		
						HIGH min. 60% of +V		
						max. +V		
						LOW max. 25% of +V		
						<b>Input current</b>		
						< 0.5 mA		
						<b>Min. pulse duration (SET)</b>		
						10 ms		
						<b>Timeout after SET signal</b>		
						14 ms		
						The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal delay time of approximately 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approximately 15 ms before the new position data can be read. If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.		
						<b>DIR input</b>		
						Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed. If DIR is reversed when the device is already switched on, this will be interpreted as an error. The status output switches to LOW. If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.		
						<b>Response time (DIR input)</b>		
						1 ms		
						<b>Power-ON</b>		
						After Power-ON the device requires a time of approx. 150 ms before valid data can be read. Hot plugging of the encoder should be avoided.		
						<b>Approvals</b>		
						<b>CE compliant</b> in accordance with		
						EMC Directive 2014/30/EU		
						RoHS Directive 2011/65/EU		
						ATEX Directive 2014/34/EU		
<b>SSI interface</b>								
<b>Output driver</b>		RS485 transceiver type						
<b>Permissible load / channel</b>		max. +/- 20 mA						
<b>Signal level</b>		HIGH	typ 3.8 V					
		LOW at I <sub>Load</sub> = 20 mA	typ 1.3 V					
<b>Resolution</b>		10 ... 14 bit and 17 bit						
<b>Code</b>		binary or gray						
<b>SSI clock rate</b>		50 kHz ... 2 MHz						
<b>Data refresh rate</b>								
		ST resolution ≤ 14 bit	< 1 µs					
		ST resolution ≥ 15 bit	4 µs					
<b>Monoflop time</b>		≤ 15 µs						
<b>Note:</b> if clock starts cycling within monoflop time a second data transfer starts with the same data. If clock starts cycling after monoflop time, the data transfer starts with updated values. The update rate depends on clock speed, data length and monoflop time.								
<b>BiSS interface</b>								
<b>Output driver</b>		RS485 transceiver type						
<b>Permissible load / channel</b>		max. +/- 20 mA						
<b>Signal level</b>		HIGH	typ 3.8 V					
		LOW at I <sub>Load</sub> = 20 mA	typ 1.3 V					
<b>Resolution</b>		10 ... 14 bit and 17 bit						
<b>Code</b>		binary						
<b>Clock rate</b>		up to 10 MHz						
<b>Max. update rate</b>		< 10 µs, depends on the clock rate and the data length						
<b>Data refresh rate</b>								
		ST resolution ≤ 14 bit	≤ 1 µs					
		ST resolution 17 bit	2.4 µs					
<b>Note:</b> <ul style="list-style-type: none"><li>– bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings</li><li>– CRC data verification</li></ul>								

# Absolute encoders - singleturn

<b>Standard, ATEX/IECEX – zone 1/21 optical</b>	<b>Sendix 7053 / 7073 (shaft / hollow shaft)</b>	<b>SSI / BiSS</b>
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## Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)											
2	1, 2, A, B	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	⊥	⊥
			Core marking:	1	2	3	4	5	6	7	8	9	YE/GN	shield

+V: Supply voltage encoder +V DC

0 V: Supply voltage encoder ground GND (0 V)

C+, C-: Clock signal

D+, D-: Data signal

SET: Set input

DIR: Direction input

Stat: Status output

⊥: Protective earth

## Dimensions shaft version

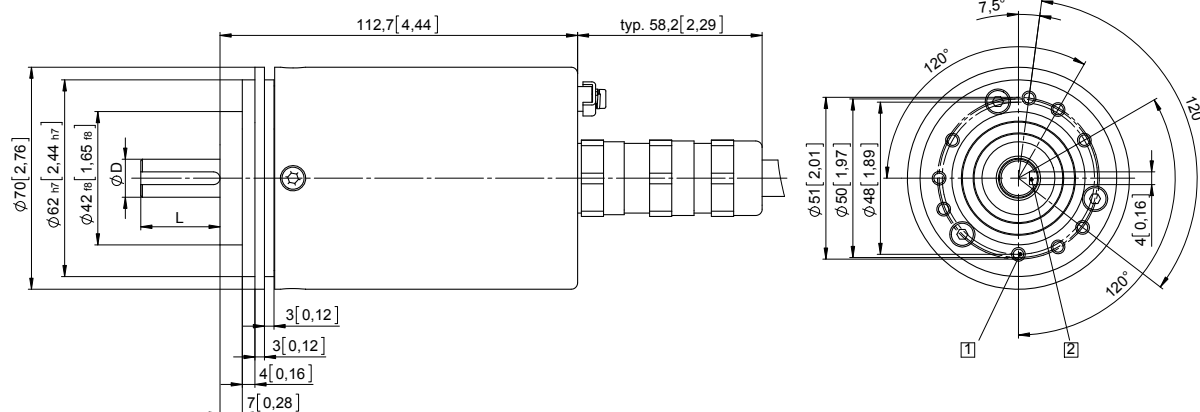
Dimensions in mm [inch]

### Clamping / synchronous flange, ø 70 [2.76]

#### Shaft type 1 with axial cable outlet

1 9 x M4, 10 [0.39] deep

2 Keyway for DIN 6885-A-4x4x25 key

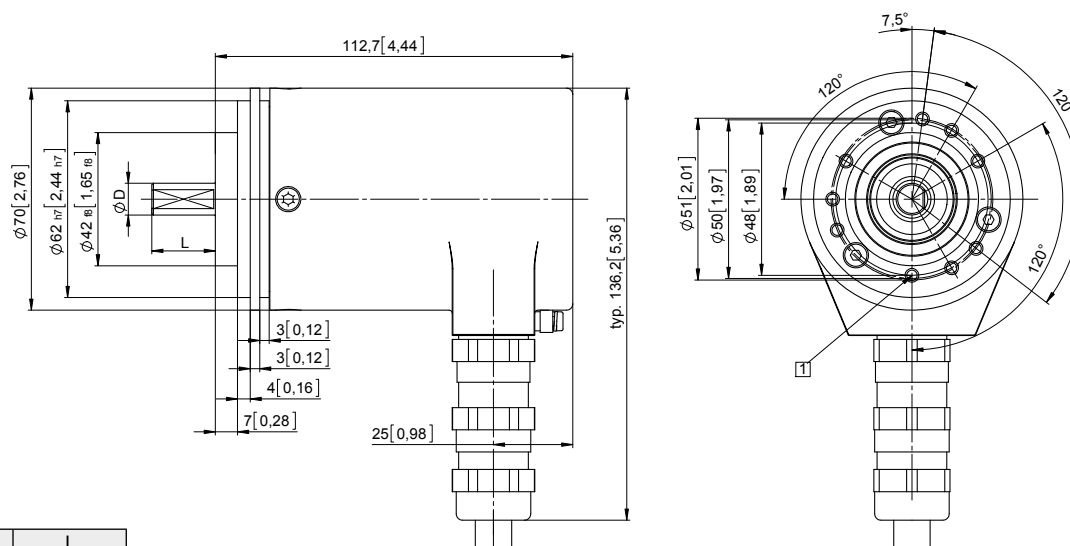


D	Fit	L
12 [0.47]	g6	25 [0.98]

### Clamping / synchronous flange, ø 70 [2.76]

#### Shaft type 2 with radial cable outlet

1 9 x M4, 10 [0.39] deep



D	Fit	L
10 [0.39]	f7	20 [0.79]



# Absolute encoders - singleturn

**Standard, ATEX/IECEx – zone 1/21  
optical**

**Sendix 7053 / 7073 (shaft / hollow shaft)**

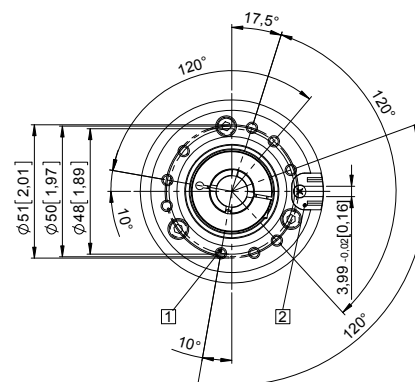
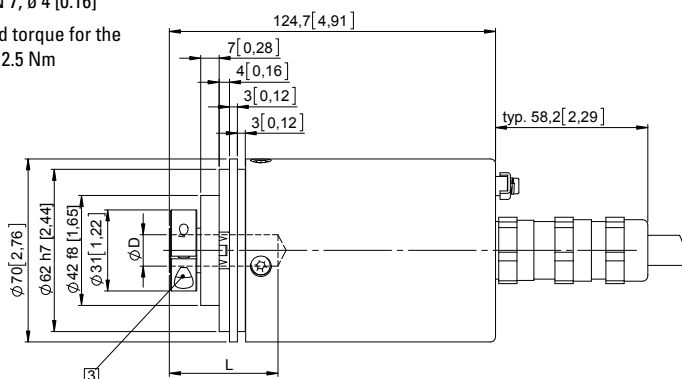
**SSI / BiSS**

## Dimensions hollow shaft version

Dimensions in mm [inch]

### Flange with spring element, short Flange type 1

- 1 9 x M4, 10 [0.39] deep
- 2 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing$  4 [0.16]
- 3 Recommended torque for the clamping ring 2.5 Nm

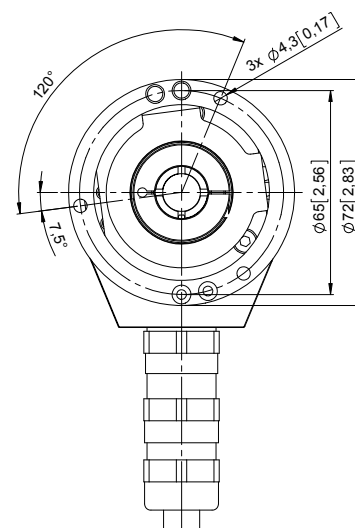
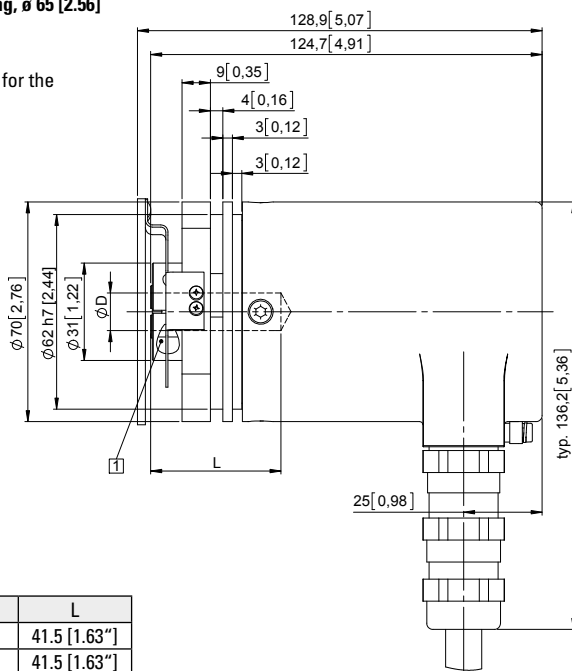


D	Fit	L
12 [0.47]	H7	41.5 [1.63"]
14 [0.55]	H7	41.5 [1.63"]

L = insertion depth max. blind hollow shaft

### Flange with stator coupling, $\varnothing$ 65 [2.56] Flange type 5

- 1 Recommended torque for the clamping ring 2.5 Nm



D	Fit	L
12 [0.47]	H7	41.5 [1.63"]
14 [0.55]	H7	41.5 [1.63"]

L = insertion depth max. blind hollow shaft

# Absolute encoders - singleturn

**Standard  
SIL2/PLd, optical**

**Sendix 5853FS2 / 5873FS2 (shaft / hollow shaft)**

**SSI / BiSS + SinCos**



**SIL2**  
Functional Safety  
**PLd**

The absolute singleturn encoders 5853FS2 and 5873FS2 of the Sendix family are suited for use in safety-related applications up to SIL2 according to EN 61800-5-2 or PLd to EN ISO 13849-1.

The extra strong Safety-Lock™ design interlocked bearings, the high integration density of the components based on OptoASIC technology and the rugged die-cast housing make these devices ideal also for demanding applications outdoors up to IP67.



Safety-Lock™



High rotational speed



Temperature range



High protection level



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Reverse polarity protection



SinCos



Optical sensor

## Functional Safety

- Encoder with individual certificate from TÜV.
- Suitable for applications up to SIL2 acc. to EN 61800-5-2.
- Suitable for applications up to PLd acc. to EN ISO 13849-1.
- SSI or BiSS interface with incremental SinCos tracks with 2048 ppr.
- Certified mechanical mounting + electronic.

## Flexible

- Shaft and hollow shaft versions.
- Cable and connector variants.
- Various mounting options available.

## Order code

**8.5853FS2**

## Shaft version

Type

. XXXX . XX2X  
a b c d e f g

### a Flange

- 1 = clamping flange, IP65, ø 58 mm [2.28"]
- 3 = clamping flange, IP67, ø 58 mm [2.28"]

### b Shaft (ø x L)

- 2 = 10 x 20 mm [0.39 x 0.79"], with flat
- A = 10 x 20 mm [0.39 x 0.79"], with feather key

### c Interface / supply voltage

- 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC
- 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC

### d Type of connection

- 1 = axial cable, 1 m [3.28'] PVC
- A = axial cable, special length PVC \*)
- 2 = radial cable, 1 m [3.28'] PVC
- B = radial cable, special length PVC \*)
- 3 = axial M23 connector, 12-pin
- 4 = radial M23 connector, 12-pin

\*) Available special lengths (connection types A, B):  
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']  
order code expansion .XXXX = length in dm  
ex.: 8.5853FS2.124A.G322.0030 (for cable length 3 m)

### e Code

- B = SSI, binary
- C = BiSS, binary
- G = SSI, gray

### f Resolution <sup>1)</sup>

- A = 10 bit
- 1 = 11 bit
- 2 = 12 bit
- 3 = 13 bit
- 4 = 14 bit
- 7 = 17 bit

### g Options (service)

- 1 = no option
- 2 = status LED
- 3 = SET button and status LED

### Optional on request

- Ex 2/22 (only for variants with IP67) <sup>2)</sup>
- other resolutions
- surface protection salt spray

1) Resolution, preset value and count direction are factory-programmable.

2) For the cable connection type, cable material PUR.

# Absolute encoders - singleturn

Standard SIL2/PLd, optical	Sendix 5853FS2 / 5873FS2 (shaft / hollow shaft)	SSI/BiSS + SinCos
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Order code Hollow shaft	8.5873FS2 Type	. XXXXX . XX2X a b c d e f g
<p><b>a Flange</b>            9 = with torque stop FS, flexible, IP65            J = with torque stop FS, flexible, IP67            A = with torque stop FS, rigid, IP65 (incl. torque pin FS)            K = with torque stop FS, rigid, IP67 (incl. torque pin FS)            B = with stator coupling FS, ø 63 mm [2.48"], IP65            L = with stator coupling FS, ø 63 mm [2.48"], IP67</p> <p><b>b Through hollow shaft</b>            3 = ø 10 mm [0.39"]            4 = ø 12 mm [0.47"]            5 = ø 14 mm [0.55"]  <i>Tapered shaft</i>            K = ø 10 mm [0.39"]</p> <p><b>c Interface / supply voltage</b>            3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC            4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC</p> <p><b>d Type of connection</b>            2 = radial cable, 1 m [3.28'] PVC            B = radial cable, special length PVC *)            E = tangential cable, 1 m [3.28'] PVC            F = tangential cable, special length PVC *)            4 = radial M23 connector, 12-pin</p> <p>*) Available special lengths (connection types B, F):            2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']            order code expansion .XXXX = length in dm            ex.: 8.5873FS2.B44B.G322.0030 (for cable length 3 m)</p> <p><b>e Code</b>            B = SSI, binary            C = BiSS, binary            G = SSI, gray</p> <p><b>f Resolution <sup>1)</sup></b>            A = 10 bit            1 = 11 bit            2 = 12 bit            3 = 13 bit            4 = 14 bit            7 = 17 bit</p> <p><b>g Options (service)</b>            1 = no option            2 = status LED            3 = SET button and status LED</p> <p><i>Optional on request</i>            - Ex 2/22 (only for variants with IP67) <sup>2)</sup>              not for type of connection E, F            - other resolutions            - surface protection salt spray</p>		

Accessories		Order no.
<b>EMC shield terminal</b>	for top-hat rail mounting	8.0000.4G06.0312
<b>Screw retention</b>	Loctite 243, 5 ml	8.0000.4G05.0000
<b>Bellows coupling, safety-oriented</b>	You will find an overview of our couplings for Sendix shaft encoders under /accessories.	
<b>Safety modules Safety-M compact</b>	You will find an overview of our systems and components for Functional Safety and the corresponding software under /safety.	
<b>LED SSI display 570 / 575</b>	Electronic position display up to 32 bit. You will find an overview or under /position_display	
Connection technology		Order no.
<b>Cordset, pre-assembled</b>	M23 female connector with coupling nut, 12-pin, cw single ended 2 m [6.56'] PVC cable <sup>3)</sup>	8.0000.6901.0002.0031
	M23 female connector with coupling nut, 12-pin, cw M23 male connector with external thread, 12-pin, ccw 2 m [6.56'] PVC cable <sup>3)</sup>	8.0000.6905.0002.0032
<b>Connector, self-assembly</b>	M23 female connector with coupling nut, 12-pin, cw	8.0000.5012.0000

Further Kübler accessories can be found at: [/accessories](#)  
 Further Kübler cables and connectors can be found at: [/connection-technology](#)

1) Resolution, preset value and count direction are factory-programmable.  
 2) For the cable connection type, cable material PUR.  
 3) Other lengths available.

# Absolute encoders - singleturn

<b>Standard SIL2/PLd, optical</b>	<b>Sendix 5853FS2 / 5873FS2 (shaft / hollow shaft)</b>	<b>SSI/BiSS + SinCos</b>
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## Technical data

<b>Notes regarding "Functional Safety"</b> These encoders are suitable for use in safety-related systems up to SIL2 acc. to EN 61800-5-2 and PLd to EN ISO 13849-1 in conjunction with controllers or evaluation units, which possess the necessary functionality. Additional functions can be found in the operating manual.			<b>EMC</b> <b>Relevant standards</b> EN 55011 class B :2009 / A1:2010 EN 61326-1:2013 EN 61326-3-1:2008		
<b>Safety characteristics</b> <b>Classification</b> PLd / SIL2 <b>System structure</b> 2 channel (Cat. 3) <b>PFH<sub>d</sub> value<sup>1)</sup></b> $2.16 \times 10^{-8} \text{ h}^{-1}$ <b>Mission time / Proof test interval</b> 20 years <b>Relevant standards</b> EN ISO 13849-1:2015; EN ISO 13849-2:2012; EN 61800-5-2:2007			<b>SSI interface</b> <b>Output driver</b> RS485 transceiver type <b>Permissible load / channel</b> max. +/- 20 mA <b>Signal level</b> HIGH typ. 3.8 V LOW at $I_{\text{Load}} = 20 \text{ mA}$ typ. 1.3 V <b>Resolution</b> 10 ... 14 bit and 17 bit <b>Code</b> binary or gray <b>SSI clock rate</b> 50 kHz ... 2 MHz <b>Data refresh rate</b> ST resolution $\leq 14 \text{ bit}$ $\leq 1 \mu\text{s}$ ST resolution $\geq 15 \text{ bit}$ $4 \mu\text{s}$ <b>Monoflop time</b> $\leq 15 \mu\text{s}$ <b>Note:</b> If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the data transfer starts with the new values. The update rate is dependent on the clock speed, data length and monoflop-time.		
<b>Electrical characteristics</b> <b>Supply voltage</b> 5 V DC ( $\pm 5 \%$ ) or 10 ... 30 V DC <b>Current consumption</b> 5 V DC max. 70 mA (no load) 10 ... 30 V DC max. 45 mA <b>Reverse polarity protection of the supply voltage</b> yes <b>Short circuit proof outputs</b> yes <sup>2)</sup>			<b>BiSS interface</b> <b>Output driver</b> RS485 transceiver type <b>Permissible load / channel</b> max. +/- 20 mA <b>Signal level</b> HIGH typ. 3.8 V LOW at $I_{\text{Load}} = 20 \text{ mA}$ typ. 1.3 V <b>Resolution</b> 10 ... 14 bit and 17 bit <b>Code</b> binary <b>Clock rate</b> up to 10 MHz <b>Max. update rate</b> $< 10 \mu\text{s}$ , depends on the clock rate and the data length <b>Data refresh rate</b> ST resolution $\leq 14 \text{ bit}$ $\leq 1 \mu\text{s}$ ST resolution 17 bit $2.4 \mu\text{s}$ <b>Note:</b> <ul style="list-style-type: none"> <li>– bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings</li> <li>– CRC data verification</li> </ul>		
<b>Mechanical characteristics</b> <b>Maximum speed shaft version</b> up to 70 °C [158 °F] 12000 min <sup>-1</sup> , 10000 min <sup>-1</sup> (continuous) up to T <sub>max</sub> 8000 min <sup>-1</sup> , 5000 min <sup>-1</sup> (continuous) <b>Maximum speed hollow shaft version</b> up to 70 °C [158 °F] 9000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous) up to T <sub>max</sub> 6000 min <sup>-1</sup> , 3000 min <sup>-1</sup> (continuous) <b>Starting torque - at 20 °C [68 °F]</b> shaft version $< 0.01 \text{ Nm}$ hollow shaft version $< 0.03 \text{ Nm}$ <b>Mass moment of inertia</b> shaft version $4.0 \times 10^{-6} \text{ kgm}^2$ hollow shaft version $7.0 \times 10^{-6} \text{ kgm}^2$ <b>Insertion depth for shaft</b> hollow shaft version min. 34 mm [1.34"] <b>Load capacity of shaft</b> radial 80 N axial 40 N <b>Weight</b> approx. 0.45 kg [15.87 oz] <b>Protection acc. to EN 60529</b> IP65, IP67 <b>Working temperature range</b> -40 °C ... +90 °C [-40 °F ... +194 °F] <sup>3)</sup> <b>Material</b> shaft / hollow shaft stainless steel flange aluminum housing zinc die-cast cable PVC (PUR for Ex 2/22) <b>Shock resistance acc. to EN 60068-2-27</b> 500 m/s <sup>2</sup> , 11 ms <b>Vibration resistance acc. to EN 60068-2-6</b> 200 m/s <sup>2</sup> , 5 ... 2000 Hz			<b>SinCos interface</b> <b>Max. frequency -3dB</b> 400 kHz <b>Signal level</b> 1 V <sub>pp</sub> ( $\pm 10 \%$ ) <b>Short circuit proof</b> yes <sup>2)</sup> <b>Pulse rate</b> 2048 ppr		
<b>LED</b> The optional LED (red) serves to display various alarm or error messages. In normal operation the LED is OFF. If the LED is ON (status output LOW) this indicates: <ul style="list-style-type: none"> <li>- sensor error, singleturn or multiturn (soiling, glass breakage etc.)</li> <li>- LED error, failure or ageing</li> <li>- Over- or under-temperature</li> </ul> In the SSI mode, the fault indication can only be reset by switching off the supply voltage to the device.					

1) The specified value is based on a diagnostic coverage of 90 %, that must be achieved with an encoder evaluation unit.  
The encoder evaluation unit must meet at least the requirements for SIL2.

2) Short circuit to 0 V or to output, one channel at a time, supply voltage correctly applied.

3) Cable version: -30 °C ... +90 °C [-22 °F ... +194 °F].

# Absolute encoders - singleturn

Standard SIL2/PLd, optical	Sendix 5853FS2 / 5873FS2 (shaft / hollow shaft)	SSI/BiSS + SinCos
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SET input or SET button	
Input	HIGH active
Input type	comparator
Signal level	HIGH min: 60 % of +V, max: +V LOW max: 25 % of +V (supply voltage)
Input current	< 0.5 mA
Min. pulse duration (SET)	10 ms
Timeout after SET signal	14 ms
<p>The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point pen or similar). Other preset values can be factory-programmed.</p> <p>The SET input has a signal delay time of approx. 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approx. 15 ms before the new position data can be read. During this time the LED is ON.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	

DIR input	
<p>Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This function can also be factory-programmed to be inverted. If DIR is changed when the device is already switched on, then this will be interpreted as an error.</p> <p>The LED will come ON and the status output will switch to LOW.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	
Response time (DIR input)	1 ms

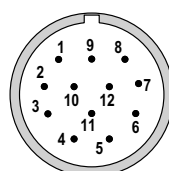
Power-ON	
<p>After Power-ON the device requires a time of approx. 150 ms before valid data can be read.</p> <p>Hot plugging of the encoder should be avoided.</p>	

## Terminal assignment

Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)													
3, 4	1, 2, A, B, E, F	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	$\bar{A}$	B	$\bar{B}$	$\perp$
		Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield
Interface	Type of connection	M23 connector, 12-pin													
3, 4	3, 4	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	$\bar{A}$	B	$\bar{B}$	$\perp$
		Pin:	1	2	3	4	5	6	7	8	9	10	11	12	PH

+V: Supply voltage encoder +V DC  
 0 V: Supply voltage encoder ground GND (0 V)  
 C+, C-: Clock signal  
 D+, D-: Data signal  
 SET: Set input  
 DIR: Direction input  
 A,  $\bar{A}$ : Cosine signal  
 B,  $\bar{B}$ : Sine signal  
 PH  $\perp$ : Plug connector housing (shield)

Top view of mating side, male contact base



M23 connector, 12-pin

# Absolute encoders - singleturn

**Standard**  
**SIL2/PLd, optical**

**Sendix 5853FS2 / 5873FS2 (shaft / hollow shaft)**

**SSI / BiSS + SinCos**

## Dimensions shaft version

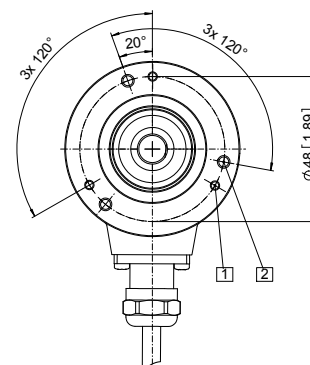
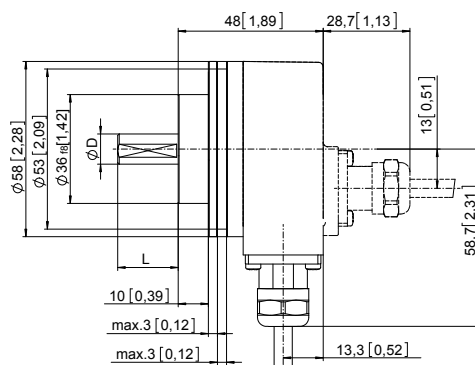
Dimensions in mm [inch]

### Clamping flange, $\varnothing$ 58 [2.28]

#### Flange type 1 + 3 with shaft type 2

(drawing with cable)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep



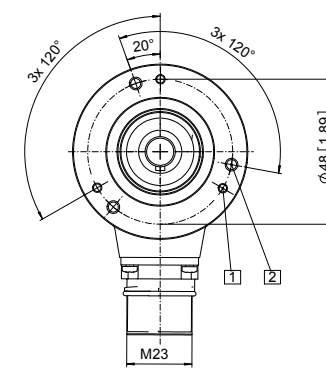
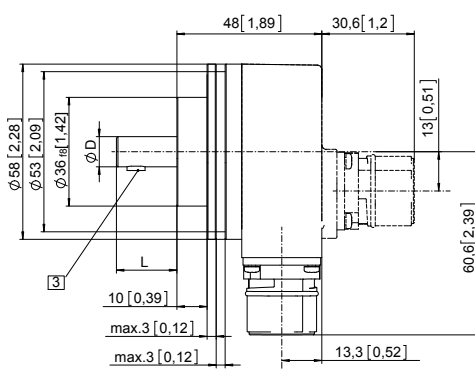
D	Fit	L
10 [0.39]	f7	20 [0.79]

### Clamping flange, $\varnothing$ 58 [2.28]

#### Flange type 1 + 3 with shaft type A

(drawing with M23 connector)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep
- 3 Feather key DIN 6885 - A - 3x3x6



D	Fit	L
10 [0.39]	f7	20 [0.79]

## SSI / BiSS + SinCos

Dimensions in mm [inch]

(drawing with cable)

- Torque pin with rectangular sleeve with  
M4 thread

(drawing with M23 connector)

- | D         | Fit |
|-----------|-----|
| 10 [0.39] | H7  |
| 12 [0.47] | H7  |
| 14 [0.55] | H7  |

# Absolute encoders - singleturn

**Standard**  
**SIL2/PLd, optical**

**Sendix 5853FS2 / 5873FS2 (shaft / hollow shaft)**

**SSI / BiSS + SinCos**

## Dimensions hollow shaft version

Dimensions in mm [inch]

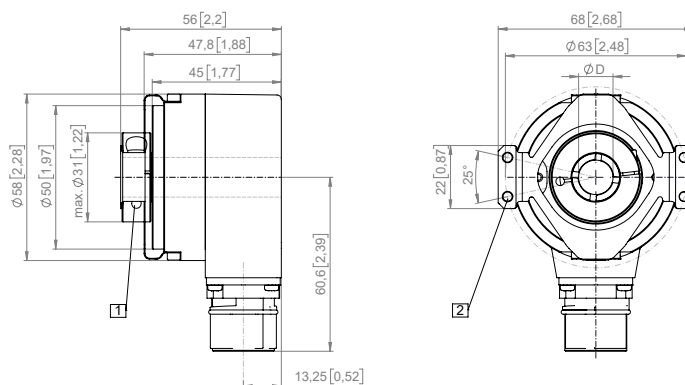
**Flange with stator coupling FS, ø 63 [2.48]**

**Flange type B + L**

**Through hollow shaft**

(drawing with M23 connector)

- 1 SW 3, recommended torque for the clamping ring 2.5 Nm
- 2 For (4x) M3 screw



D	Fit
10 [0.39]	H7
12 [0.47]	H7
14 [0.55]	H7

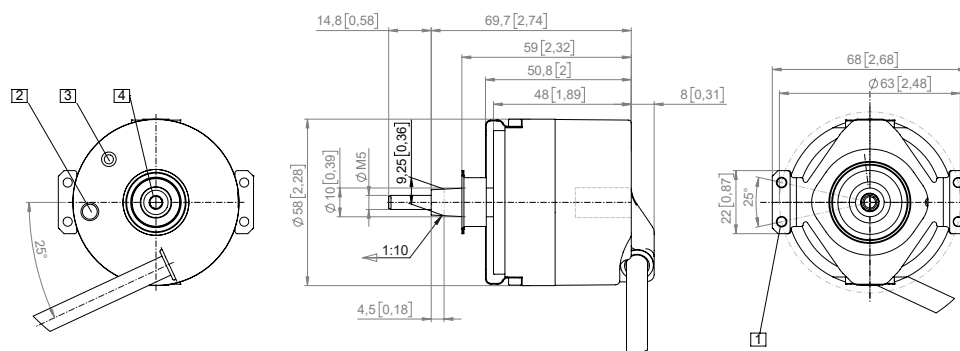
**Flange with stator coupling FS, ø 63 [2.48]**

**Flange type B + L**

**Tapered shaft**

(drawing with tangential cable outlet)

- 1 For (4x) M3 screw
- 2 Status-LED
- 3 SET button
- 4 Recommended torque for central screw M5 (SW 4) 3.0 <sup>+0.5</sup> Nm (tapered shaft)





# Absolute encoders - singleturn

Standard, ATEX/IECEX – mining M2  
optical

Sendix 7153 / 7173 (shaft / hollow shaft)

SSI / BiSS



The Sendix 7153 / 7173 absolute singleturn encoders in a compact 70 mm stainless-steel housing, with a an SSI or BiSS interface and optical sensor technology have an ATEX/IECEX mining M2 approval.

These shock and vibration-resistant encoders operate flexibly with a resolution of up to 17 bits; they are also available with axial and radial cable outlets.



Ex approval



Safety-Lock™



High rotational speed



High protection level



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Short-circuit proof



Reverse polarity protection



Optical sensor

## Compact and safe

- Can be used even when space is tight.
- Minimal installation depth, diameter 70 mm.
- Compact cable outlet axial or radial.
- Remains sealed even in harsh everyday use and ensures highest safety against field breakdowns (IP67 protection).

## Explosion protection

- Mining M2 approval.
- “Flame-proof enclosure” construction.
- ATEX with EU type examination certificate.
- IECEx with certificate of conformity (CoC).

## Order code

### Shaft version

8.7153 . 2X2X . XX21 . XXXX  
Type a b c d e f g h i 1)

#### a Flange

2 = clamping / synchronous flange, ø 70 mm [2.76"]

#### b Shaft (ø x L)

2 = 10 x 20 mm [0.39 x 0.79"], with flat

1 = 12 x 25 mm [0.47 x 0.98"], with keyway for 4 x 4 mm [0.16 x 0.16"] key

#### c Interface / supply voltage

2 = SSI, BiSS / 10 ... 30 V DC

#### d Type of connection

1 = axial cable, 2 m [6.56'] PUR

2 = radial cable, 2 m [6.56'] PUR

A = axial cable, length > 2 m [6.56']

B = radial cable, length > 2 m [6.56']

#### e Code

B = SSI, binary

C = BiSS, binary

G = SSI, gray

#### f Resolution 2)

A = 10 bit

1 = 11 bit

2 = 12 bit

3 = 13 bit

4 = 14 bit

7 = 17 bit

#### g Inputs / outputs 2)

2 = SET, DIR input  
additional status output

#### h Options

1 = no option

#### i Cable length in dm 1)

0050 = 5 m [16.40']

0100 = 10 m [32.81']

0150 = 15 m [49.21']

Optional on request

- special cable length

- other resolutions

1) Not applicable with connection types 1 and 2





2) Resolution, preset value and counting direction factory-programmable.

# Absolute encoders - singleturn

<b>Standard, ATEX/IECEX – mining M2 optical</b>	<b>Sendix 7153 / 7173 (shaft / hollow shaft)</b>	<b>SSI / BiSS</b>
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<b>Order code</b>	<b>8.7173</b>	<b>.XX2X.XX21.XXXX</b>	<b>Hollow shaft</b>
	Type	<b>a b c d e f g h i</b>	<b>i</b> <sup>1)</sup>
<b>a</b> Flange		<b>e</b> Code	<b>i</b> Inputs / outputs <sup>2)</sup>
2 = with spring element, short		B = SSI, binary	2 = SET, DIR input
6 = with stator coupling, ø 65 mm [2.56"]		C = BiSS, binary	additional status output
		G = SSI, gray	
<b>b</b> Blind hollow shaft		<b>f</b> Resolution <sup>2)</sup>	<b>h</b> Options
(insertion depth max. 41.5 mm [1.63"])		A = 10 bit	1 = no option
1 = ø 12 mm [0.47"]		1 = 11 bit	
2 = ø 14 mm [0.55"]		2 = 12 bit	
		3 = 13 bit	
<b>c</b> Interface / supply voltage		4 = 14 bit	<b>i</b> Cable length in dm <sup>1)</sup>
2 = SSI, BiSS / 10 ... 30 V DC		7 = 17 bit	0050 = 5 m [16.40']
			0100 = 10 m [32.81']
<b>d</b> Type of connection			0150 = 15 m [49.21']
1 = axial cable, 2 m [6.56'] PUR			Optional on request
2 = radial cable, 2 m [6.56'] PUR			- special cable length
A = axial cable, length > 2 m [6.56']			- other resolutions
B = radial cable, length > 2 m [6.56']			

## Technical data

Explosion protection		
ATEX		
EU type-examination certificate		IBExU 15 ATEX 1057 X
Category		
Sendix 7153 – 6000 rpm	 I M2 Ex db I/IIC T4 Mb	
Sendix 7153 – 2000 rpm	 I M2 Ex db I/IIC T5 Mb	
Sendix 7173 – 3000 rpm	 I M2 Ex db I/IIC T4 Mb	
Sendix 7173 – 2000 rpm	 I M2 Ex db I/IIC 120°C (T4) Mb	
Relevant standards		EN 60079-0:2018
ATEX guideline 2014/34/EU		EN 60079-1:2014
IECEX		
Certificate of Conformity (CoC)		IECEX IBE 15.0019 X
Category		
Sendix 7153 – 6000 rpm	Ex db I/IIC T4 Mb	
Sendix 7153 – 2000 rpm	Ex db I/IIC T5 Mb	
Sendix 7173 – 3000 rpm	Ex db I/IIC T4 Mb	
Sendix 7173 – 2000 rpm	Ex db I/IIC 120°C (T4) Mb	
Relevant standards		IEC 60079-0:2017
		IEC 60079-1:2014

EMC	
<b>Relevant standards</b>	EN 55011 class B
	EN (IEC) 61326-1

Electrical characteristics	
<b>Supply voltage</b>	10 ... 30 V DC
<b>Current consumption</b> (no load)	max. 45 mA
<b>Reverse polarity protection for supply voltage</b>	yes
<b>Short-circuit proof outputs</b>	yes <sup>3)</sup>

Mechanical characteristics	
<b>Maximum speed</b>	shaft 6000 min <sup>-1</sup> (continuous)
	hollow shaft 3000 min <sup>-1</sup> (continuous)
<b>Starting torque - at 20 °C [68 °F]</b>	< 0.05 Nm
<b>Mass moment of inertia</b>	4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
<b>Load capacity of shaft</b>	radial 80 N
	axial 40 N
<b>Weight</b>	approx. 2.8 kg [98.77 oz]
<b>Protection</b> acc. to EN 60529	IP67
<b>Ambient temperature</b>	-40 °C ... +60 °C [-4 °F ... +140 °F]
	Please note the specifications for temperature class in EU type-examination certificate!
<b>Material</b>	shaft stainless steel
	flange / housing stainless steel
	cable PUR
<b>Shock resistance</b>	
acc. to EN/IEC 60068-2-27	1000 m/s <sup>2</sup> , 6 ms
<b>Vibration resistance</b>	
acc. to EN/IEC 60068-2-6	100 m/s <sup>2</sup> , 55 ... 2000 Hz

1) Not applicable with connection types 1 and 2

2) Resolution, preset value and counting direction factory-programmable.

3) Short-circuit with 0 V or output, only one channel at a time, supply voltage correctly applied.

# Absolute encoders - singleturn

Standard, ATEX/IECEX – mining M2 optical	Sendix 7153 / 7173 (shaft / hollow shaft)	SSI / BiSS
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SSI interface	
Output driver	RS485 transceiver type
Permissible load / channel	max. +/- 20 mA
Signal level	HIGH typ 3.8 V LOW at I <sub>Load</sub> = 20 mA typ 1.3 V
Resolution	10 ... 14 bit and 17 bit
Code	binary or gray
SSI clock rate	50 kHz ... 2 MHz
Data refresh rate	ST resolution ≤ 14 bit ≤ 1 μs ST resolution ≥ 15 bit 4 μs
Monoflop time	≤ 15 μs
<b>Note:</b> if clock starts cycling within monoflop time a second data transfer starts with the same data. If clock starts cycling after monoflop time, the data transfer starts with updated values. The update rate depends on clock speed, data length and monoflop time.	

BiSS interface	
Output driver	RS485 transceiver type
Permissible load / channel	max. +/- 20 mA
Signal level	HIGH typ 3.8 V LOW at I <sub>Load</sub> = 20 mA typ 1.3 V
Resolution	10 ... 14 bit and 17 bit
Code	binary
Clock rate	up to 10 MHz
Max. update rate	< 10 μs, depends on the clock rate and the data length
Data refresh rate	ST resolution ≤ 14 bit ≤ 1 μs ST resolution 17 bit 2.4 μs
<b>Note:</b> <ul style="list-style-type: none"> <li>– bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings</li> <li>– CRC data verification</li> </ul>	

Status output	
Output driver	open collector, internal pull-up resistor 22 kΩ
Permissible load	max. 20 mA
Signal level	HIGH +V LOW < 1 V
Active at	LOW
The status output serves to display various alarm or error messages. The status output is HIGH (open collector with internal pull-up 22 kΩ) in normal operation.	

## Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)											
2	1, 2, A, B	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	⊥	⊥
			Core marking:	1	2	3	4	5	6	7	8	9	YE/GN	shield

+V: Supply voltage encoder +V DC  
 0 V: Supply voltage encoder ground GND (0 V)  
 C+, C-: Clock signal  
 D+, D-: Data signal  
 SET: Set input  
 DIR: Direction input  
 Stat: Status output  
 ⊥: Protective earth

SET input	
Input	HIGH active
Input type	comparator
Signal level	HIGH min. 60% of +V (+V = supply voltage) max. +V LOW max. 25% of +V
Input current	< 0.5 mA
Min. pulse duration (SET)	10 ms
Timeout after SET signal	14 ms
The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal delay time of approximately 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approximately 15 ms before the new position data can be read. If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.	

DIR input	
Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed. If DIR is reversed when the device is already switched on, this will be interpreted as an error. The status output switches to LOW. If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.	
Response time (DIR input)	1 ms

Power-ON	
After Power-ON the device requires a time of approx. 150 ms before valid data can be read.	
Hot plugging of the encoder should be avoided.	

Approvals	
<b>CE compliant</b> in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU

# Absolute encoders - singleturn

<b>Standard, ATEX/IECEx – mining M2 optical</b>	<b>Sendix 7153 / 7173 (shaft / hollow shaft)</b>	<b>SSI / BiSS</b>
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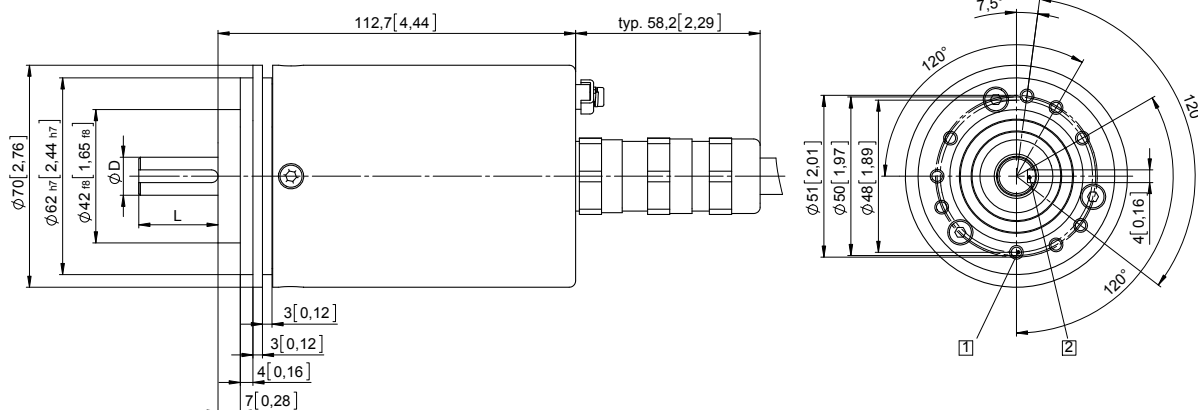
## Dimensions shaft version

Dimensions in mm [inch]

**Clamping / synchronous flange,  $\varnothing$  70 [2.76]**

**Shaft type 1 with axial cable outlet**

- 1** 9 x M4, 10 [0.39] deep
- 2** Keyway for DIN 6885-A-4x4x25 key

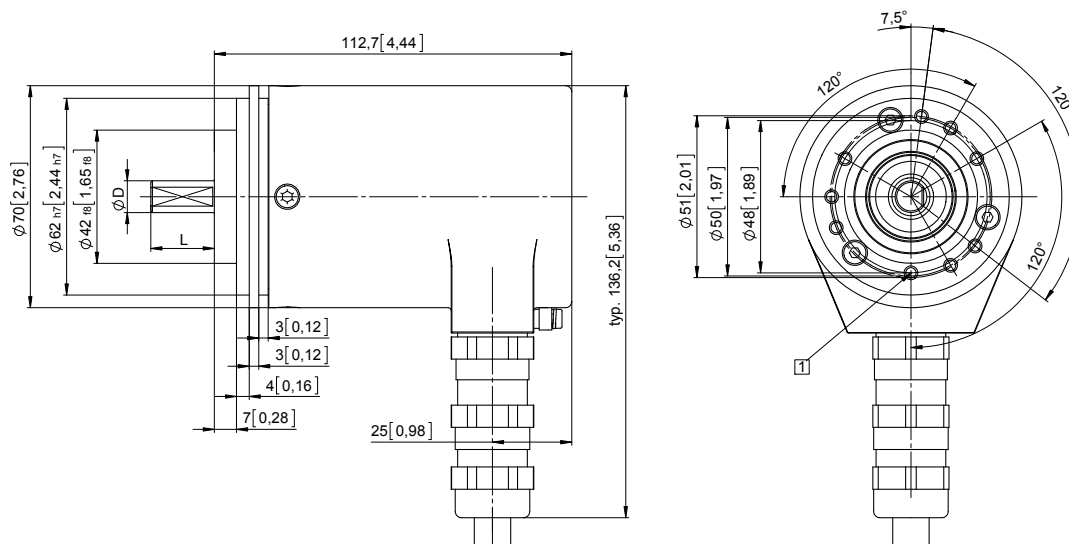


D	Fit	L
12 [0.47]	g6	25 [0.98]

**Clamping / synchronous flange,  $\varnothing$  70 [2.76]**

**Shaft type 2 with radial cable outlet**

- 1** 9 x M4, 10 [0.39] deep



D	Fit	L
10 [0.39]	f7	20 [0.79]

# Absolute encoders - singleturn

**Standard, ATEX/IECEx – mining M2 optical**

**Sendix 7153 / 7173 (shaft / hollow shaft)**

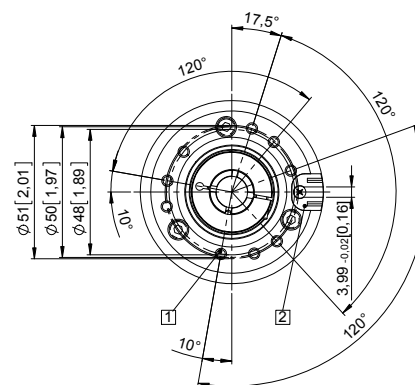
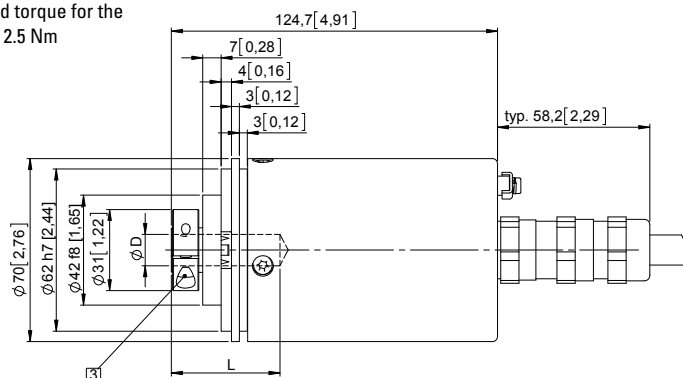
**SSI / BiSS**

## Dimensions hollow shaft version

Dimensions in mm [inch]

### Flange with spring element, short Flange type 2

- 1 9 x M4, 10 [0.39] deep
- 2 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing$  4 [0.16]
- 3 Recommended torque for the clamping ring 2.5 Nm

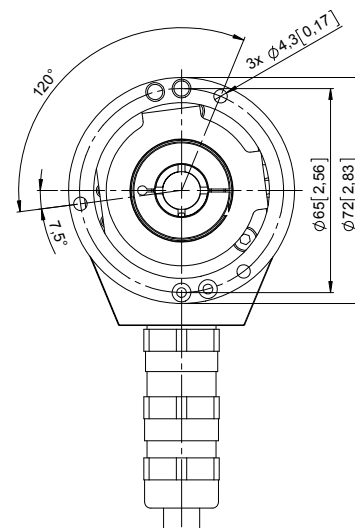
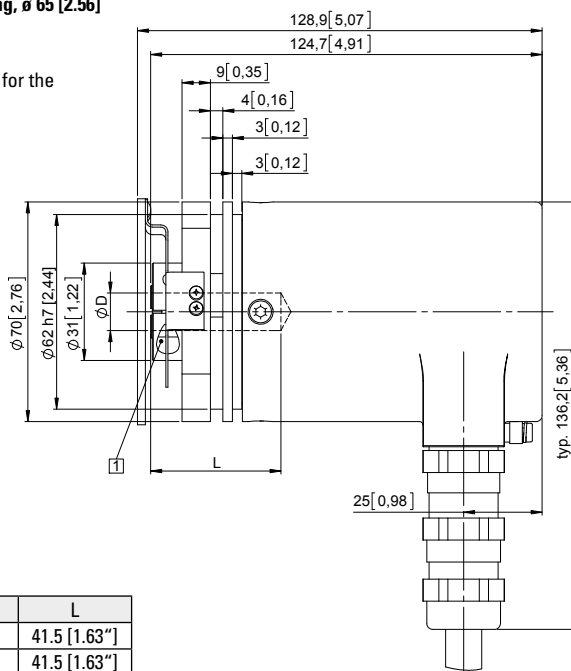


D	Fit	L
12 [0.47]	H7	41.5 [1.63"]
14 [0.55]	H7	41.5 [1.63"]

L = insertion depth max. blind hollow shaft

### Flange with stator coupling, $\varnothing$ 65 [2.56] Flange type 6

- 1 Recommended torque for the clamping ring 2.5 Nm



D	Fit	L
12 [0.47]	H7	41.5 [1.63"]
14 [0.55]	H7	41.5 [1.63"]

L = insertion depth max. blind hollow shaft

# Absolute encoders - singleturn

Standard, ATEX/IECEx – zone 1/21  
optical

Sendix 7058 / 7078 (shaft / hollow shaft)

PROFIBUS DP



The Sendix 7058 / 7078 absolute singleturn encoders offer Ex protection in a compact 70 mm seawater durable aluminum housing, with a Profibus interface and optical sensor technology.

These shock and vibration-resistant encoders operate flexibly with a resolution of up to 16 bits; they are also available with axial and radial cable outlets.



Ex approval



Safety-Lock™



High rotational speed



High protection level



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Short-circuit proof



Reverse polarity protection



Optical sensor



Seawater durable

## Compact and safe

- Can be used even when space is tight.
- Minimal installation depth, diameter 70 mm.
- Compact cable outlet axial or radial.
- Can be operated in marine environments – housing and flange manufactured from seawater durable aluminum.
- Remains sealed even in harsh everyday use and ensures highest safety against field breakdowns (IP67 protection).

## Explosion protection

- “Flameproof-enclosure” version.
- ATEX with EU type examination certificate.
- IECEx with certificate of conformity (CoC).

## Order code

### Shaft version

8.7058 . 1 X 3 X . 31 11 . XXXX  
Type a b c d e f 1)

#### a Flange

1 = clamping / synchronous flange, ø 70 mm [2.76"]

#### b Shaft (ø x L)

2 = 10 x 20 mm [0.39 x 0.79"], with flat  
1 = 12 x 25 mm [0.47 x 0.98"], with keyway  
for 4 x 4 mm [0.16 x 0.16"] key

#### c Interface / Supply voltage

3 = PROFIBUS DP V0 / 10 ... 30 V DC

#### d Type of connection

1 = axial cable, 2 m [6.56'] PUR  
2 = radial cable, 2 m [6.56'] PUR  
A = axial cable, length > 2 m [6.56']  
B = radial cable, length > 2 m [6.56']

#### e Fieldbus profile

31 = PROFIBUS DP V0 encoder profile class 2

#### f Cable length in dm 1)

0050 = 5 m [16.40']  
0100 = 10 m [32.81']  
0150 = 15 m [49.21']

#### Optional on request

- special cable length
- seawater resistant (stainless steel V4A)

1) Not applicable with connection types 1 and 2.

# Absolute encoders - singleturn

<b>Standard, ATEX/IECEX – zone 1/21 optical</b>	<b>Sendix 7058 / 7078 (shaft / hollow shaft)</b>	<b>PROFIBUS DP</b>
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<b>Order code</b> <b>Hollow shaft</b>	<b>8.7078</b> Type	<b>.XX3X.3111.XXXX</b> a b c d e i 1)
<b>a Flange</b> 1 = with spring element, short 5 = with stator coupling, ø 65 mm [2.56"]	<b>d Type of connection</b> 1 = axial cable, 2 m [6.56'] PUR 2 = radial cable, 2 m [6.56'] PUR A = axial cable, length > 2 m [6.56'] B = radial cable, length > 2 m [6.56']	<b>Optional on request</b> - special cable length - seawater resistant (stainless steel V4A)
<b>b Blind hollow shaft</b> (insertion depth max. 41.5 mm [1.63"]) 1 = ø 12 mm [0.47"] 2 = ø 14 mm [0.55"]	<b>e Fieldbus profile</b> 31 = PROFIBUS DP V0 encoder profile class 2	
<b>c Interface / Supply voltage</b> 3 = PROFIBUS DP V0 / 10 ... 30 V DC	<b>i Cable length in dm 1)</b> 0050 = 5 m [16.40'] 0100 = 10 m [32.81'] 0150 = 15 m [49.21']	

<b>Mounting accessory for shaft encoders</b>	Order no.
<b>Coupling</b>	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]
	<b>8.0000.1102.1010</b>

Further Kübler accessories can be found at: [/accessories](#)  
Further Kübler cables and connectors can be found at: [/connection-technology](#)

## Technical data

Explosion protection		Electrical characteristics	
<b>ATEX</b>		<b>Supply voltage</b>	10 ... 30 V DC
<b>EU type-examination certificate</b>	IBExU 15 ATEX 1091 X	<b>Current consumption (no load)</b>	max. 110 mA
<b>Category (gas)</b>	Sendix 7058 – 6000 rpm  II 2G Ex db IIC T4 Gb Sendix 7058 – 2000 rpm  II 2G Ex db IIC T5 Gb Sendix 7078 – 3000 rpm  II 2G Ex db IIC T4 Gb Sendix 7078 – 2000 rpm  II 2G Ex db IIC 120°C (T4) Gb	<b>Reverse polarity protection for supply voltage</b>	yes
<b>Category (dust)</b>	Sendix 7058 – 6000 rpm  II 2D Ex tb IIIC T135°C Db Sendix 7058 – 2000 rpm  II 2D Ex tb IIIC T100°C Db Sendix 7078 – 3000 rpm  II 2D Ex tb IIIC T135°C Db Sendix 7078 – 2000 rpm  II 2D Ex tb IIIC T120°C Db	<b>Mechanical characteristics</b>	
<b>Relevant standards</b>	EN 60079-0:2018 ATEX guideline 2014/34/EU EN 60079-1:2014 EN 60079-31:2014	<b>Maximum speed</b>	shaft 6000 min <sup>-1</sup> (continuous) hollow shaft 3000 min <sup>-1</sup> (continuous)
<b>IECEX</b>		<b>Starting torque – at 20 °C [68 °F]</b>	< 0.05 Nm
<b>Certificate of Conformity (CoC)</b>	IECEX IBE 15.0020 X	<b>Mass moment of inertia</b>	4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
<b>Category (gas)</b>	Sendix 7058 – 6000 rpm Ex db IIC T4 Gb Sendix 7058 – 2000 rpm Ex db IIC T5 Gb Sendix 7078 – 3000 rpm Ex db IIC T4 Gb Sendix 7078 – 2000 rpm Ex db IIC 120°C (T4) Gb	<b>Load capacity of shaft</b>	radial 80 N axial 40 N
<b>Category (dust)</b>	Sendix 7058 – 6000 rpm Ex tb IIIC T135°C Db Sendix 7058 – 2000 rpm Ex tb IIIC T100°C Db Sendix 7078 – 3000 rpm Ex tb IIIC T135°C Db Sendix 7078 – 2000 rpm Ex tb IIIC T120°C Db	<b>Weight</b>	approx. 1.5 kg [52.91 oz]
<b>Relevant standards</b>	IEC 60079-0:2017 IEC 60079-1:2014 IEC 60079-31:2013	<b>Protection acc. to EN 60529</b>	IP67
<b>EMC</b>		<b>Ambient temperature</b>	-40 °C ... +60 °C [-4 °F ... +140 °F] Please note the specifications for temperature class in EU type-examination certificate!
<b>Relevant standards</b>	EN 55011 class B EN (IEC) 61326-1	<b>Material</b>	shaft stainless steel flange / housing seawater durable Al, type AlSiMgMn (EN AW-6082) cable PUR
		<b>Shock resistance to EN/IEC 60068-2-27</b>	2500 m/s <sup>2</sup> , 6 ms
		<b>Vibration resistance to EN/IEC 60068-2-6</b>	100 m/s <sup>2</sup> , 55 ... 2000 Hz

1) Not applicable with connection types 1 and 2.

# Absolute encoders - singleturn

<b>Standard, ATEX/IECEX – zone 1/21 optical</b>	<b>Sendix 7058 / 7078 (shaft / hollow shaft)</b>	<b>PROFIBUS DP</b>
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Interface characteristics PROFIBUS DP	
<b>Resolution</b>	1 ... 65536 (16 bit), behavior default: 8192 (13 bit)
<b>Interface</b>	specification according to PROFIBUS DP 2.0 / standard (DIN 19245 part 3) / RS485 driver galvanically isolated
<b>Protocol</b>	Profibus encoder profile V1.1 class 1 and class 2 with manufacturer-specific add-ons
<b>Baud rate</b>	maximum 12 Mbit/s
<b>Device address</b>	software controlled setting of the device address via the SSA service with a class 2 master; default address: 125
<b>Termination</b>	active termination can only be switched on externally

Approvals	
<b>CE compliant</b> in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU

## Profibus encoder profile V1.1

The PROFIBUS DP device profile describes the functionality of the communication and the manufacturer-specific component within the PROFIBUS fieldbus system. The encoder profile applies to encoders and defines the individual objects independently of the manufacturer. In addition, the profile makes provision for additional extended functions specific to the manufacturer. The use of PROFIBUS compatible devices ensures that the systems of today are ready to meet the demands of the future.

### The following parameters can be programmed

- Direction of rotation.
- Scaling – number of steps per revolution.
- Preset value.
- Diagnostics mode.

### The following functionality is integrated

- Galvanic isolation of the bus stage with DC/DC converter.
- Line driver acc. to RS485 max. 12 MB.
- Full class 1 and class 2 functionality.
- Speed value.

## Terminal assignment

Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)								
3	1, 2, A, B	Signal:	0 V	+V	PB_A IN	PB_B IN	BUS_GND	BUS_VDC	PB_A OUT	PB_B OUT
		Core marking:	1	2	4	5	6	7	8	9



# Absolute encoders - singleturn

<b>Standard, ATEX/IECEx – zone 1/21 optical</b>	<b>Sendix 7058 / 7078 (shaft / hollow shaft)</b>	<b>PROFIBUS DP</b>
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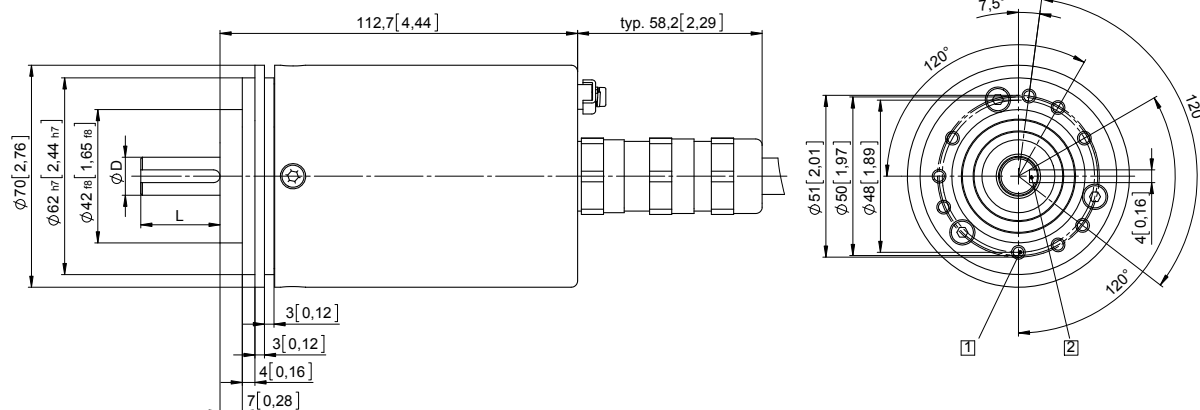
## Dimensions shaft version

Dimensions in mm [inch]

### Clamping / synchronous flange, $\varnothing$ 70 [2.76]

#### Shaft type 1 with axial cable outlet

- 1 9 x M4, 10 [0.39] deep
- 2 Keyway for DIN 6885-A-4x4x25 key

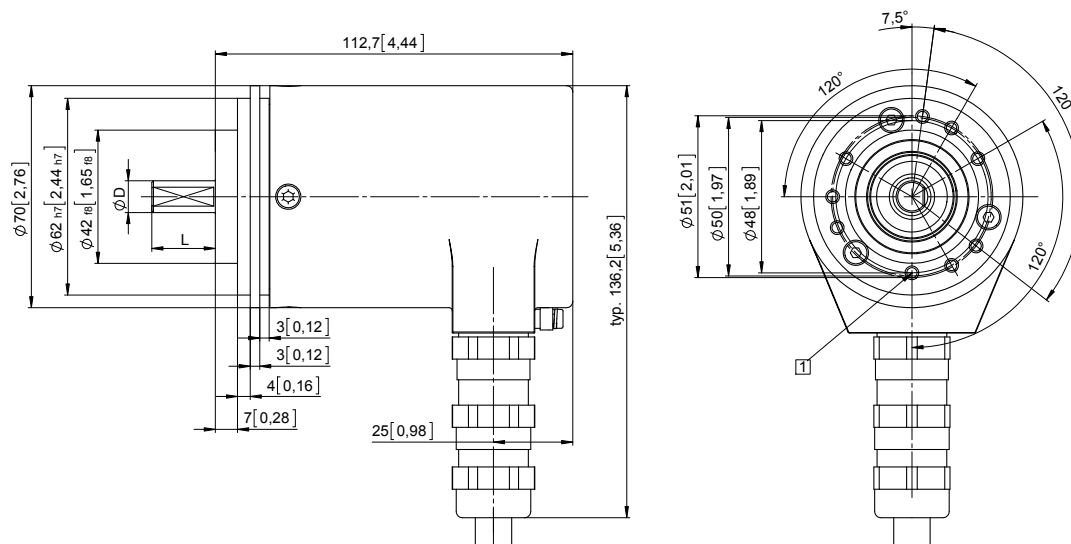


D	Fit	L
12 [0.47]	g6	25 [0.98]

### Clamping / synchronous flange, $\varnothing$ 70 [2.76]

#### Shaft type 2 with radial cable outlet

- 1 9 x M4, 10 [0.39] deep



D	Fit	L
10 [0.39]	f7	20 [0.79]

# Absolute encoders - singleturn

**Standard, ATEX/IECEx – zone 1/21  
optical**

**Sendix 7058 / 7078 (shaft / hollow shaft)**

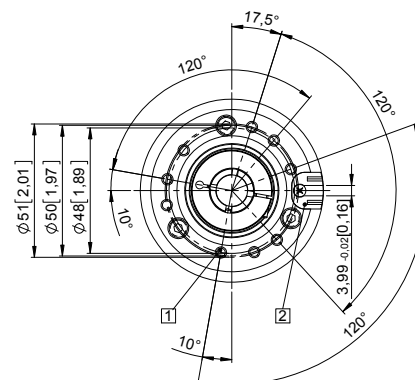
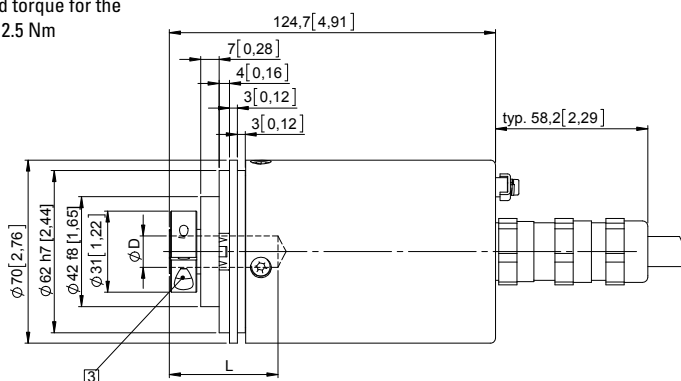
**PROFIBUS DP**

## Dimensions hollow shaft version

Dimensions in mm [inch]

### Flange with spring element, short Flange type 1

- 1 9 x M4, 10 [0.39] deep
- 2 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing$  4 [0.16]
- 3 Recommended torque for the clamping ring 2.5 Nm

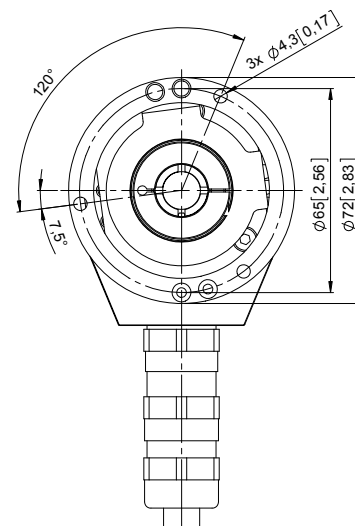
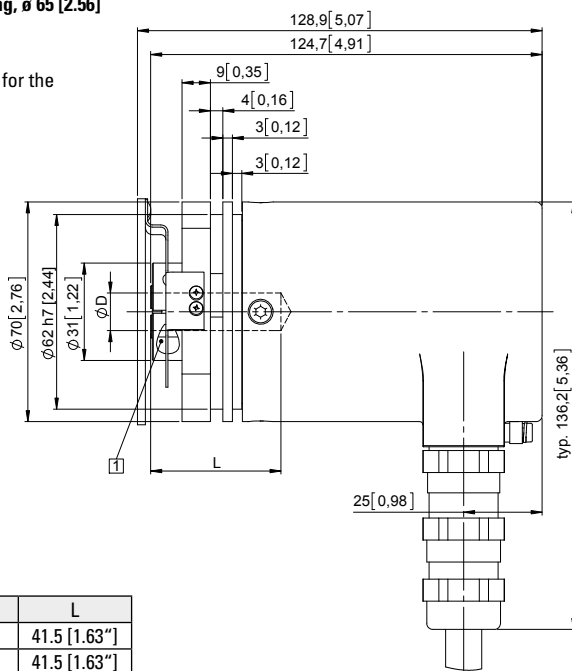


D	Fit	L
12 [0.47]	H7	41.5 [1.63"]
14 [0.55]	H7	41.5 [1.63"]

L = insertion depth max. blind hollow shaft

### Flange with stator coupling, $\varnothing$ 65 [2.56] Flange type 5

- 1 Recommended torque for the clamping ring 2.5 Nm



D	Fit	L
12 [0.47]	H7	41.5 [1.63"]
14 [0.55]	H7	41.5 [1.63"]

L = insertion depth max. blind hollow shaft

# Absolute encoders - singleturn

**Standard, ATEX/IECEx – mining M2 optical**

**Sendix 7158 / 7178 (shaft / hollow shaft)**

**CANopen**



The Sendix 7158 / 7178 absolute singleturn encoders in a compact 70 mm stainless-steel housing, with a CANopen interface and optical sensor technology have an ATEX/IECEx mining M2 approval.

These shock and vibration-resistant encoders operate flexibly with a resolution of up to 16 bits; they are also available with axial and radial cable outlets.



## Compact and safe

- Can be used even when space is tight.
- Minimal installation depth, diameter 70 mm.
- Compact cable outlet axial or radial.
- Remains sealed even in harsh everyday use and ensures highest safety against field breakdowns (IP67 protection).

## Explosion protection

- Mining M2 approval.
- “Flame-proof enclosure” construction.
- ATEX with EU type examination certificate.
- IECEx with certificate of conformity (CoC).

**Order code** 8.7158 . 2X2X . 2111 . XXXX  
**Shaft version** Type a b c d e i 1)

**a** Flange  
2 = clamping / synchronous flange, ø 70 mm [2.76"]

**b** Shaft (ø x L)  
2 = 10 x 20 mm [0.39 x 0.79"], with flat  
1 = 12 x 25 mm [0.47 x 0.98"], with keyway for 4 x 4 mm [0.16 x 0.16"] key

**c** Interface / supply voltage  
2 = CANopen DS301 V4.02 / 10 ... 30 V DC

**d** Type of connection  
1 = axial cable, 2 m [6.56'] PUR  
2 = radial cable, 2 m [6.56'] PUR  
A = axial cable, length > 2 m [6.56']  
B = radial cable, length > 2 m [6.56']

**e** Fieldbus profile  
21 = CANopen

**i** Cable length in dm 1)  
0050 = 5 m [16.40']  
0100 = 10 m [32.81']  
0150 = 15 m [49.21']

Optional on request  
- special cable length

**Order code** 8.7178 . XX2X . 2111 . XXXX  
**Hollow shaft** Type a b c d e i 1)

**a** Flange  
2 = with spring element, short  
6 = with stator coupling, ø 65 mm [2.56"]

**b** Blind hollow shaft  
(insertion depth max. 41.5 mm [1.63"])  
1 = ø 12 mm [0.47"]  
2 = ø 14 mm [0.55"]

**c** Interface / supply voltage  
2 = CANopen DS301 V4.02 / 10 ... 30 V DC

**d** Type of connection  
1 = axial cable, 2 m [6.56'] PUR  
2 = radial cable, 2 m [6.56'] PUR  
A = axial cable, length > 2 m [6.56']  
B = radial cable, length > 2 m [6.56']

**e** Fieldbus profile  
21 = CANopen





**i** Cable length in dm 1)  
0050 = 5 m [16.40']  
0100 = 10 m [32.81']  
0150 = 15 m [49.21']

Optional on request  
- special cable length

1) Not applicable with connection types 1 and 2.

<b>Standard, ATEX/IECEx – mining M2 optical</b>	<b>Sendix 7158 / 7178 (shaft / hollow shaft)</b>	<b>CANopen</b>
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## Technical data

Explosion protection		
<b>ATEX</b>		
<b>EU type-examination certificate</b>	IBExU 15 ATEX 1057 X	
<b>Category</b>	<div> <div>Sendix 7158 – 6000 rpm</div> <div>  I M2 Ex db I/IIC T4 Mb </div> </div> <div> <div>Sendix 7158 – 2000 rpm</div> <div>  I M2 Ex db I/IIC T5 Mb </div> </div> <div> <div>Sendix 7178 – 3000 rpm</div> <div>  I M2 Ex db I/IIC T4 Mb </div> </div> <div> <div>Sendix 7178 – 2000 rpm</div> <div>  I M2 Ex db I/IIC 120°C (T4) Mb </div> </div>	
<b>Relevant standards</b>	EN 60079-0:2018	
ATEX guideline 2014/34/EU	EN 60079-1:2014	
<b>IECEx</b>		
<b>Certificate of Conformity (CoC)</b>	IECEx IBE 15.0019 X	
<b>Category</b>	<div> <div>Sendix 7158 – 6000 rpm</div> <div>Ex db I/IIC T4 Mb</div> </div> <div> <div>Sendix 7158 – 2000 rpm</div> <div>Ex db I/IIC T5 Mb</div> </div> <div> <div>Sendix 7178 – 3000 rpm</div> <div>Ex db I/IIC T4 Mb</div> </div> <div> <div>Sendix 7178 – 2000 rpm</div> <div>Ex db I/IIC 120°C (T4) Mb</div> </div>	
<b>Relevant standards</b>	IEC 60079-0:2017	
	IEC 60079-1:2014	

EMC	
<b>Relevant standards</b>	EN 55011 class B EN (IEC) 61326-1

## Approvals

<b>CE compliant</b> in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
ATEX Directive	2014/34/EU

## Electrical characteristics

<b>Supply voltage</b>	10 ... 30 V DC
<b>Current consumption</b> (no load)	max. 90 mA
<b>Reverse polarity protection</b> <b>for supply voltage</b>	yes

## Mechanical characteristics

<b>Maximum speed</b>	shaft hollow shaft	6000 min <sup>-1</sup> (continuous) 3000 min <sup>-1</sup> (continuous)
<b>Starting torque</b> – at 20 °C [68 °F]		< 0.05 Nm
<b>Mass moment of inertia</b>		4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
<b>Load capacity of shaft</b>	radial axial	80 N 40 N
<b>Weight</b>		approx. 2.8 kg [98.77 oz]
<b>Protection</b> acc. to EN 60529		IP67
<b>Ambient temperature</b>		-40 °C ... +60 °C [-4 °F ... +140 °F] Please note the specifications for temperature class in EU type- examination certificate!
<b>Material</b>	shaft flange / housing cable	stainless steel stainless steel PUR
<b>Shock resistance</b>		
	acc. to EN/IEC 60068-2-27	1000 m/s <sup>2</sup> , 6 ms
<b>Vibration resistance</b>		
	acc. to EN/IEC 60068-2-6	100 m/s <sup>2</sup> , 55 ... 2000 Hz

# Absolute encoders - singleturn

Standard, ATEX/IECEx – mining M2 optical	Sendix 7158 / 7178 (shaft / hollow shaft)	CANopen
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Interface characteristics CANopen	
Resolution	1 ... 65536 (16 bit), scalable default: 8192 (13 bit)
Interface	CAN high-speed acc. to ISO 11898, Basic- and Full-CAN, CAN specification 2.0 B
Protocol	CANopen profile DS406 V3.2 with manufacturer-specific add-ons
Baud rate	10 ... 1000 kbit/s software configurable
Node address	1 ... 127 software configurable
Switchable termination	software configurable

## General information about CANopen

The CANopen encoders support the latest CANopen communication profile according to DS301 V4.02 .

In addition, device-specific profiles like the encoder profile DS406 V3.2 are available.

The following operating modes may be selected: Polled Mode, Cyclic Mode, Sync Mode and a High Resolution Sync Protocol. Moreover, scale factors, preset values, limit switch values and many other additional parameters can be programmed via the CANbus. When switching the device on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure.

As output values **position**, **speed**, **acceleration** as well as the **working area status** may be combined freely as PDO (PDO mapping)

## CANopen communication profile DS301 V4.02

Among others, the following functionality is integrated:

Class C2 functionality

- NMT slave.
- Heartbeat protocol.
- High resolution sync protocol.
- Identity object.
- Error behavior object.
- Variable PDO mapping self-start programmable (power on to operational), 3 Sending PDO's.
- Node address, baud rate and CANbus termination programmable.

## CANopen encoder profile DS406 V3.2

The following parameters can be programmed:

- Event mode.
- Units for speed selectable (steps/sec or min<sup>-1</sup>).
- Factor for speed calculation (e.g. measuring wheel circumference)
- Integration time for speed value of 1...32.
- 2 work areas with 2 upper and lower limits and the corresponding output states.
- Variable PDO mapping of position, speed, acceleration, working area status.
- Extended failure management for position sensing with integrated temperature control.
- User interface with visual display of bus and failure status - 3 LED's.
- Optional - 32 CAMs programmable.
- Customer-specific memory - 16 Bytes.

## Terminal assignment

Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)								
2	1, 2, A, B	Signal:	0 V	+V	CAN_H	CAN_L	CAN_GND	CAN_H	CAN_L	CAN_GND
		Core marking:	1	2	4	5	6	7	8	9

# Absolute encoders - singleturn

Standard, ATEX/IECEx – mining M2 optical	Sendix 7158 / 7178 (shaft / hollow shaft)	CANopen
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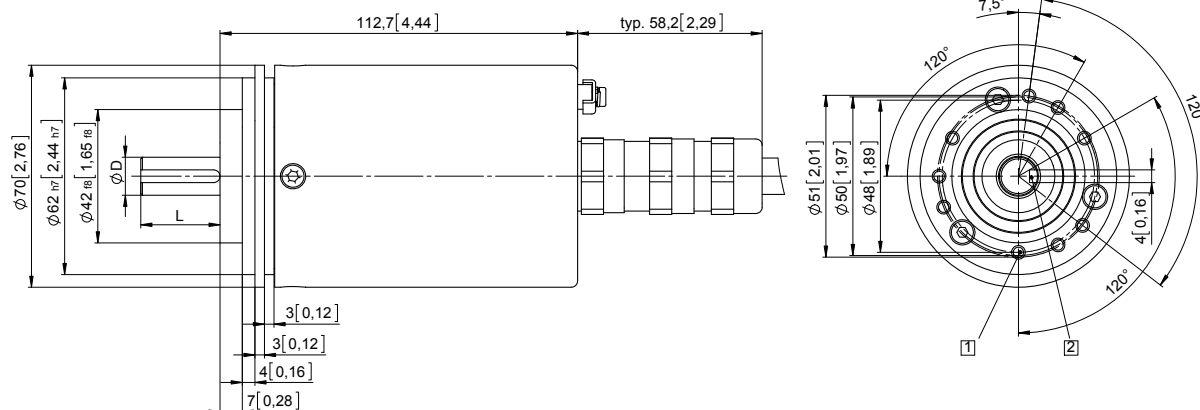
## Dimensions shaft version

Dimensions in mm [inch]

Clamping / synchronous flange,  $\varnothing$  70 [2.76]

Shaft type 1 with axial cable outlet

- 1 9 x M4, 10 [0.39] deep
- 2 Keyway for DIN 6885-A-4x4x25 key

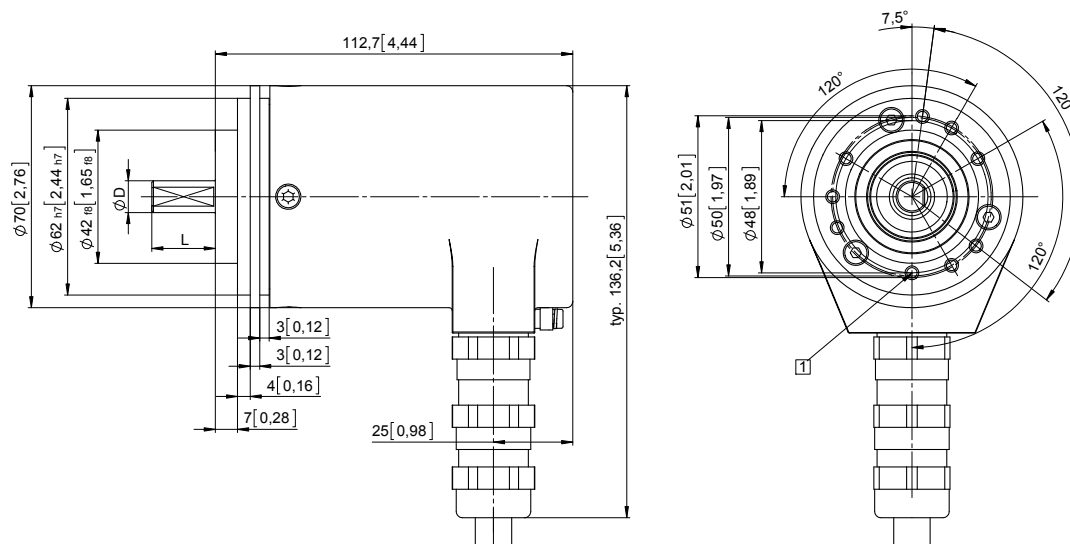


D	Fit	L
12 [0.47]	g6	25 [0.98]

Clamping / synchronous flange,  $\varnothing$  70 [2.76]

Shaft type 2 with radial cable outlet

- 1 9 x M4, 10 [0.39] deep



D	Fit	L
10 [0.39]	f7	20 [0.79]

# Absolute encoders - singleturn

**Standard, ATEX/IECEx – mining M2 optical**

**Sendix 7158 / 7178 (shaft / hollow shaft)**

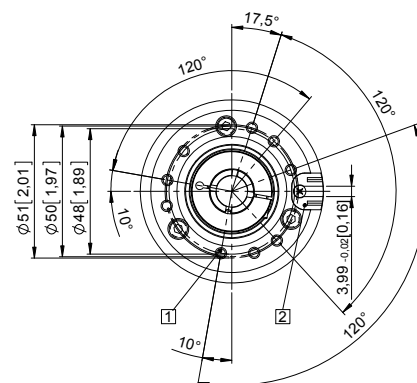
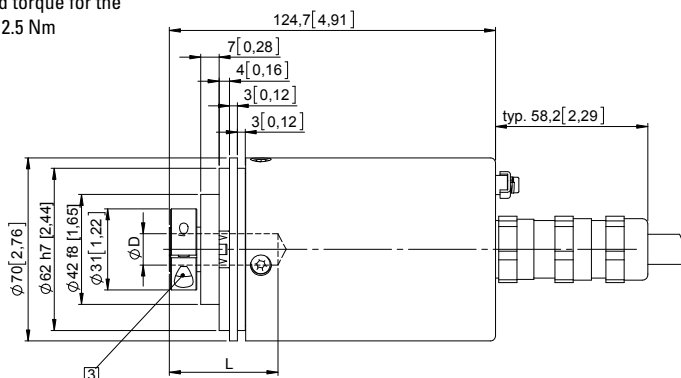
**CANopen**

## Dimensions hollow shaft version

Dimensions in mm [inch]

### Flange with spring element, short Flange type 2

- 1 9 x M4, 10 [0.39] deep
- 2 Slot spring element, recommendation: torque pin DIN 7,  $\varnothing$  4 [0.16]
- 3 Recommended torque for the clamping ring 2.5 Nm

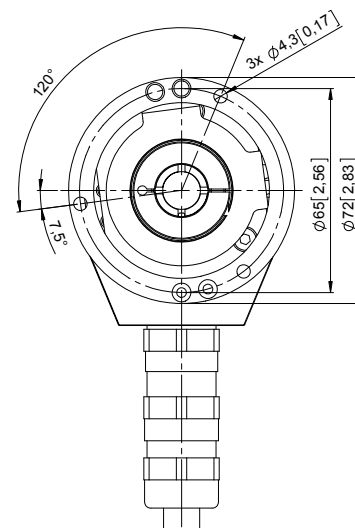
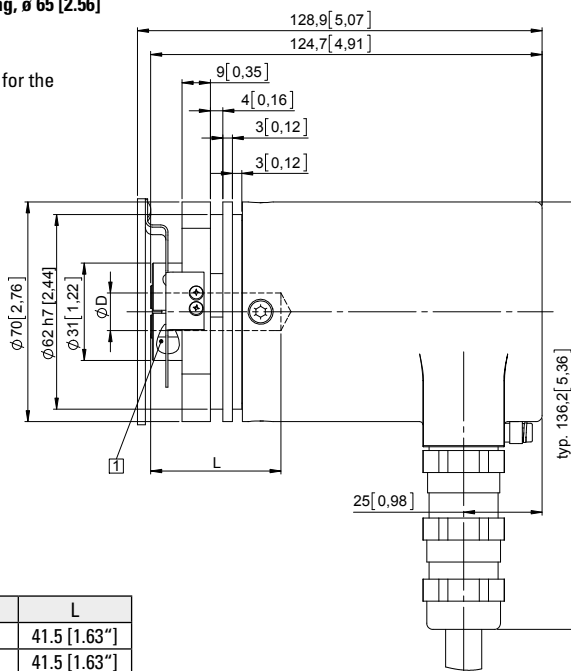


D	Fit	L
12 [0.47]	H7	41.5 [1.63"]
14 [0.55]	H7	41.5 [1.63"]

L = insertion depth max. blind hollow shaft

### Flange with stator coupling, $\varnothing$ 65 [2.56] Flange type 6

- 1 Recommended torque for the clamping ring 2.5 Nm



D	Fit	L
12 [0.47]	H7	41.5 [1.63"]
14 [0.55]	H7	41.5 [1.63"]

L = insertion depth max. blind hollow shaft



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